

Parity-energy ATL for Qualitative and Quantitative Reasoning in MAS

D. Della Monica, A. Murano



Istituto Nazionale di Alta Matematica “F. Severi” (INdAM)

Università di Napoli “Federico II”
Universidad Complutense de Madrid

`dario.dellamonica@unina.it`

FMLAMAS 2018
Stockholm, July 10, 2018

1 Introduction and motivations

2 The logic pe-ATL

- pe-ATL at work

3 Model checking pe-ATL

- Warming up: Parity and energy conditions in isolation
- Unbounded $[-\infty, +\infty]$ and bounded $[a, b]$ energy range
- Left-bounded $[a, +\infty]$ and right-bounded $[-\infty, b]$ energy range

4 Conclusions

1 Introduction and motivations

2 The logic pe-ATL

- pe-ATL at work

3 Model checking pe-ATL

- Warming up: Parity and energy conditions in isolation
- Unbounded $[-\infty, +\infty]$ and bounded $[a, b]$ energy range
- Left-bounded $[a, +\infty]$ and right-bounded $[-\infty, b]$ energy range

4 Conclusions

Multi-Agent Systems (MAS)

- Several agents
- Intelligent (take decisions, moves)
- Independent
- Next state univocally identified by joint moves (all agents)

Multi-Agent Systems (MAS)

- Several agents
- Intelligent (take decisions, moves)
- Independent
- Next state univocally identified by joint moves (all agents)

Multi-Agent Systems (MAS)

- Several agents
- Intelligent (take decisions, moves)
- Independent
- Next state univocally identified by joint moves (all agents)

Multi-Agent Systems (MAS)

- Several agents
- Intelligent (take decisions, moves)
- Independent
- Next state univocally identified by joint moves (all agents)

COALITION - modeling collective behaviors/strategies

COALITION - modeling collective behaviors/strategies

Logical Formalisms

Coalition Logic (CL) and Alternating-time Temporal Logic (ATL)

COALITION - modeling collective behaviors/strategies

Logical Formalisms

Coalition Logic (CL) and Alternating-time Temporal Logic (ATL)

Theorem (Goranko, TARK 2001)

CL can be embedded into ATL

ATL: syntax and models

- **Syntax.** Formulae of ATL are given by the grammar:

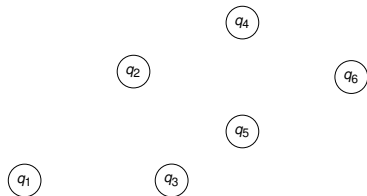
$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \langle\langle A \rangle\rangle \bigcirc \varphi \mid \langle\langle A \rangle\rangle \square \varphi \mid \langle\langle A \rangle\rangle \varphi \mathcal{U} \varphi$$

ATL: syntax and models

- **Syntax.** Formulae of ATL are given by the grammar:

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \langle\langle A \rangle\rangle \bigcirc \varphi \mid \langle\langle A \rangle\rangle \square \varphi \mid \langle\langle A \rangle\rangle \varphi \mathcal{U} \varphi$$

- **Models.** CGS's (**concurrent game structure**) are labeled transition systems:



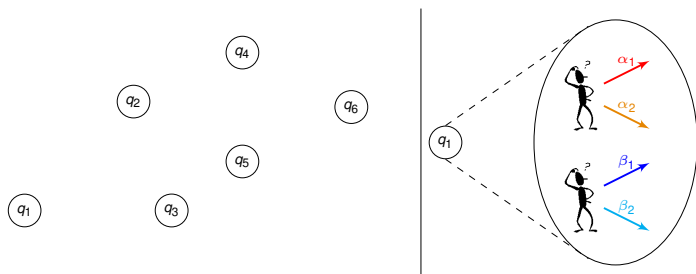
- ▶ **vertices** labeled by **atomic propositions**
- ▶ in vertices agents choose **actions**
- ▶ possible combinations → **transitions** (edges of the graph)

ATL: syntax and models

- **Syntax.** Formulae of ATL are given by the grammar:

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \langle\langle A \rangle\rangle \bigcirc \varphi \mid \langle\langle A \rangle\rangle \square \varphi \mid \langle\langle A \rangle\rangle \varphi \mathcal{U} \varphi$$

- **Models.** CGS's (**concurrent game structure**) are labeled transition systems:



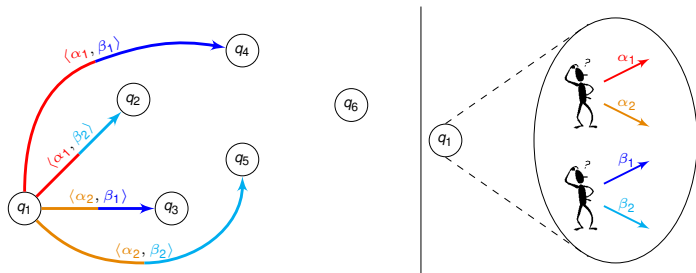
- ▶ **vertices** labeled by **atomic propositions**
- ▶ in vertices agents choose **actions**
- ▶ possible combinations \rightarrow **transitions** (edges of the graph)

ATL: syntax and models

- **Syntax.** Formulae of ATL are given by the grammar:

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \langle\langle A \rangle\rangle \bigcirc \varphi \mid \langle\langle A \rangle\rangle \square \varphi \mid \langle\langle A \rangle\rangle \varphi \mathcal{U} \varphi$$

- **Models.** CGS's (**concurrent game structure**) are labeled transition systems:



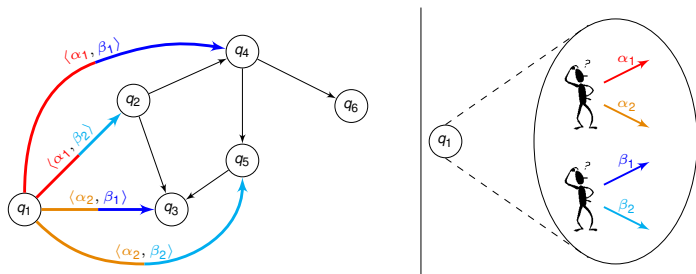
- ▶ **vertices** labeled by **atomic propositions**
- ▶ in vertices agents choose **actions**
- ▶ possible combinations \rightarrow **transitions** (edges of the graph)

ATL: syntax and models

- **Syntax.** Formulae of ATL are given by the grammar:

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \langle\langle A \rangle\rangle \bigcirc \varphi \mid \langle\langle A \rangle\rangle \square \varphi \mid \langle\langle A \rangle\rangle \varphi \mathcal{U} \varphi$$

- **Models.** CGS's (**concurrent game structure**) are labeled transition systems:



- ▶ **vertices** labeled by **atomic propositions**
- ▶ in vertices agents choose **actions**
- ▶ possible combinations \rightarrow **transitions** (edges of the graph)

ATL: (intuitive) semantics

Collective strategy for the **proponent** team to guarantee φ holds

ATL: (intuitive) semantics

Collective strategy for the **proponent** team to guarantee φ holds

$\langle\langle A \rangle\rangle \bigcirc \varphi$ next

ATL: (intuitive) semantics

Collective strategy for the **proponent** team to guarantee φ holds

$\langle\langle A \rangle\rangle \bigcirc \varphi$ next

$\langle\langle A \rangle\rangle \square \varphi$ always

ATL: (intuitive) semantics

Collective strategy for the **proponent** team to guarantee φ holds

$\langle\langle A \rangle\rangle \bigcirc \varphi$ next

$\langle\langle A \rangle\rangle \square \varphi$ always

$\langle\langle A \rangle\rangle \varphi \mathcal{U} \psi$ until ψ

ATL: (intuitive) semantics

Collective strategy for the **proponent** team to guarantee φ holds

$\langle\langle A \rangle\rangle \bigcirc \varphi$ next

$\langle\langle A \rangle\rangle \square \varphi$ always

$\langle\langle A \rangle\rangle \varphi \mathcal{U} \psi$ until ψ

regardless of actions performed by other agents (opponent)

Motivations

- ATL = coalition abilities + temporal goals
- pe-ATL = ATL + qualitative (parity) + quantitative (energy)

Motivations

- ATL = coalition abilities + temporal goals
- pe-ATL = ATL + qualitative (parity) + quantitative (energy)

Sample scenario:

- printing system: n printers + shared bounded printing queue
- $n + m$ agents (n printers + m users/environment)
- printer actions: { **n** (*do-nothing*), **p** (*print*) }
- user actions: { **n** (*do-nothing*), **j** (*send-a-job*) }

Motivations

- ATL = coalition abilities + temporal goals
- pe-ATL = ATL + qualitative (parity) + quantitative (energy)

Sample scenario:

- printing system: n printers + shared bounded printing queue
- $n + m$ agents (n printers + m users/environment)
- printer actions: { \mathbf{n} (*do-nothing*), \mathbf{p} (*print*) }
- user actions: { \mathbf{n} (*do-nothing*), \mathbf{j} (*send-a-job*) }

pe-ATL abilities

- avoid errors (i printers do *print* and queue only contains $j < i$ jobs)
(safety \mapsto coalition+temporal)
- queue is emptied infinitely often
(Büchi \mapsto parity)
- users send infinitely many jobs \Rightarrow queue is filled up infinitely often
(fairness \mapsto parity)
- devices' turnover
(alternation \mapsto energy)

Outline

1 Introduction and motivations

2 The logic pe-ATL

- pe-ATL at work

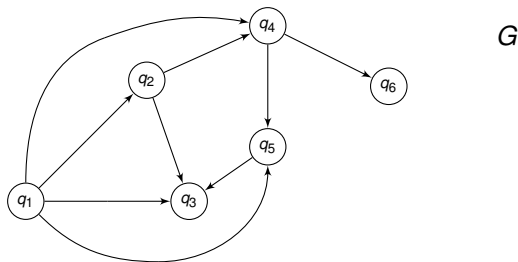
3 Model checking pe-ATL

- Warming up: Parity and energy conditions in isolation
- Unbounded $[-\infty, +\infty]$ and bounded $[a, b]$ energy range
- Left-bounded $[a, +\infty]$ and right-bounded $[-\infty, b]$ energy range

4 Conclusions

pe-ATL: syntax and models

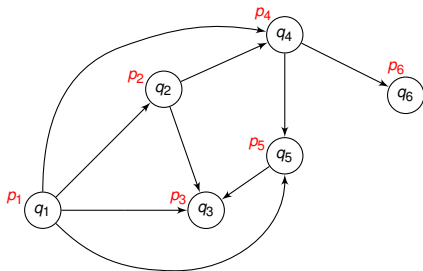
- **Syntax.** The same as ATL
- **Models.** pe-CGS = CGS + parity + energy conditions



- ▶ **vertices** labeled by **atomic propositions**
- ▶ in vertices agents choose **actions**
- ▶ possible combinations \rightarrow **transitions** (edges of the graph)
- ▶ **parity condition**
- ▶ **energy condition**

pe-ATL: syntax and models

- **Syntax.** The same as ATL
- **Models.** pe-CGS = CGS + parity + energy conditions

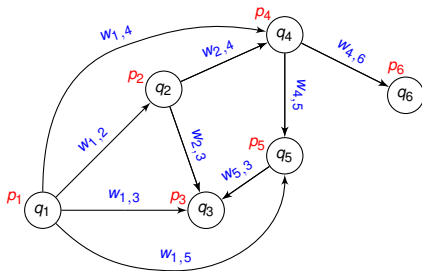


$\langle G, p \rangle$

- ▶ **vertices** labeled by **atomic propositions**
- ▶ in vertices agents choose **actions**
- ▶ possible combinations → **transitions** (edges of the graph)
- ▶ **parity condition**
- ▶ **energy condition**

pe-ATL: syntax and models

- **Syntax.** The same as ATL
- **Models.** pe-CGS = CGS + parity + energy conditions



$\langle G, p, e \rangle$

- initial energy level \mathcal{E}_0
- energy range $[a, b]$

- ▶ **vertices** labeled by **atomic propositions**
- ▶ in vertices agents choose **actions**
- ▶ possible combinations \rightarrow **transitions** (edges of the graph)
- ▶ **parity condition**
- ▶ **energy condition**

pe-ATL: (intuitive) semantics

Collective (p, e) -strategy for the proponent team to guarantee φ holds

$\langle\langle A \rangle\rangle \bigcirc \varphi$ next

$\langle\langle A \rangle\rangle \square \varphi$ always

$\langle\langle A \rangle\rangle \varphi \mathcal{U} \psi$ until ψ

regardless of actions performed by other agents (opponent)

pe-ATL: (intuitive) semantics

Collective (p, e) -strategy for the proponent team to guarantee φ holds

$\langle\langle A \rangle\rangle \bigcirc \varphi$ next

$\langle\langle A \rangle\rangle \square \varphi$ always

$\langle\langle A \rangle\rangle \varphi \mathcal{U} \psi$ until ψ

regardless of actions performed by other agents (opponent)

strategies must be (p, e) -strategies, i.e.,
they only produce plays satisfying **parity** and **energy** conditions

Outline

1 Introduction and motivations

2 The logic pe-ATL

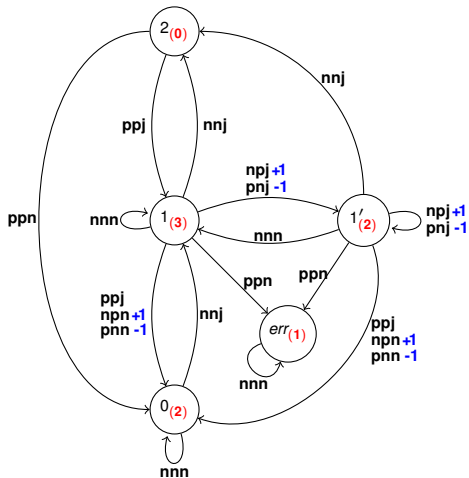
- pe-ATL at work

3 Model checking pe-ATL

- Warming up: Parity and energy conditions in isolation
- Unbounded $[-\infty, +\infty]$ and bounded $[a, b]$ energy range
- Left-bounded $[a, +\infty]$ and right-bounded $[-\infty, b]$ energy range

4 Conclusions

The printing system scenario



agents = $\{p_1, p_2, u\}$

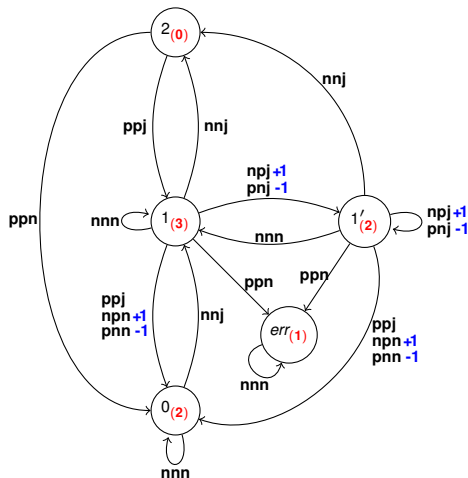
actions	p_1	p_2	u	joint actions
0	n	n	nj	{nnn, nnj}
1	np	np	nj	{nnn, nnj, npn, npj, pnn, pnj, ppn, ppj}
1'	np	np	nj	{nnn, nnj, npn, npj, pnn, pnj, ppn, ppj}
2	p	p	nj	{ppn, ppj}
err	n	n	n	{nnn}

energy weights $w(\text{nnx}) = w(\text{ppx}) = 0$
 $w(\text{npx}) = +1$
 $w(\text{pnx}) = -1$

energy range = $[0, 1]$

initial energy level $\mathcal{E}_0 = 0$

The printing system scenario

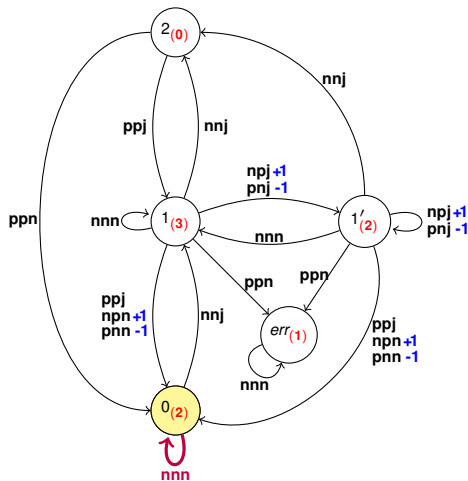


$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

The printing system scenario



$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

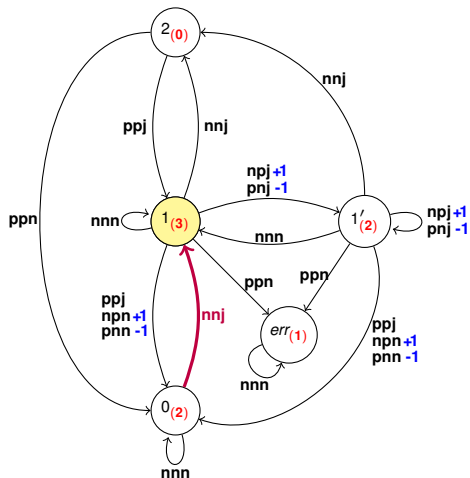
\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

0

$\in [0, 1]$

The printing system scenario



$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

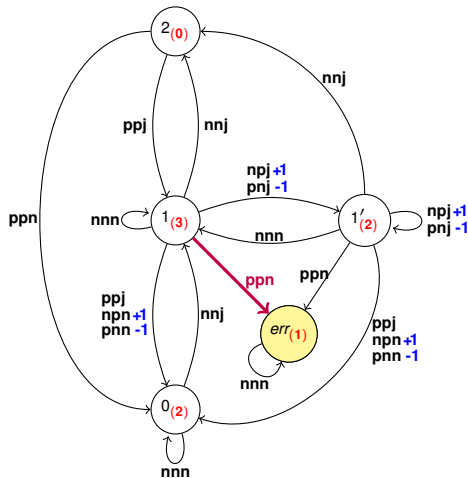
\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

0

$\in [0, 1]$

The printing system scenario



$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

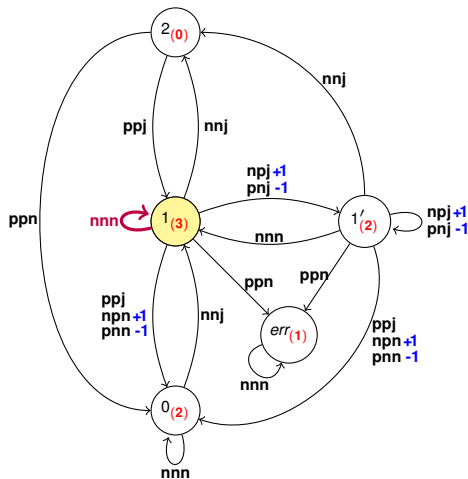
\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

0

$\in [0, 1]$

The printing system scenario



$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

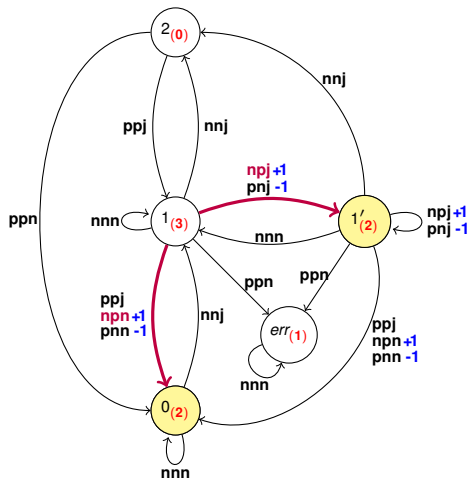
\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

0

$\in [0, 1]$

The printing system scenario



$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

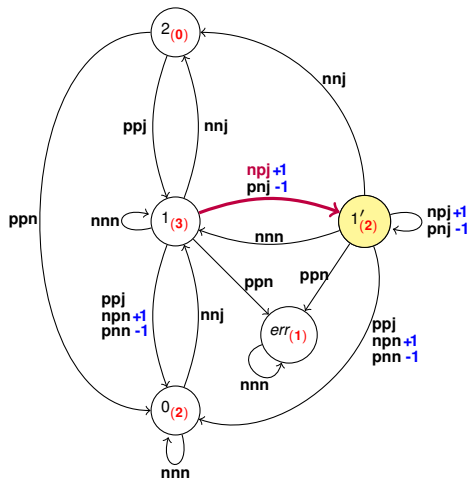
\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

01

$\in [0, 1]$

The printing system scenario



$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

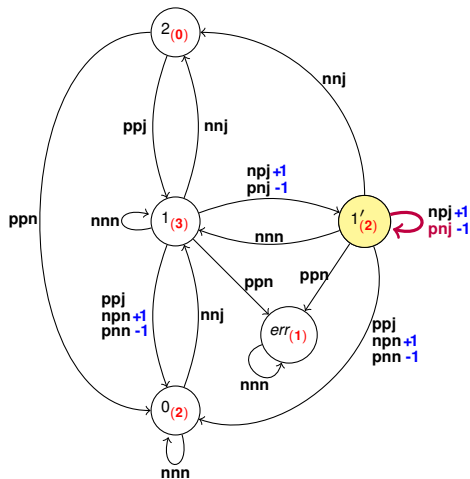
\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

01

$\in [0, 1]$

The printing system scenario



$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

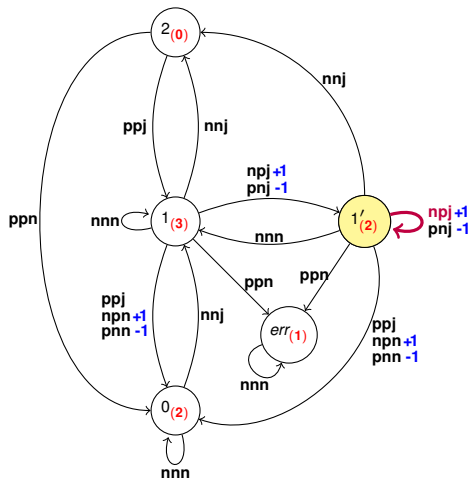
\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

0 1 0

$\in [0, 1]$

The printing system scenario



$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

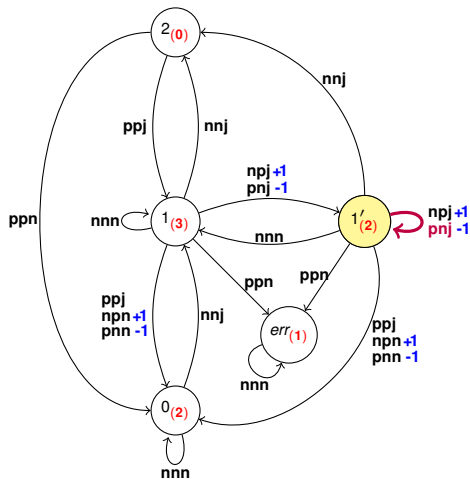
\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

0101

$\in [0, 1]$

The printing system scenario



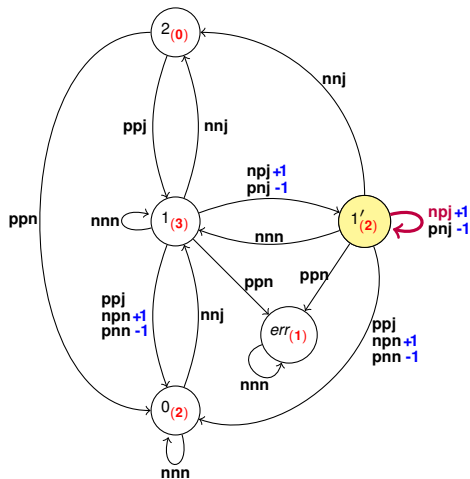
$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

$$01010 \in [0, 1]$$

The printing system scenario



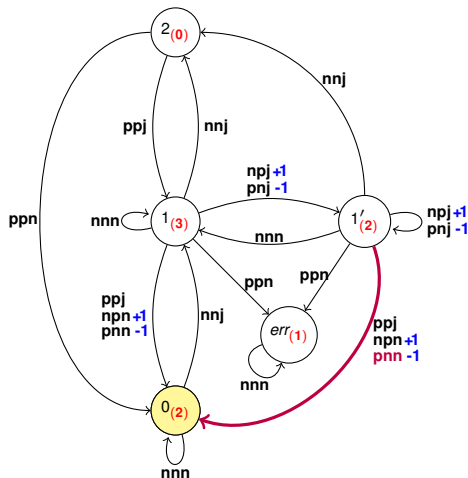
$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

$$010101 \in [0, 1]$$

The printing system scenario



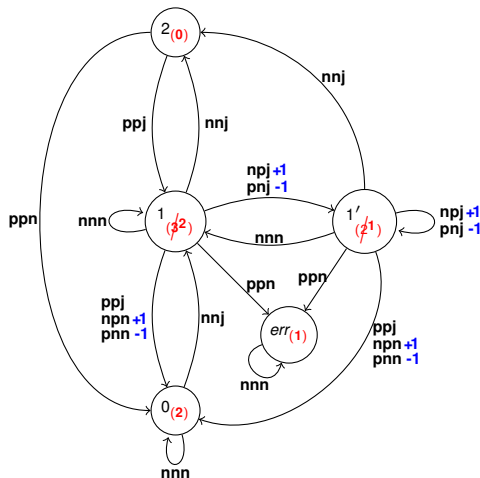
$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- all jobs are processed (parity)
- printers alternate (energy)

$$0101010 \in [0, 1]$$

The printing system scenario



$$\mathcal{G}, 0 \models \langle\langle \{p_1, p_2\} \rangle\rangle \Box \neg err$$

\exists joint strategy for p_1 and p_2 s.t.:

- error state is avoided (temporal)
- if user sends infinitely many jobs, then queue is filled up infinitely often (parity)
- printers alternate (energy)

Outline

1 Introduction and motivations

2 The logic pe-ATL

- pe-ATL at work

3 Model checking pe-ATL

- Warming up: Parity and energy conditions in isolation
- Unbounded $[-\infty, +\infty]$ and bounded $[a, b]$ energy range
- Left-bounded $[a, +\infty]$ and right-bounded $[-\infty, b]$ energy range

4 Conclusions

Outline

1 Introduction and motivations

2 The logic pe-ATL

- pe-ATL at work

3 Model checking pe-ATL

- **Warming up: Parity and energy conditions in isolation**
- Unbounded $[-\infty, +\infty]$ and bounded $[a, b]$ energy range
- Left-bounded $[a, +\infty]$ and right-bounded $[-\infty, b]$ energy range

4 Conclusions

The model checking problem

Definition (pe-ATL model checking problem)

Given a pe-CGS $\mathcal{G} = \langle G, p, e \rangle$ and a pe-ATL formula φ , establish whether $\mathcal{G} \models \varphi$

Definition (p-ATL/e-ATL)

- p-ATL: relax the energy condition
strategies fulfill **parity condition only**
- e-ATL relaxing the parity condition
strategies fulfill **energy condition only**

Parity and energy conditions in isolation

Lemma

p-ATL/e-ATL model checking problem easily reduce to pe-ATL one

- spurious parity condition:
 - ▶ $p(q) = 0$ for all $q \in Q$
 - all parity are even and so is the smallest occurring infinitely often
- spurious energy condition:
 - ▶ weight is 0 for every transition
 - ▶ initial energy level is any value in the energy range, e.g., a
 - initial energy level is in range and never changes

Outline

1 Introduction and motivations

2 The logic pe-ATL

- pe-ATL at work

3 Model checking pe-ATL

- Warming up: Parity and energy conditions in isolation
- **Unbounded $[-\infty, +\infty]$ and bounded $[a, b]$ energy range**
- Left-bounded $[a, +\infty]$ and right-bounded $[-\infty, b]$ energy range

4 Conclusions

Unbounded energy range $[-\infty, +\infty]$

- Just ignore the energy condition (p-ATL instead of pe-ATL)
- Also, the problem easily reduces to the bounded case:
 - ▶ $w(t) = 0$ for all transitions
 - ▶ $[a, b] = [0, 0]$
 - ▶ $\mathcal{E}^{init} = 0$

Bounded energy range $[a, b]$

- $a \neq -\infty, b \neq +\infty$

Lemma (normalization)

It is possible to focus on instances where no rationals are involved

- integer energy range ($a, b \in \mathbb{Z}$)
- integer initial energy level ($\mathcal{E}^{init} \in \mathbb{Z}$)
- weights over transitions are integers as well

Lemma (positional strategies)

- a (p, e) -strategy exists iff a uniform one exists (bounded instance)
- a (p, e) strategy exists iff a memoryless one exists (unbounded instance)

Bounded energy range $[a, b]$

- $a \neq -\infty, b \neq +\infty$

Lemma (normalization)

It is possible to focus on instances where no rationals are involved

- integer energy range ($a, b \in \mathbb{Z}$)
- integer initial energy level ($\mathcal{E}^{init} \in \mathbb{Z}$)
- weights over transitions are integers as well

Lemma (positional strategies)

- a (p, e) -strategy exists iff a uniform one exists (bounded instance)
- a (p, e) strategy exists iff a memoryless one exists (unbounded instance)

(Un)Bounded energy range $[a, b]$: Complexity

- uniform strategies: positional in $Q \times [a, b]$ (**exponentially** many positions $(q, \text{energy-level})$ when a and b are in binary—thanks to **normalization**)
- memoryless strategies: positional in Q (**polynomially** many positions q)

A non-deterministic algorithm:

- guess the strategy
- return **false** when a loop with odd parity or an out-of-range is detected
- no position is visited twice
- bounded case: exponential time
- unbounded case: polynomial time

Outline

1 Introduction and motivations

2 The logic pe-ATL

- pe-ATL at work

3 Model checking pe-ATL

- Warming up: Parity and energy conditions in isolation
- Unbounded $[-\infty, +\infty]$ and bounded $[a, b]$ energy range
- Left-bounded $[a, +\infty]$ and right-bounded $[-\infty, b]$ energy range

4 Conclusions

Left-bounded energy range $[a, +\infty]$

(right-bounded energy range $[-\infty, b]$ is symmetric)

- Model-theoretic argument (technically quite involved)
- Difficulty: the space of positions (q , *energy-level*) is infinite
- We define suitable structures (**witnesses**)
 - ▶ compact representations for strategies
 - ▶ bounded size
 - ▶ we prove it to be complete for strategies
- A non-deterministic algorithm guesses one such structure and check that it is indeed a witness for the desired strategy

Key ideas

- A witness (for a $\langle\langle A \rangle\rangle \Box \psi$ formula) is a pair of graphs

$$(S_1, S_2)$$

- Elements of such graphs are positions $(q, \text{energy-level})$

$(q, \text{energy-level}) \in S$ iff there is a *winning* strategy for A , i.e.,
a (p, e) -strategy that guarantees the invariant ψ

- Left-bounded range ensures monotonicity

a strategy exists from $(q, \text{energy-level})$ iff a strategy exists from (q, E) for all $E \geq \text{energy-level}$

- Thus, only the smallest energy level appears in S_1 and S_2 for each q

$$|S_1| \leq |Q|, \quad |S_2| \leq |Q|$$

- S_1 represents the strategy for parity and temporal goals
 S_2 contains increasing loops to increase the energy levels

Key ideas

- A witness (for a $\langle\langle A \rangle\rangle \Box \psi$ formula) is a pair of graphs

$$(S_1, S_2)$$

- Elements of such graphs are positions $(q, \text{energy-level})$

$(q, \text{energy-level}) \in S$ iff there is a *winning* strategy for A , i.e.,
a (p, e) -strategy that guarantees the invariant ψ

- Left-bounded range ensures monotonicity

a strategy exists from $(q, \text{energy-level})$ iff a strategy exists from (q, E) for all $E \geq \text{energy-level}$

- Thus, only the smallest energy level appears in S_1 and S_2 for each q

$$|S_1| \leq |Q|, \quad |S_2| \leq |Q|$$

- S_1 represents the strategy for parity and temporal goals
 S_2 contains increasing loops to increase the energy levels

Key ideas

- A witness (for a $\langle\langle A \rangle\rangle \Box \psi$ formula) is a pair of graphs

$$(S_1, S_2)$$

- Elements of such graphs are positions $(q, \text{energy-level})$

$(q, \text{energy-level}) \in S$ iff there is a *winning* strategy for A , i.e.,
a (p, e) -strategy that guarantees the invariant ψ

- Left-bounded range ensures monotonicity

a strategy exists from $(q, \text{energy-level})$ iff a strategy exists from (q, E) for all $E \geq \text{energy-level}$

- Thus, only the smallest energy level appears in S_1 and S_2 for each q

$$|S_1| \leq |Q|, \quad |S_2| \leq |Q|$$

- S_1 represents the strategy for parity and temporal goals
 S_2 contains increasing loops to increase the energy levels

Key ideas

- A witness (for a $\langle\langle A \rangle\rangle \Box \psi$ formula) is a pair of graphs

$$(S_1, S_2)$$

- Elements of such graphs are positions $(q, \text{energy-level})$

$(q, \text{energy-level}) \in S$ iff there is a *winning* strategy for A , i.e.,
a (p, e) -strategy that guarantees the invariant ψ

- Left-bounded range ensures monotonicity

a strategy exists from $(q, \text{energy-level})$ iff a strategy exists from (q, E) for all $E \geq \text{energy-level}$

- Thus, only the smallest energy level appears in S_1 and S_2 for each q

$$|S_1| \leq |Q|, \quad |S_2| \leq |Q|$$

- S_1 represents the strategy for parity and temporal goals
 S_2 contains increasing loops to increase the energy levels

Key ideas

- A witness (for a $\langle\langle A \rangle\rangle \Box \psi$ formula) is a pair of graphs

$$(S_1, S_2)$$

- Elements of such graphs are positions $(q, \text{energy-level})$

$(q, \text{energy-level}) \in S$ iff there is a *winning* strategy for A , i.e.,
a (p, e) -strategy that guarantees the invariant ψ

- Left-bounded range ensures monotonicity

a strategy exists from $(q, \text{energy-level})$ iff a strategy exists from (q, E) for all $E \geq \text{energy-level}$

- Thus, only the smallest energy level appears in S_1 and S_2 for each q

$$|S_1| \leq |Q|, \quad |S_2| \leq |Q|$$

- S_1 represents the strategy for parity and temporal goals
 S_2 contains increasing loops to increase the energy levels

Alechina, Logan, Nguyen, Raimondi, JCSS (2017)

Model-checking for Resource-Bounded ATL with production and consumption of resources, p. 126–144

From witnesses to strategies

- *internal constraints*

- ▶ e.g., elements of S_1 and S_2 satisfy the invariant ψ in a formula $\langle\langle A \rangle\rangle \Box \psi$

- *diagonal constraints*

- ▶ e.g., elements of S_1 with low energy level also occur as (and can be merged with) elements of S_2

- the unfolding/merging of S_1 and S_2 corresponds to the outcome of a winning strategy for A

From strategies to witnesses

Witness construction

(from the **tree** \mathcal{T} of outcomes of a winning strategy for A)

- q appears in the witness iff it appears in the tree \mathcal{T}
- suitably cut tree \mathcal{T} into a finite (not bounded) prefix
- for every q , a representative node in the cut of \mathcal{T} is chosen
 - ▶ based on their **topological order** and their **energy level** in the tree
- energy level and outgoing transition for q in the witness are determined by its representative in the cut of \mathcal{T}

Outline

1 Introduction and motivations

2 The logic pe-ATL

- pe-ATL at work

3 Model checking pe-ATL

- Warming up: Parity and energy conditions in isolation
- Unbounded $[-\infty, +\infty]$ and bounded $[a, b]$ energy range
- Left-bounded $[a, +\infty]$ and right-bounded $[-\infty, b]$ energy range

4 Conclusions

Conclusions

- pe-ATL: **coalitional** abilities to pursue **temporal** goals while satisfying qualitative (**parity**) and quantitative (**energy**) conditions
- pe-ATL model checking problem

Theorem

The model checking problem for pe-ATL is:

- in NEXPTIME if the energy range is bounded ($[a, b]$)
- in NPTIME if the energy range is unbounded ($[-\infty, +\infty]$)
- in NPTIME if the energy range is left- or right-unbounded ($[a, +\infty]$ or $[-\infty, b]$)

Future work

- establishing tight complexity bounds (parity game complexity)
- to extend the proposed framework to ATL^*
 - ▶ comparison of the expressive power with ATL^* and other logics for strategic reasoning, e.g., SR
- different modeling choices
 - ▶ energy level evolves along the entire game
 - ▶ opponent must also act according to parity and energy conditions

Bulling & Farwer, ECAI 2010

On the (Un-)Decidability of Model Checking Resource-Bounded Agents, p. 567–572

The end

Thank you!