

The original version of the slides is available at: extras.springer.com

Outline (today)

- Query decomposition and data localization (Ch. 7) *
 - The problem of distributed data localization
 - ➡ A naïve algorithm
 - Optimization steps (reductions)
 - PHF (selection, join)
 - VF (projection)
 - DHF (selection, join)
 - Hybrid Fragmentation (selection/join + projection)

* Özsu and Valduriez, Principles of Distributed Database Systems (3rd Ed.), 2011

Data Localization

Özsu and Valduriez, Principles of Distributed Database Systems (3rd Ed.), 2011

Input: Relational algebra expression on global, distributed relations (distributed query)

- Determine which fragments are involved in a query (over global, distributed relations) and transform such a query into an equivalent one over such fragments (localized query)
- Localization uses information about distribution of fragments stored in the fragment schema
- Recall that fragmentation is obtained by several application of rules expressed by relational algebra ...
- \Rightarrow primary horizontal fragmentation: selection σ
- \Rightarrow derived horizontal fragmentation: semijoin \ltimes
- vertical fragmentation: projection Π
- ... and that reconstruction (reverse fragmentation) rules are also expressed in relational algebra
 horizontal fragmentation: union U
 - → vertical fragmentation: join ⋈

A naïve algorithm to localize distribute queries

- Localization program: relational algebra expression that reconstructs a global relation from its fragments, by reverting the rules employed for fragmentation
- A localized query is obtained from distributed, global query by replacing leaves (global relations) with (the tree of) its corresponding localization program
 - Leaves of localized queries are fragments
- This approach to obtain a localized query from a distributed one is inefficient and the result can be improved through several optimizations























