

Department of Mathematics, Computer Science and Physics, University of Udine

# The Safety Fragment of Temporal Logics on Infinite Sequences

Lesson 5

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# THE SAFETY FRAGMENT

OF  $\omega$ -REGULAR LANGUAGES



# The Safety Fragment of $\omega$ -regular languages

In this part, we will mainly deal with language of *infinite words* and with logics interpreted over *infinite words*.



Informal definitions:

*Safety properties express the fact that "something bad never happens".*

E.g.: a deadlock or a simultaneous access to a critical section.

*Any violation of a safety property is irremediable.*

E.g.: once a deadlock occurred, we don't have any hope to do better.

*Any violation of a safety property has a finite witness.*

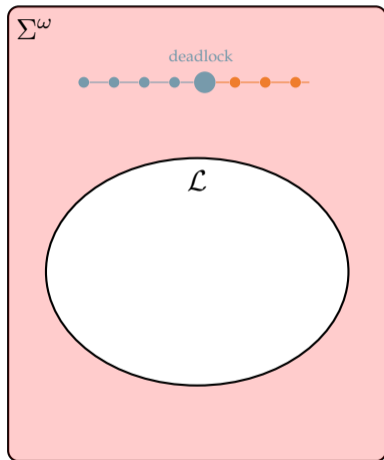
## Notation:

- For any  $i \in \mathbb{N}$ ,  $\sigma_{[0,i]}$  is the prefix of  $\sigma$  up to position  $i$ .
- for any  $\sigma \in \Sigma^*$  and for any  $\sigma' \in \Sigma^\omega$ ,  $\sigma \cdot \sigma'$  is the *concatenation* of  $\sigma'$  to the end of  $\sigma$ .

## Definition (Safety Property)

$\mathcal{L} \subseteq \Sigma^\omega$  is a *safety property* iff, for all  $\sigma \notin \mathcal{L}$ , there exists an position  $i \in \mathbb{N}$  such that  $\sigma_{[0,i]} \cdot \sigma' \notin \mathcal{L}$ , for all  $\sigma' \in \Sigma^\omega$ .

$\sigma_{[0,i]}$  is called the *bad prefix* of  $\sigma$ .



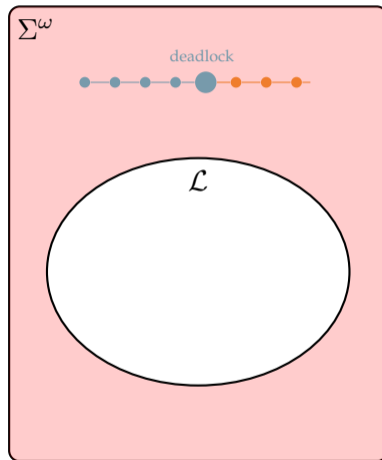
## Examples

- $b \cdot (a)^\omega$  is a safety language.
- “The set of infinite words in which each ‘a’ is followed by some ‘b’ ” is not a safety language.

- We denote with  $\text{bad}(\mathcal{L})$  the set of bad prefixes of  $\mathcal{L}$ .
- For any safety language  $\mathcal{L}$ , it holds that:

$$\overline{\mathcal{L}} = \text{bad}(\mathcal{L}) \cdot \Sigma^\omega$$

where  $\overline{\mathcal{L}}$  is the *complement* of  $\mathcal{L}$ .



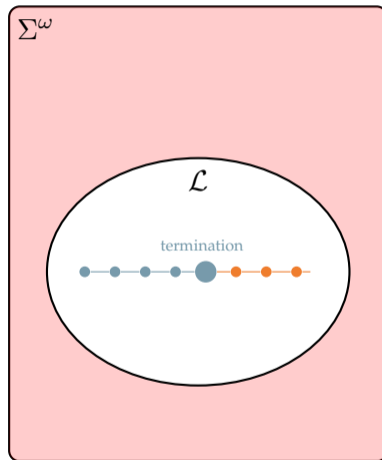
## Definition (Cosafety Property)

$\mathcal{L} \subseteq \Sigma^\omega$  is a *cosafety property* iff for all  $\sigma \in \mathcal{L}$ , there exists an position  $i \in \mathbb{N}$  such that  $\sigma_{[0,i]} \cdot \sigma' \in \mathcal{L}$ , for all  $\sigma' \in \Sigma^\omega$ .

$\sigma_{[0,i]}$  is called the *good prefix* of  $\sigma$ .

## Property:

$\mathcal{L}$  is a cosafety property iff  $\overline{\mathcal{L}}$  is a safety property.

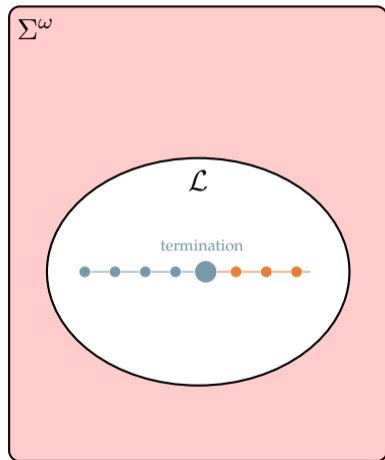


## Examples

- “The set of infinite words in which there is an ‘*a*’ that is followed by some ‘*b*’ ” is a cosafety language.
- “The set of infinite words in which each ‘*a*’ is followed by some ‘*b*’ ” is not a cosafety language.

- We denote with  $\text{good}(\mathcal{L})$  the set of good prefixes of  $\mathcal{L}$ .
- For any cosafety language  $\mathcal{L}$ , it holds that:

$$\mathcal{L} = \text{good}(\mathcal{L}) \cdot \Sigma^\omega$$

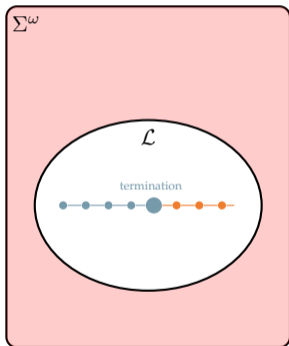




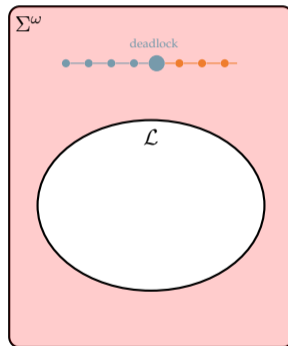


# The Safety and coSafety Fragments of $\omega$ -regular languages

We denote with **coSAFETY** the set of all  
cosafety  $\omega$ -regular languages.



We denote with **SAFETY** the set of all  
safety  $\omega$ -regular languages.





# The Safety and coSafety Fragments of $\omega$ -regular languages

We denote with **coSAFETY** the set of all cosafety  $\omega$ -regular languages.

## $\omega$ -Regular Expressions

coSAFETY is characterized by the following type of  $\omega$ -regular expressions:

$$K \cdot \Sigma^\omega$$

where  $K \in \text{REG}$ .

We denote with **SAFETY** the set of all safety  $\omega$ -regular languages.

## $\omega$ -Regular Expressions

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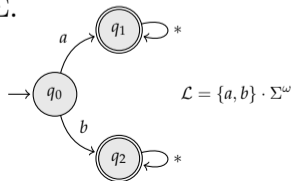
$$\overline{K \cdot \Sigma^\omega}$$

where  $K \in \text{REG}$ .

We denote with **coSAFETY** the set of all cosafety  $\omega$ -regular languages.

## Automata

coSAFETY is characterized by the following type of automata: *terminal deterministic Büchi automata* (**tDBA**, for short), that is DBAs in which each final state has self-loop labeled with each letter in  $\Sigma$ .

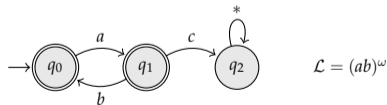


We denote with **SAFETY** the set of all safety  $\omega$ -regular languages.

## Automata

SAFETY is characterized by the following type of automata: *deterministic safety automata* (**DSA**, for short).

**Accepting condition:** visit *only* final states.





# The Safety and coSafety Fragments of $\omega$ -regular languages

We denote with **coSAFETY** the set of all cosafety  $\omega$ -regular languages.

S1S

To the best of our knowledge, no characterizations of coSAFETY in terms of S1S have been studied.

We denote with **SAFETY** the set of all safety  $\omega$ -regular languages.

S1S

To the best of our knowledge, no characterizations of SAFETY in terms of S1S have been studied.



# The Safety and coSafety Fragments of $\omega$ -regular languages

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## Temporal Logics

To the best of our knowledge, no characterizations of coSAFETY in terms of temporal logics have been studied.

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## Temporal Logics

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$\omega$ -REG

S1S

NBA

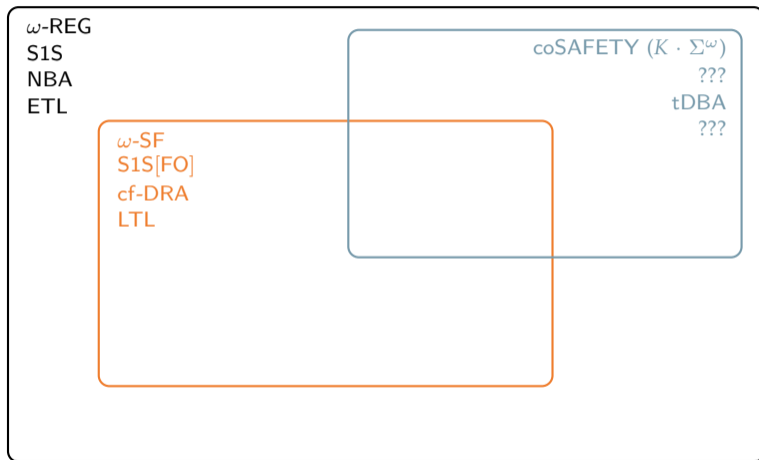
ETL

$\omega$ -SF

S1S[FO]

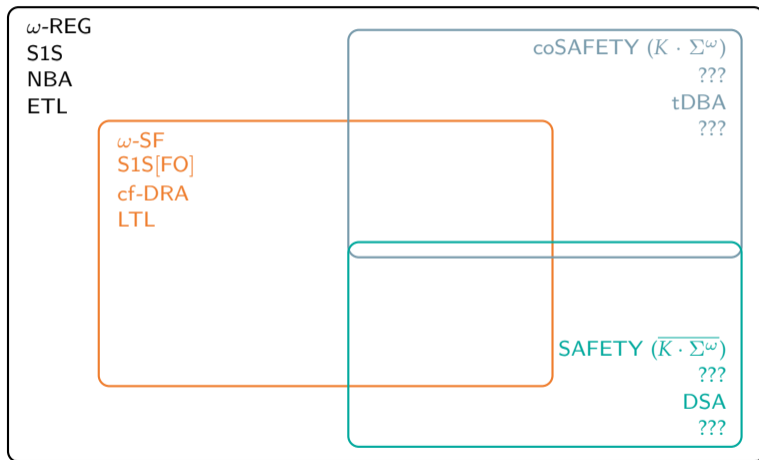
cf-DRA

LTL





# Set-theoretic view of (co)safety $\omega$ -languages







Informal definitions:

*In a liveness property, no partial execution is irremediable.*

E.g.: “each request is eventually followed by a grant” is a liveness property.

## Definition (Liveness Property)

$\mathcal{L} \subseteq \Sigma^\omega$  is a *liveness property* iff, for all  $\sigma \in \Sigma^*$ , there exists a  $\sigma' \in \Sigma^\omega$  such that  $\sigma \cdot \sigma' \in \mathcal{L}$ .

Examples:

- “The set of infinite words in which each ‘*a*’ is followed by some ‘*b*’ ” is a liveness language.
- $b \cdot (a)^\omega$  is not a liveness language.



## Theorem (Alpern & Schneider (1987))

Each  $\omega$ -regular property is the intersection of a *safety* property and a *liveness* property.

## Reference:

**Bowen Alpern and Fred B. Schneider (1987). "Recognizing Safety and Liveness".** In: *Distributed Comput.* 2.3, pp. 117–126. DOI: 10.1007/BF01782772.  
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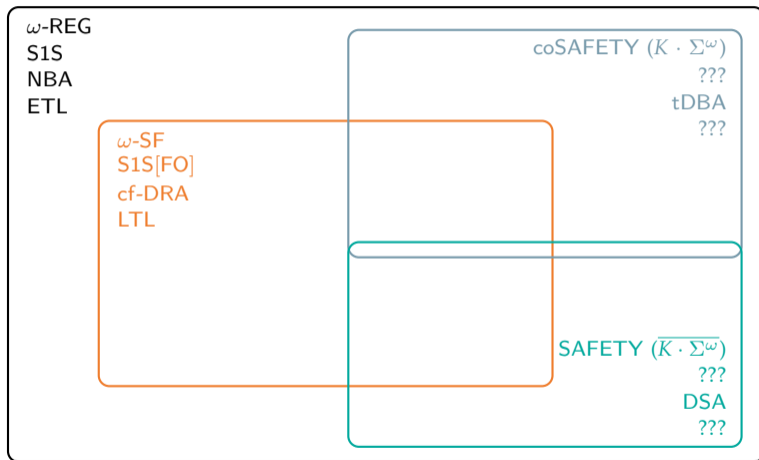
This decomposition can be performed effectively:

Given a NBA  $\mathcal{A}$ , there is an algorithm to build two NBA  $\mathcal{A}_s$  and  $\mathcal{A}_l$  such that:

- $\mathcal{L}(\mathcal{A}_s)$  is safety;
- $\mathcal{L}(\mathcal{A}_l)$  is liveness;
- $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{A}_s) \cap \mathcal{L}(\mathcal{A}_l)$ .

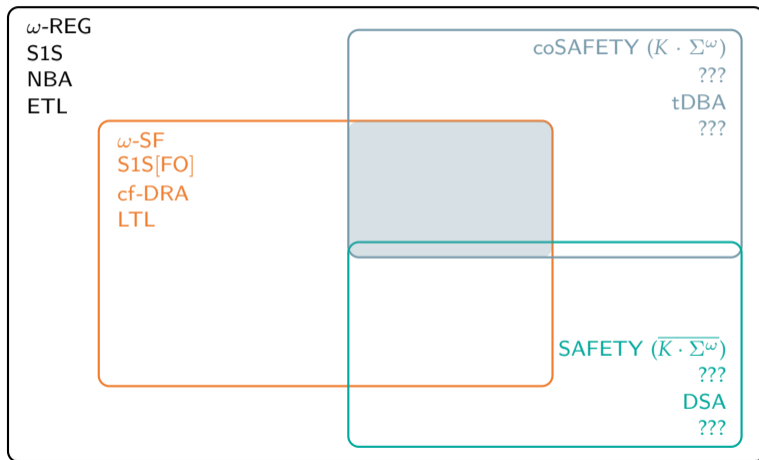


# Set-theoretic view of (co)safety $\omega$ -languages



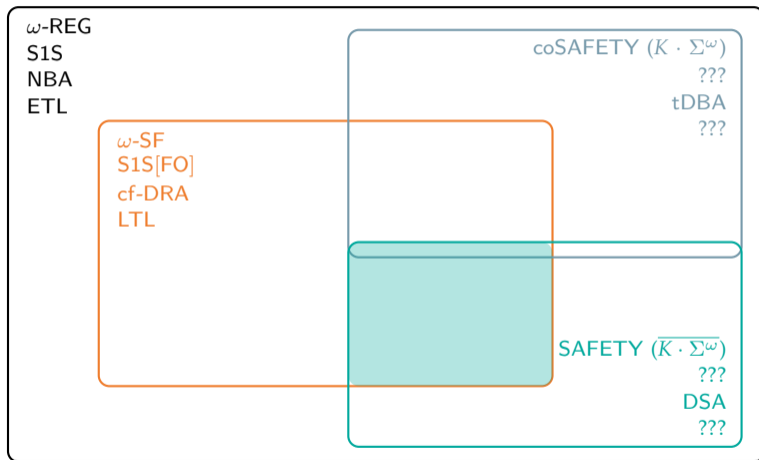


# Set-theoretic view of (co)safety $\omega$ -languages





# Set-theoretic view of (co)safety $\omega$ -languages



# THE SAFETY FRAGMENT OF LTL

AND ITS THEORETICAL FEATURES



## Definition

The *cosafety fragment of LTL* is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{coSAFETY}$$

We will see four characterizations in terms of:

- regular expressions
- automata
- first-order logic
- temporal logic





## Definition

The *cosafety fragment* of LTL is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{coSAFETY}$$

## $\omega$ -regular expressions

$$\text{SF} \cdot \Sigma^\omega = \{K \cdot \Sigma^\omega \mid K \in \text{SF}\}$$

- the "SF" part corresponds to LTL
- the " $\cdot \Sigma^\omega$ " part corresponds to being a cosafety fragment

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Ina Schiering and Wolfgang Thomas (1996). "Counter-free automata, first-order logic, and star-free expressions extended by prefix oracles". In: *Developments in Language Theory, II (Magdeburg, 1995)*, World Sci. Publishing, River Edge, NJ, pp. 166–175



## Definition

The *cosafety fragment* of LTL is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{coSAFETY}$$

## First-order logic

We define **coSafety-FO** as the fragment of  $\text{S1S}[\text{FO}]$  in which quantifiers are bounded as follows:

- $\exists y . (x < y \wedge \dots)$
- $\forall y . (x < y < z \rightarrow \dots)$

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Alessandro Cimatti et al. (2022). "A first-order logic characterisation of safety and co-safety languages". In: *Foundations of Software Science and Computation Structures - 25th International Conference, FOSSACS 2022, Held as Part of the European Joint Conferences on Theory and Practice of Software, ETAPS 2022, Munich, Germany, April 2-7, 2022, Proceedings*. Ed. by Patricia Bouyer and Lutz Schröder. Vol. 13242. Lecture Notes in Computer Science. Springer, pp. 244–263. DOI: 10.1007/978-3-030-99253-8\\_13. URL: [https://doi.org/10.1007/978-3-030-99253-8%5C\\_13](https://doi.org/10.1007/978-3-030-99253-8%5C_13)



## Definition

The *cosafety fragment* of LTL is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{coSAFETY}$$

First-order logic

## Example

$$\phi(x) := \exists y . (x < y \wedge P(y) \wedge \forall z . (x < z < y \rightarrow Q(z)))$$



## Definition

The *cosafety fragment of LTL* is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{coSAFETY}$$

### First-order logic

- the "first-order" part corresponds to LTL
- the "bounded quantifiers" part corresponds to being a cosafety fragment



## Definition

The *cosafety fragment* of LTL is the set of languages in this set:

$$\llbracket \text{LTL} \rrbracket \cap \text{coSAFETY}$$

## Automata

**cf-tDBA** = counter-free terminal DBA

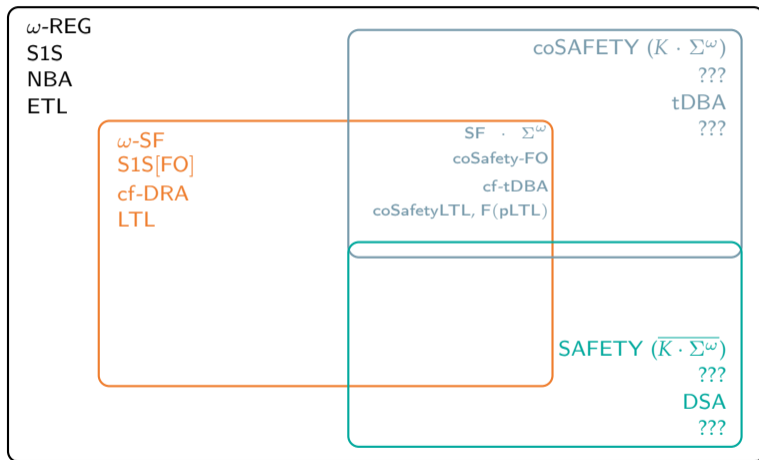
- the "counter-free" part corresponds to LTL
- the "terminal" part corresponds to being a cosafety fragment

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# Set-theoretic view of the (co)safety fragment of LTL





# The cosafety fragment of LTL

## Temporal Logics

We say that a temporal logic  $\mathbb{L}$  is *cosafety* iff, for any  $\phi \in \mathbb{L}$ ,  $\mathcal{L}(\phi)$  is *cosafety*.

coSafetyLTL

### Definition

$\phi := p \mid \neg p \mid \phi \vee \phi \mid \phi \wedge \phi \mid X\phi \mid F\phi \mid \phi U \phi$

### Example:

$p U q$

F(pLTL)

### Definition

$\phi := F(\alpha)$ , where  $\alpha \in \text{pLTL}$ , that is  $\alpha$  is a pure-past LTL formula.

### Example:

$F(q \wedge \tilde{Y}Hp)$

F(pLTL) is the **canonical form** of coSafetyLTL.



## Theorem

- $\text{coSafetyLTL}$  and  $F(\text{pLTL})$  are expressively equivalent.
- $\text{coSafetyLTL}$  and  $F(\text{pLTL})$  are expressively complete w.r.t.  $[[\text{LTL}]] \cap \text{coSAFETY}$ .

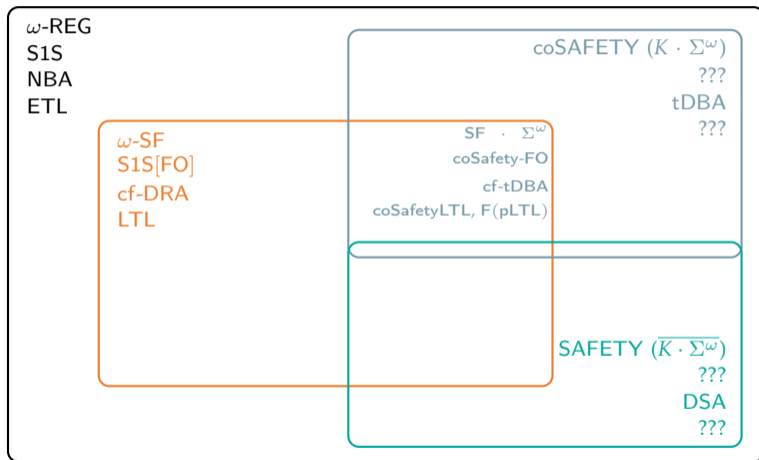
## Reference:

**Edward Y. Chang, Zohar Manna, and Amir Pnueli (1992).** “Characterization of Temporal Property Classes”. In: *Proceedings of the 19th International Colloquium on Automata, Languages and Programming*. Ed. by Werner Kuich. Vol. 623. Lecture Notes in Computer Science. Springer, pp. 474–486. DOI: 10.1007/3-540-55719-9\\_97





# Set-theoretic view of (co)safety $\omega$ -languages



# REFERENCES



**Bowen Alpern and Fred B. Schneider (1987).** “Recognizing Safety and Liveness”. In: *Distributed Comput.* 2.3, pp. 117–126. DOI: 10.1007/BF01782772. URL: <https://doi.org/10.1007/BF01782772>.

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