Towards A Hybrid (Combined?) Approach to Software Verification



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Outline

Introduction: model checking vs. runtime verification (motivations)

Runtime verification for μHML (= μ -calculus)

Extending runtime verification applicability: hybrid (combined?) approach

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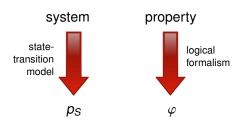
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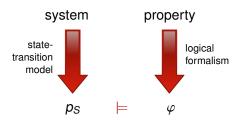
Runtime verification for μHML (= μ -calculus)

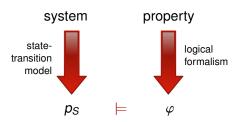
Extending runtime verification applicability: hybrid (combined?) approach

system

property







unfeasible for most real-world applications (state explosion problem)

monitoring a single partial execution and try to give a verdict

eventually p

monitoring a single partial execution and try to give a verdict

eventually p $\neg p$

monitoring a single partial execution and try to give a verdict

eventually peventually p?

eventually
$$p$$
 $p \rightarrow p$
 $p \rightarrow p$
 $p \rightarrow p$
 $p \rightarrow p$
 $p \rightarrow p$

eventually
$$p$$

$$\begin{array}{c}
\neg p & \neg p & \neg p \\
\bullet - - - \bullet \\
? & ?
\end{array}$$

eventually p
$$\begin{array}{c} \neg p & \neg p & \neg p & p \\ \bullet & --- & \bullet & --- & \bullet \\ ? & ? & ? \end{array}$$

always
$$p$$

$$\begin{array}{c}
p & p & p & \neg p \\
\bullet & --- & \bullet & --- & \bullet \\
? & ? & ? & no
\end{array}$$

monitoring a single partial execution and try to give a verdict

[(p or q) until r] or (always p)

always
$$p$$

$$\begin{array}{c}
p & p & p & \neg p \\
\bullet & --- & \bullet & --- & \bullet \\
? & ? & ? & no
\end{array}$$

[(p or q) until r]
$$\stackrel{p}{\circ}$$
 $\stackrel{p}{\circ}$ $\stackrel{p}{\circ}$ $\stackrel{r}{\circ}$ $\stackrel{r}{\circ}$ $\stackrel{r}{\circ}$ $\stackrel{r}{\circ}$ $\stackrel{r}{\circ}$ yes

always
$$p$$

$$\begin{array}{c}
p & p & p & \neg p \\
\bullet & --- & \bullet \\
? & ? & ? & no
\end{array}$$

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Monitorability

Definition (monitorability)

```
\varphi \text{ is monitorable } := \varphi \text{ is suitable to be runtime verified} \\ := \text{ either} \\ \text{ there exists} \\ \text{ a finite witness for satisfaction} \\ \text{ whenever } \varphi \text{ is true} \\ \text{ or} \\ \text{ there exists} \\ \text{ a finite witness for violation} \\ \text{ whenever } \varphi \text{ is false} \\
```

The branching time logic μHML

```
\begin{array}{llll} \varphi, \phi \in \mu \text{HML} ::= & \\ & \text{tt} & (\text{truth}) & | \text{ ff} & (\text{falsehood}) \\ & | \varphi \vee \phi & (\text{disjunction}) & | \varphi \wedge \phi & (\text{conjunction}) \\ & | \langle \alpha \rangle \varphi & (\text{possibility}) & | [\alpha] \varphi & (\text{necessity}) \\ & | \min X. \varphi & (\min. \text{fixpoint}) & | \max X. \varphi & (\max. \text{fixpoin}) \\ & | X & (\text{rec. variable}) & \end{array}
```

The maximal monitorable subset

```
\begin{split} \pi,\varpi \in \mathsf{cHML} &::= \mathsf{tt} \quad \mid \mathsf{ff} \quad \mid \pi \vee \varpi \quad \mid \langle \alpha \rangle \pi \quad \mid \mathsf{min} \ X.\pi \quad \mid X \\ \theta,\vartheta \in \mathsf{sHML} &::= \mathsf{tt} \quad \mid \mathsf{ff} \quad \mid \theta \wedge \vartheta \quad \mid [\alpha]\theta \quad \mid \mathsf{max} \ X.\theta \quad \mid X \end{split}
```

Francalanza, Aceto, Ingólfsdóttir, **On verifying Hennessy-Milner logic with**recursion at runtime. In Runtime Verification, 2015

The branching time logic μHML

```
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```

Examples

⟨a⟩tt

The maximal monitorable subset

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\begin{split} \pi,\varpi \in \mathsf{cHML} ::= \mathsf{tt} & | \mathsf{ff} & | \pi \vee \varpi & | \langle \alpha \rangle \pi & | \min X.\pi & | X \\ \theta,\vartheta \in \mathsf{sHML} ::= \mathsf{tt} & | \mathsf{ff} & | \theta \wedge \vartheta & | [\alpha]\theta & | \max X.\theta & | X \end{split}
```

```
\langle a \ranglett [a]ff
```

The maximal monitorable subset

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\begin{split} \pi, \varpi \in \mathsf{cHML} &::= \mathsf{tt} \quad \mid \mathsf{ff} \quad \mid \pi \vee \varpi \quad \mid \langle \alpha \rangle \pi \quad \mid \mathsf{min} \ X.\pi \quad \mid X \\ \theta, \vartheta \in \mathsf{sHML} &::= \mathsf{tt} \quad \mid \mathsf{ff} \quad \mid \theta \wedge \vartheta \quad \mid [\alpha]\theta \quad \mid \mathsf{max} \ X.\theta \quad \mid X \end{split}
```

$$\langle a \rangle$$
tt $[a]$ ff $\langle a \rangle$ tt $\vee \langle b \rangle$ tt

The maximal monitorable subset

```
\begin{split} \pi,\varpi \in \mathsf{cHML} ::= \mathsf{tt} & | \mathsf{ff} & | \pi \vee \varpi & | \langle \alpha \rangle \pi & | \min X.\pi & | X \\ \theta,\vartheta \in \mathsf{sHML} ::= \mathsf{tt} & | \mathsf{ff} & | \theta \wedge \vartheta & | [\alpha]\theta & | \max X.\theta & | X \end{split}
```

$$\langle a \rangle$$
tt [a]ff $\langle a \rangle$ tt $\vee \langle b \rangle$ tt $\langle a \rangle (\langle b \rangle$ tt $\vee [c]$ ff)

The maximal monitorable subset

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 \begin{aligned} \pi,\varpi \in \mathsf{cHML} &::= \mathsf{tt} & | \mathsf{ff} & | \pi \vee \varpi & | \langle \alpha \rangle \pi & | \min X.\pi & | X \\ \theta,\vartheta \in \mathsf{sHML} &::= \mathsf{tt} & | \mathsf{ff} & | \theta \wedge \vartheta & | [\alpha]\theta & | \max X.\theta & | X \end{aligned}
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$$\langle a \rangle$$
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Where runtime verification can reach so far

 $\langle a \rangle (\langle b \rangle tt \vee [c]ff)$: not monitorable, do model checking

Where runtime verification can reach so far

 $\langle a \rangle (\langle b \rangle tt \vee [c]ff)$: not monitorable, do model checking

$$\langle a \rangle (\langle b \rangle \text{tt} \vee [c] \text{ff}) \equiv \langle a \rangle \langle b \rangle \text{tt} \vee \langle a \rangle [c] \text{ff}$$

Where runtime verification can reach so far

 $\langle a \rangle (\langle b \rangle \text{tt} \vee [c] \text{ff})$: not monitorable, do model checking $\langle a \rangle (\langle b \rangle \text{tt} \vee [c] \text{ff}) \equiv \underline{\langle a \rangle \langle b \rangle \text{tt}} \vee \underline{\langle a \rangle [c] \text{ff}}$ monitorable:
do runtime verification

not monitorable:
do model checking

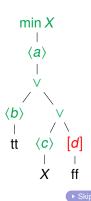
$$\varphi \equiv \varphi_{RV} \ \Diamond \ \varphi_{MC}$$

Universal: \land , [α], max X Existential: \lor , $\langle \alpha \rangle$, min X

$$\varphi \equiv \varphi_{RV} \Leftrightarrow \varphi_{MC}$$

Universal: \land , $[\alpha]$, $\max X$ Existential: \lor , $\langle \alpha \rangle$, $\min X$

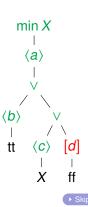
 $\min X.\langle a\rangle(\langle b\rangle\mathsf{tt}\vee\langle c\rangle X\vee[d]\mathsf{ff})$



$$\varphi \equiv \varphi_{RV} \Leftrightarrow \varphi_{MC}$$

Universal: \land , $[\alpha]$, max X Existential: \lor , $\langle \alpha \rangle$, min X

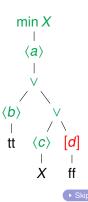
```
\min X.\langle a \rangle (\langle b \rangle \mathsf{tt} \vee \langle c \rangle X \vee [d] \mathsf{ff}) = \\ \left( \min X.\langle a \rangle (\langle b \rangle \mathsf{tt} \vee \langle c \rangle X) \right) \vee \boxed{?}
```

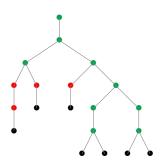


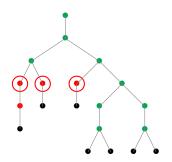
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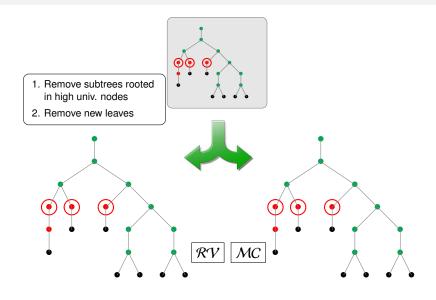
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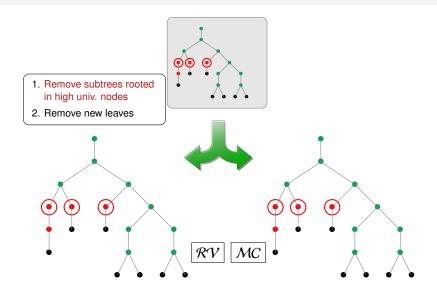
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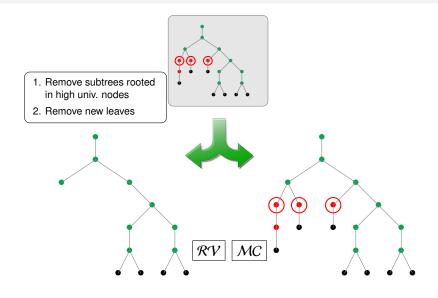


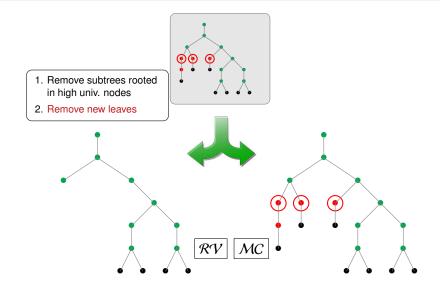


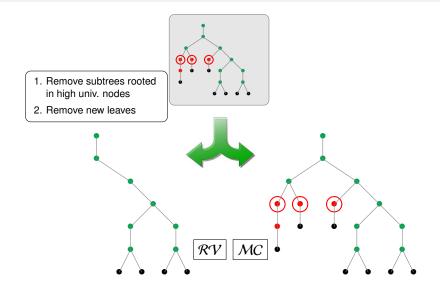


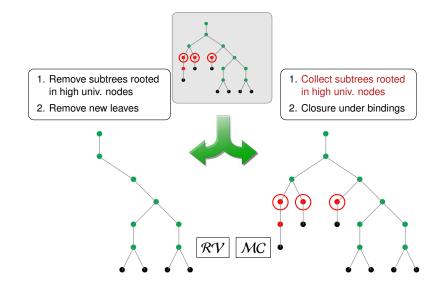


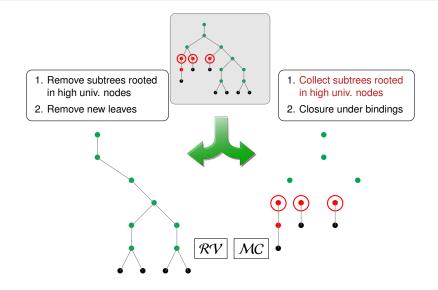


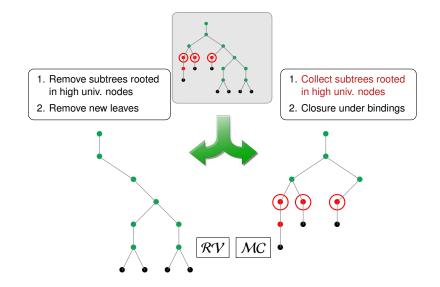


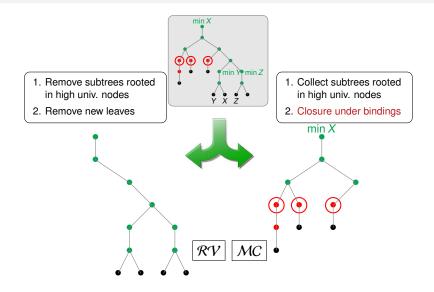


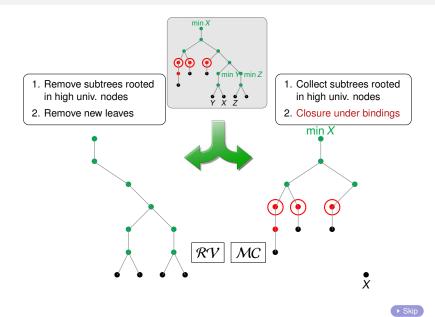


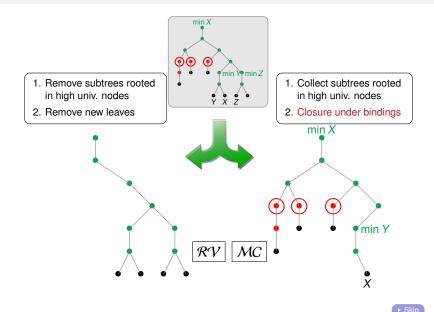


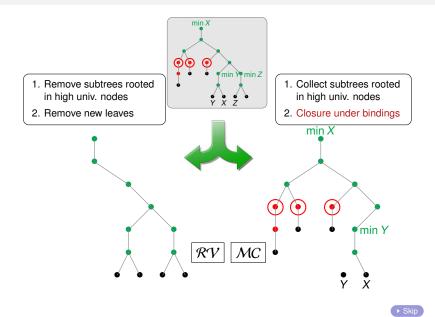


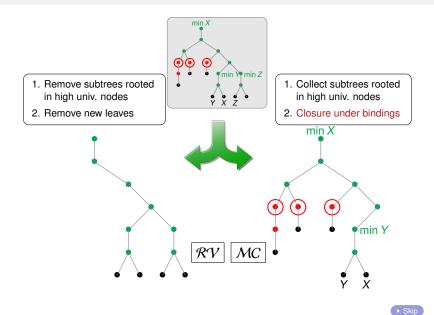






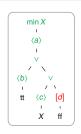






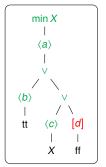
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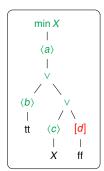
```
\min X.\langle a \rangle (\langle b \rangle \text{tt} \vee \langle c \rangle X \vee [d] \text{ff}) \\
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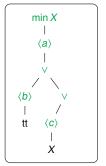


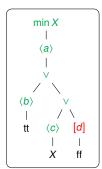




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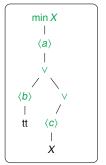


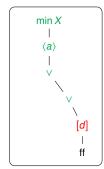




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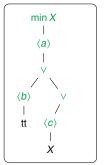


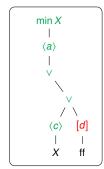




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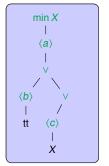


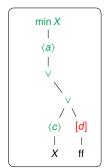




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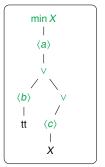


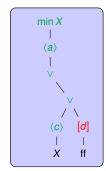




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```







Correctness

Claim (correctness)

```
 \qquad \qquad \varphi \quad \equiv \quad \varphi_{\mathcal{RV}} \quad \lor \quad \varphi_{\mathcal{MC}} \qquad \text{(existential)}
```

Correctness

Claim (correctness)

```
ho \varphi \equiv \varphi_{RV} \lor \varphi_{MC} (existential)
```

 $ho \varphi \equiv \varphi_{RV} \wedge \varphi_{MC}$ (universal)



Conclusions and future direction

Contribution

- A decomposition of μHML formulae into:
 - a runtime verification formula
 - a model checking formula
- Runtime verification is applicable to a larger set of formulae

Future work

- Formal correctness proof
- Empirical tests for efficiency
- Extending the approach to other formalisms
- Expressiveness study of induced μHML fragments/hierarchy

The end

Thank you