

Department of Mathematics, Computer Science and Physics, University of Udine

The Safety Fragment of Temporal Logics on Infinite Sequences

Lesson 6

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April 15th, 2024



The cosafety fragment of LTL

Temporal Logics

We say that a temporal logic \mathbb{L} is *cosafety* iff, for any $\phi \in \mathbb{L}$, $\mathcal{L}(\phi)$ is *cosafety*.

coSafetyLTL

Definition

$\phi := p \mid \neg p \mid \phi \vee \phi \mid \phi \wedge \phi \mid X\phi \mid F\phi \mid \phi U \phi$

Example:

$p U q$

F(pLTL)

Definition

$\phi := F(\alpha)$, where $\alpha \in \text{pLTL}$, that is α is a pure-past LTL formula.

Example:

$F(q \wedge \tilde{Y}Hp)$

F(pLTL) is the **canonical form** of coSafetyLTL.



Theorem

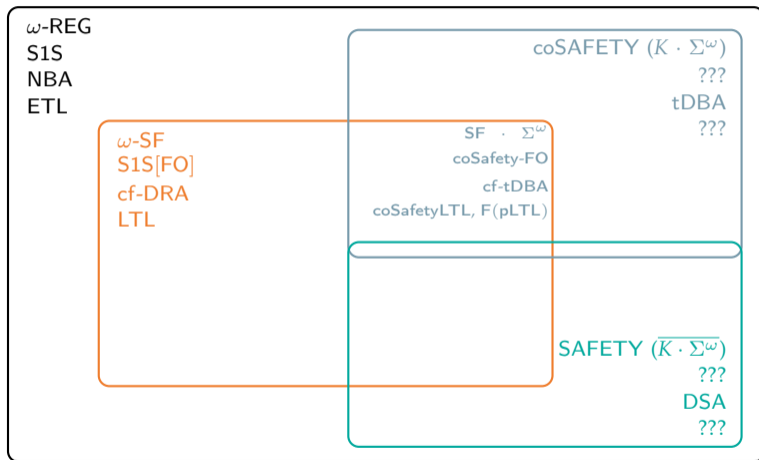
- coSafetyLTL and $F(\text{pLTL})$ are expressively equivalent.
- coSafetyLTL and $F(\text{pLTL})$ are expressively complete w.r.t. $[[\text{LTL}]] \cap \text{coSAFETY}$.

Reference:

Edward Y. Chang, Zohar Manna, and Amir Pnueli (1992). “Characterization of Temporal Property Classes”. In: *Proceedings of the 19th International Colloquium on Automata, Languages and Programming*. Ed. by Werner Kuich. Vol. 623. Lecture Notes in Computer Science. Springer, pp. 474–486. DOI: 10.1007/3-540-55719-9_97



Set-theoretic view of (co)safety ω -languages





Proposition

$$\llbracket \text{coSafetyLTL} \rrbracket^{<\omega} \subsetneq \llbracket \text{LTL} \rrbracket^{<\omega}$$

Proof.

- It is simple to prove that, for all $\phi \in \text{coSafetyLTL}$, $\mathcal{L}^{<\omega}(\phi) = \mathcal{L}^{<\omega}(\phi) \cdot \Sigma^*$. In particular, either $|\mathcal{L}^{<\omega}(\phi)| = 0$ or $|\mathcal{L}^{<\omega}(\phi)| = \omega$ for all $\phi \in \text{coSafetyLTL}$.
- In LTL_f we can use the *weak tomorrow* operator to hook the last position of a finite word.

$$\psi := p \wedge \tilde{X}\perp$$

The formula ψ is such that $|\mathcal{L}^{<\omega}(\psi)| = 1$. Therefore, it can't be expressed in coSafetyLTL over finite words.



Proposition

$$\llbracket \text{coSafetyLTL} \rrbracket^{<\omega} \subsetneq \llbracket \text{LTL} \rrbracket^{<\omega}$$

Proposition

$$\llbracket \text{coSafetyLTL} \rrbracket^{<\omega} \cdot (2^\Sigma)^\omega = \llbracket \text{LTL} \rrbracket^{<\omega} \cdot (2^\Sigma)^\omega$$



Reference:

Alessandro Cimatti et al. (2022). “A first-order logic characterisation of safety and co-safety languages”. In: *Foundations of Software Science and Computation Structures - 25th International Conference, FOSSACS 2022, Held as Part of the European Joint Conferences on Theory and Practice of Software, ETAPS 2022, Munich, Germany, April 2-7, 2022, Proceedings*. Ed. by Patricia Bouyer and Lutz Schröder. Vol. 13242. Lecture Notes in Computer Science. Springer, pp. 244–263. DOI: 10.1007/978-3-030-99253-8_13. URL: https://doi.org/10.1007/978-3-030-99253-8%5C_13



$$\begin{aligned} & \llbracket LTL \rrbracket \cap \text{coSAFETY} \\ & = \\ & \llbracket \text{coSafetyLTL} \rrbracket \\ & = \\ & \llbracket F(pLTL) \rrbracket \\ & = \\ & \llbracket \text{coSafetyLTL} \rrbracket^{<\omega} \cdot (2^\Sigma)^\omega \\ & = \\ & \llbracket LTL \rrbracket^{<\omega} \cdot (2^\Sigma)^\omega \end{aligned}$$



Definition

The *safety fragment* of LTL is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{SAFETY}$$

We will see four characterizations in terms of:

- regular expressions
- automata
- first-order logic
- temporal logic



Definition

The *safety fragment* of LTL is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{SAFETY}$$

ω -regular expressions

$$\overline{\text{SF}} \cdot \overline{\Sigma^\omega} = \{ \overline{K} \cdot \overline{\Sigma^\omega} \mid K \in \text{SF} \}$$

- the "SF" part corresponds to LTL
- the " $\overline{\Sigma^\omega}$ " part corresponds to being a safety fragment

Ina Schiering and Wolfgang Thomas (1996). "Counter-free automata, first-order logic, and star-free expressions extended by prefix oracles". In: *Developments in Language Theory, II (Magdeburg, 1995)*, World Sci. Publishing, River Edge, NJ, pp. 166–175



Definition

The *safety fragment* of LTL is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{SAFETY}$$

First-order logic

We define **Safety-FO** as the fragment of S1S[FO] in which quantifiers are bounded as follows:

- $\exists y . (x < y < z \wedge \dots)$
- $\forall y . (x < y \rightarrow \dots)$

Alessandro Cimatti et al. (2022). "A first-order logic characterisation of safety and co-safety languages". In: *Foundations of Software Science and Computation Structures - 25th International Conference, FOSSACS 2022, Held as Part of the European Joint Conferences on Theory and Practice of Software, ETAPS 2022, Munich, Germany, April 2-7, 2022, Proceedings*. Ed. by Patricia Bouyer and Lutz Schröder. Vol. 13242. Lecture Notes in Computer Science. Springer, pp. 244–263. DOI: 10.1007/978-3-030-99253-8_13. URL: https://doi.org/10.1007/978-3-030-99253-8%5C_13



Definition

The *safety fragment* of LTL is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{SAFETY}$$

First-order logic

Example

$$\phi(x) := \forall y . ((x < y \wedge G(y)) \rightarrow \exists z . (x < z < y \wedge R(z)))$$



Definition

The *safety fragment* of LTL is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{SAFETY}$$

First-order logic

- the "first-order" part corresponds to LTL
- the "bounded quantifiers" part corresponds to being a safety fragment



Definition

The *safety fragment* of LTL is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{SAFETY}$$

Automata

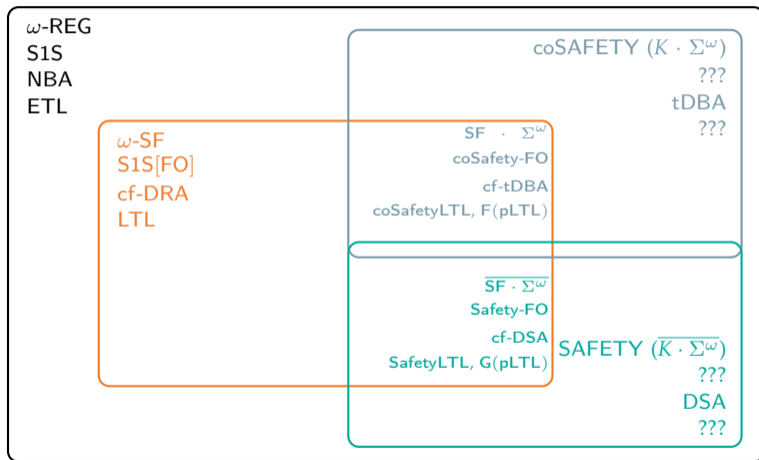
cf-DSA = counter-free DSA

- the "counter-free" part corresponds to LTL
- the "DSA" part corresponds to being a safety fragment

Ina Schiering and Wolfgang Thomas (1996). "Counter-free automata, first-order logic, and star-free expressions extended by prefix oracles". In: *Developments in Language Theory, II (Magdeburg, 1995)*, World Sci. Publishing, River Edge, NJ, pp. 166–175



Set-theoretic view of the (co)safety fragment of LTL





The safety fragment of LTL

Temporal Logics

We say that a temporal logic \mathbb{L} is *safety* iff, for any $\phi \in \mathbb{L}$, $\mathcal{L}(\phi)$ is *safety*.

SafetyLTL

Definition

$\phi := p \mid \neg p \mid \phi \vee \phi \mid \phi \wedge \phi \mid X\phi \mid G\phi \mid \phi R \phi$

Example:

$G(r \rightarrow XXg)$

G(pLTL)

Definition

$\phi := G(\alpha)$, where $\alpha \in \text{pLTL}$, that is α is a pure-past LTL formula.

Example:

$G(\tilde{Y}\tilde{Y}r \rightarrow g)$

$G(\text{pLTL})$ is the **canonical form** of SafetyLTL.



Proposition

- $\phi \in \text{SafetyLTL}$ iff $\text{nnf}(\neg\phi) \in \text{coSafetyLTL}$
- $\phi \in G(\text{pLTL})$ iff $\text{nnf}(\neg\phi) \in F(\text{pLTL})$



Theorem

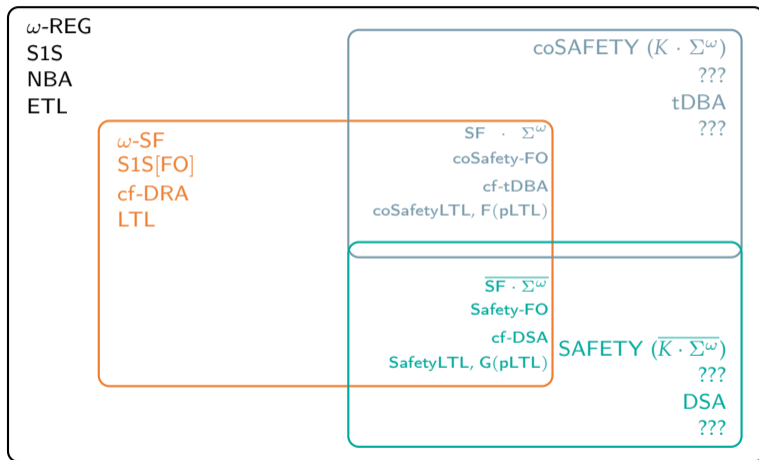
- SafetyLTL and $G(\text{pLTL})$ are expressively equivalent.
- SafetyLTL and $G(\text{pLTL})$ are expressively complete w.r.t. $\llbracket \text{LTL} \rrbracket \cap \text{SAFETY}$.

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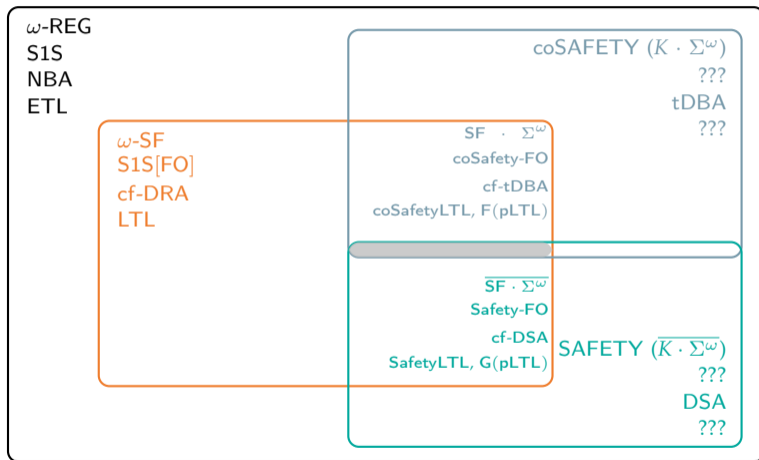


Set-theoretic view of (co)safety ω -languages





Set-theoretic view of (co)safety ω -languages





- We denote with \mathbb{B} the set of Boolean formulas.
- We denote with LTL[X] the set of LTL formulas in which the only temporal operator that is used is the *tomorrow* (X).

Proposition

- $\mathbb{B} \subseteq \text{LTL} \cap \text{coSAFETY} \cap \text{SAFETY}$
- $\text{LTL}[X] \subseteq \text{LTL} \cap \text{coSAFETY} \cap \text{SAFETY}$



Other safety and cosafety fragments

Cosafety

- We denote with $LTL[X, F]$ the set of coSafetyLTL formulas in which the only temporal operators that are used are the *tomorrow* (X) and the *eventually* (F).
- Clearly, $LTL[X, F]$ is a cosafety logic, but it is strictly less expressive than coSafetyLTL.

Proposition

$\llbracket LTL[X, F] \rrbracket \subsetneq \llbracket \text{coSafetyLTL} \rrbracket$

E.g. $p \cup q$ is not definable in $LTL[X, F]$.

Safety

- We denote with $LTL[X, G]$ the set of SafetyLTL formulas in which the only temporal operators that are used are the *tomorrow* (X) and the *globally* (G).
- Clearly, $LTL[X, G]$ is a safety logic, but it is strictly less expressive than SafetyLTL.

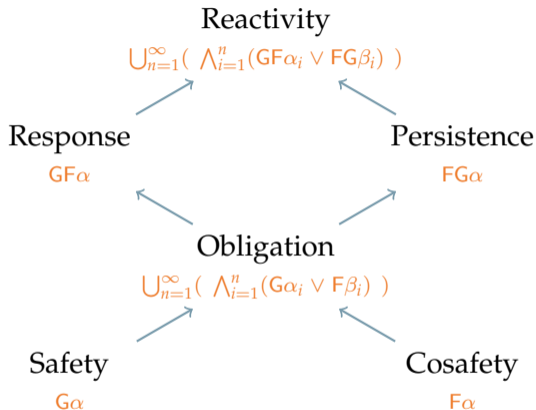
Proposition

$\llbracket LTL[X, G] \rrbracket \subsetneq \llbracket \text{SafetyLTL} \rrbracket$

E.g. $p \text{ R } q$ is not definable in $LTL[X, G]$.



The Temporal Hierarchy



Legend:

- $\alpha, \alpha_i, \beta, \beta_i$ are pure-past LTL formulas (pLTL)
- \rightarrow denotes set inclusion

Theorem

$Reactivity = \llbracket LTL \rrbracket$

Zohar Manna and Amir Pnueli (1990). "A hierarchy of temporal properties (invited paper, 1989)". In: *Proceedings of the 9th annual ACM symposium on Principles of distributed computing*, pp. 377–410. DOI:

[10.1145/93285.93442](https://doi.org/10.1145/93285.93442)

Kupferman and Vardi's Classification of the safety properties of LTL



Consider the formula $G(p)$. The following trace is a *bad prefix*:



Recall that $\sigma \in \Sigma^*$ is a bad prefix for a language \mathcal{L} iff $\sigma \cdot \sigma' \notin \mathcal{L}$, for all $\sigma' \in \Sigma^\omega$.



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Recall that $\sigma \in \Sigma^*$ is a bad prefix for a language \mathcal{L} iff $\sigma \cdot \sigma' \notin \mathcal{L}$, for all $\sigma' \in \Sigma^\omega$.

Consider now the formula

$G(p \vee (Xq \wedge X\neg q))$.

- it is equivalent to $G(p)$
- therefore, it is a safety formula
- its set of *bad prefixes* is the same as the one of $G(p)$



Classification of Safety Properties

by Kupferman and Vardi

Consider the formula $G(p)$. The following trace is a *bad prefix*:



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- it is equivalent to $G(p)$
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- its set of *bad prefixes* is the same as the one of $G(p)$

Nevertheless, the previous prefix does *not* tell the whole story about the violation of $G(p \vee (Xq \wedge X\neg q))$. In fact:

- Negation of the above formula:

$$F(\neg p \wedge (X\neg q \vee Xq))$$

- Any violation depends on the fact that at certain point:
 - p is false **and**
 - in the *next* state q or $\neg q$ holds. (*this is always true*)
- In the previous prefix, the point in which $\neg p$ holds does *not* have a successor:
 - the prefix is *not informative*



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- Negation of the above formula:

$$F(\neg p \wedge (X\neg q \vee Xq))$$

- This prefix is *informative* for the formula:



- Consider the specification:

$$G(p \vee (Xq \wedge \phi \wedge X\neg q))$$

where ϕ is a very complex Boolean formula.

- If the user is given the prefix



then it is very hard for him/her to notice that the specification contains a redundant part ($Xq \wedge X\neg q$).

- If instead the user is given this prefix



then he/she

- notice that the *first* state in which $\neg p$ holds has a successor
- inspect the parts of the specification that talk about the successor state ($Xq \wedge X\neg q$)
- notice that they are *redundant*
- and finally remove them.



Classification of Safety Properties

by Kupferman and Vardi

- This intuition of a prefix that “*tells the whole story*” is the base for a classification of safety properties in three distinct safety levels.
- This intuition is formalized by defining the notion of *informative prefix*
 - it is based on the semantics of LTL over finite traces

Reference:

Orna Kupferman and Moshe Y Vardi (2001). “Model checking of safety properties”. In: *Formal Methods in System Design* 19.3, pp. 291–314. DOI: 10.1023/A:1011254632723



Classification of Safety Properties

by Kupferman and Vardi

Usage:

- Detect the cause of inconsistent specifications:
 - e.g.: in formulas like $G(p \vee (Xq \wedge \phi \wedge X\neg q))$, the cause of inconsistency may not be easy to notice by the user, especially in more complicated examples
- Efficient automata construction
 - The automaton that recognizes all and only the informative prefixes of a formula is *exponentially smaller* than the automaton recognizing all and only the bad prefixes.
 - \Rightarrow Efficient algorithms for model checking

Reference:

Orna Kupferman and Moshe Y Vardi (2001). "Model checking of safety properties". In: *Formal Methods in System Design* 19.3, pp. 291–314. DOI: 10.1023/A:1011254632723



Recall that $\text{nnf}(\psi)$ is the *negation normal form* of ψ , that is, a formula equivalent to ψ but with negations only applied to atomic propositions.

We define a new semantics for LTL interpreted over finite traces, that we denote with \models_{KV} .

- $\sigma, i \models_{\text{KV}} p$ iff $p \in \sigma_i$
- $\sigma, i \models_{\text{KV}} \phi_1 \vee \phi_2$ iff $\sigma, i \models_{\text{KV}} \phi_1$ or $\sigma, i \models_{\text{KV}} \phi_2$
- $\sigma, i \models_{\text{KV}} \phi_1 \wedge \phi_2$ iff $\sigma, i \models_{\text{KV}} \phi_1$ and $\sigma, i \models_{\text{KV}} \phi_2$
- $\sigma, i \models_{\text{KV}} X\phi$ iff $i + 1 < |\sigma|$ and $\sigma, i + 1 \models_{\text{KV}} \phi$



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- $\sigma, i \models_{\text{KV}} X\phi$ iff $i + 1 < |\sigma|$ and $\sigma, i + 1 \models_{\text{KV}} \phi$
- $\sigma, i \models_{\text{KV}} F\phi$ iff $\exists i \leq j < |\sigma|$ and $\sigma, j \models_{\text{KV}} \phi$
- $\sigma, i \models_{\text{KV}} G\phi$ is **always false**



Recall that $\text{nnf}(\psi)$ is the *negation normal form* of ψ , that is, a formula equivalent to ψ but with negations only applied to atomic propositions.

We define a new semantics for LTL interpreted over finite traces, that we denote with \models_{KV} .

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- $\sigma, i \models_{\text{KV}} \phi_1 \wedge \phi_2$ iff $\sigma, i \models_{\text{KV}} \phi_1$ and $\sigma, i \models_{\text{KV}} \phi_2$
- $\sigma, i \models_{\text{KV}} X\phi$ iff $i + 1 < |\sigma|$ and $\sigma, i + 1 \models_{\text{KV}} \phi$
- $\sigma, i \models_{\text{KV}} \phi_1 \text{ U } \phi_2$ iff $\exists i \leq j < |\sigma| . \sigma, j \models_{\text{KV}} \phi_2$ and $\forall i \leq k < j . \sigma, k \models_{\text{KV}} \phi_1$
- $\sigma, i \models_{\text{KV}} \phi_1 \text{ R } \phi_2$ iff $\exists i \leq j < |\sigma| . \sigma, j \models_{\text{KV}} \phi_1$ and $\forall i \leq k < j . \sigma, k \models_{\text{KV}} \phi_2$



Intuition:

If $\sigma \models_{KV} \text{nnf}(\neg\phi)$, then σ carries all the information to violate ϕ over infinite traces.

Remark

The definition of \models_{KV} is exactly the one used in *Bounded Model Checking* for defining the truth of an LTL formula over a finite trace.

Reference:

Armin Biere et al. (2003). "Bounded model checking". In: *Adv. Comput.* 58, pp. 117–148. DOI: 10.1016/S0065-2458(03)58003-2. URL: [https://doi.org/10.1016/S0065-2458\(03\)58003-2](https://doi.org/10.1016/S0065-2458(03)58003-2)



Definition (Informative Prefix)

Let ϕ be an LTL formula over \mathcal{AP} and let $\sigma \in (2^{\mathcal{AP}})^+$ be a finite trace over $2^{\mathcal{AP}}$.

σ is an *informative prefix* for ϕ
iff
 $\sigma \models_{KV} \text{nnf}(\neg\phi)$

Note: in the original paper by Kupferman and Vardi, informative prefixes are defined using a mapping L . This is equivalent to our definition.



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iff
 $\sigma \models_{KV} \text{nnf}(\neg\phi)$

Example:

This prefix is *informative* for $G(p)$.



$$\text{nnf}(\neg G(p)) := F(\neg p)$$



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iff
 $\sigma \models_{KV} \text{nnf}(\neg\phi)$

Example:

This prefix is not *informative* for $\phi := G(p \vee (Xq \wedge X\neg q))$.



$\text{nnf}(\neg\phi) := F(\neg p \wedge (X\neg q \vee Xq))$



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Example:

This prefix is not informative for $\phi := (G(q \vee FGp) \wedge G(r \vee FG\neg p)) \vee Gq \vee Gr$.



$\text{nnf}(\neg\phi) := (F(\neg q \wedge GF\neg p) \vee F(\neg r \wedge GFp)) \wedge F\neg q \wedge F\neg r$



Definition (Informative Prefix)

Let ϕ be an LTL formula over \mathcal{AP} and let $\sigma \in (2^{\mathcal{AP}})^+$ be a finite trace over $2^{\mathcal{AP}}$.

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Example:

This prefix is not *informative* for $\phi := (G(q \vee FGp) \wedge G(r \vee FG\neg p)) \vee Gq \vee Gr$.

$G(\dots)$ is always false under \models_{KV} : **no prefix** is informative for ϕ

$\text{nnf}(\neg\phi) := (F(\neg q \wedge GF\neg p) \vee F(\neg r \wedge GFp)) \wedge F\neg q \wedge F\neg r$



Definition (Informative Prefix)

Let ϕ be an LTL formula over \mathcal{AP} and let $\sigma \in (2^{\mathcal{AP}})^+$ be a finite trace over $2^{\mathcal{AP}}$.

σ is an *informative prefix* for ϕ
iff
 $\sigma \models_{KV} \text{nnf}(\neg\phi)$

Remark:

Given σ and ϕ , checking whether $\sigma \models_{KV} \phi$ can be done in time $\mathcal{O}(|\sigma| \cdot |\phi|)$.



Classification of Safety Properties

by Kupferman and Vardi

Let ϕ be any LTL formula such that $\mathcal{L}(\phi)$ is a safety language. The definition of informative prefix is used to classify such formulas ϕ into three types:

- ① intentionally safe
- ② accidentally safe
- ③ pathologically safe



Classification of Safety Properties

by Kupferman and Vardi

Let ϕ be any LTL formula such that $\mathcal{L}(\phi)$ is a safety language. The definition of informative prefix is used to classify such formulas ϕ into three types:

① intentionally safe

ϕ is intentionally safe iff *all* bad prefixes are informative.

For example:

- the formula $G(p)$ is intentionally safe.
- the formula $G(p \vee (\bigwedge X q \wedge \bigwedge X \neg q))$ is *not* intentionally safe, because $\langle \{p\}, \{p\}, \{p\}, \{p\}, \emptyset \rangle$ is a bad prefix but it is not informative.

② accidentally safe

③ pathologically safe



Classification of Safety Properties

by Kupferman and Vardi

Let ϕ be any LTL formula such that $\mathcal{L}(\phi)$ is a safety language. The definition of informative prefix is used to classify such formulas ϕ into three types:

- 1 intentionally safe
- 2 accidentally safe

ϕ is accidentally safe iff (i) not all the bad prefixes of ψ are informative, but (ii) every $\sigma \in (2^{AP})^\omega$ that violates ϕ has an informative bad prefix.

For example:

- $G(p \vee (Xq \wedge X\neg q))$ is accidentally safe: $\langle \{p\}, \{p\}, \{p\}, \{p\}, \emptyset \rangle$ is a bad prefix but it is not informative. However, every infinite trace violating the formula has an informative prefix of type $\{p\}^* \cdot \emptyset \cdot \emptyset$.

- 3 pathologically safe



Classification of Safety Properties

by Kupferman and Vardi

Let ϕ be any LTL formula such that $\mathcal{L}(\phi)$ is a safety language. The definition of informative prefix is used to classify such formulas ϕ into three types:

- 1 intentionally safe
- 2 accidentally safe
- 3 pathologically safe

ϕ is pathologically safe iff there is a $\sigma \in (2^{AP})^\omega$ that violates ϕ and has no informative bad prefixes.

For example:

- $(G(q \vee FGp) \wedge G(r \vee FG\neg p)) \vee Gq \vee Gr$
 - the computation \emptyset^ω violates the formula

$$\emptyset^\omega \models (F(\neg q \wedge GF\neg p) \vee F(\neg r \wedge GFp)) \wedge F(\neg q) \wedge F(\neg r)$$

- but each of its prefixes σ is *not informative* because $\sigma \not\models_{KV} (F(\neg q \wedge GF\neg p) \vee F(\neg r \wedge GFp)) \wedge F(\neg q) \wedge F(\neg r)$, but **no finite prefix** is such.



Classification of Safety Properties

by Kupferman and Vardi

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- 1 intentionally safe
- 2 accidentally safe
- 3 pathologically safe

Formulas that are accidentally safe or pathologically safe are *needlessly complicated*:

- They contain a redundancy that can be eliminated.
- If a user wrote a pathologically safe formula, then probably he/she didn't mean to write a safety formula.
- This classification helps in detecting inconsistent or redundant specifications.



Theorem

For any formula ϕ of SafetyLTL, it holds that ϕ is either intentionally or accidentally safe.

Proof.

- By the duality between SafetyLTL and coSafetyLTL, we have that $\text{nnf}(\neg\phi)$ is a formula of coSafetyLTL and is equivalent to ϕ . Let $\psi := \text{nnf}(\neg\phi)$.
- Let $\sigma = \langle \sigma_0, \sigma_1, \dots \rangle$ be an infinite trace that satisfies ψ , that is $\sigma \models \psi$.
- Since, by definition of coSafetyLTL, ψ contains only X and U as temporal operators, there exists a furthestmost time point i such that $\sigma_{[0,i]} \models \psi$ (under finite traces semantics).



Theorem

For any formula ϕ of SafetyLTL, it holds that ϕ is either intentionally or accidentally safe.

Proof.

- Since on the operators X and U the definitions of \models and \models_{KV} coincide, we have also that $\sigma_{[0,i]} \models_{KV} \psi$. Therefore, by definition, $\sigma_{[0,i]}$ is an *informative prefix*.
- It follows that every infinite trace that violates ϕ has an informative prefix, thus ϕ is either intentionally or accidentally safe. □



As we will see, this classification is exploited for having efficient **verification algorithms**.

- An automaton that recognizes only the bad prefixes that are *informative* can be built exponentially more efficiently than the automaton for *all* the bad prefixes.
- Moreover, in practice, almost all the benefits that one can obtain from an automaton for the bad prefixes can also be obtained from an automaton for the *informative* bad prefixes.
 - for example, we can perform *model checking* algorithms considering only the informative bad prefixes
 - since there may be bad prefixes that are not informative but may become informative if extended, *minimality* of counterexamples is the only thing that is sacrificed when dealing with informative bad prefixes.

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