

The q -Exponential Operator

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Abstract

We define a q -exponential operator $R(bD_q)$ which turn out to be suitable for dealing with the Cauchy polynomials $P_n(x, y)$ and the homogeneous Rogers-Szegö polynomials $h_n(x, y|q)$. By using this operator, we derive Mehler's formula and Rogers formula for the polynomials $P_n(x, y)$ and $h_n(x, y|q)$.

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1. Introduction

In this paper we will follow the standard notations on q -series in [9] and we always assume that $|q| < 1$. The q -shifted factorial is defined by:

$$(a; q)_k = \begin{cases} 1, & \text{if } k = 0, \\ (1 - a)(1 - aq) \cdots (1 - aq^{k-1}), & \text{if } k = 1, 2, 3, \dots \end{cases}$$

We also define

$$(a; q)_\infty = \prod_{k=0}^{\infty} (1 - aq^k).$$

The generalized basic hypergeometric series is defined by

$$\begin{aligned}
 {}_r\phi_s(a_1, a_2, \dots, a_r; b_1, b_2, \dots, b_s; q, x) &= {}_r\phi_s \left(\begin{matrix} a_1, a_2, \dots, a_r \\ b_1, b_2, \dots, b_s \end{matrix}; q, x \right) \\
 &= \sum_{n=0}^{\infty} \frac{(a_1; q)_n (a_2; q)_n \cdots (a_r; q)_n}{(q; q)_n (b_1; q)_n (b_2; q)_n \cdots (b_s; q)_n} \left[(-1)^n q^{\binom{n}{2}} \right]^{1+s-r} x^n, \tag{1.1}
 \end{aligned}$$

where $q \neq 0$ when $r > s + 1$. Note that

$${}_{r+1}\phi_r \left(\begin{matrix} a_1, a_2, \dots, a_{r+1} \\ b_1, b_2, \dots, b_r \end{matrix}; q, x \right) = \sum_{n=0}^{\infty} \frac{(a_1; q)_n (a_2; q)_n \cdots (a_{r+1}; q)_n}{(q; q)_n (b_1; q)_n (b_2; q)_n \cdots (b_r; q)_n} x^n.$$

The following easily verified identities will be frequently used in this paper:

$$\begin{aligned}
 (x; q)_n &= \frac{(x; q)_{\infty}}{(q^n x; q)_{\infty}}, \\
 (a; q)_{n+k} &= (a; q)_n (aq^n; q)_k.
 \end{aligned}$$

We shall adopt the following notation of multiple q -shifted factorials:

$$\begin{aligned}
 (a_1, a_2, \dots, a_m; q)_n &= (a_1; q)_n (a_2; q)_n \cdots (a_m; q)_n, \\
 (a_1, a_2, \dots, a_m; q)_{\infty} &= (a_1; q)_{\infty} (a_2; q)_{\infty} \cdots (a_m; q)_{\infty}.
 \end{aligned}$$

The q -binomial coefficients is defined by:

$$\left[\begin{matrix} n \\ k \end{matrix} \right] = \begin{cases} \frac{(q; q)_n}{(q; q)_k (q; q)_{n-k}}, & \text{if } 0 \leq k \leq n, \\ 0, & \text{otherwise.} \end{cases}$$

One of the most classical identities in q -series is Cauchy identity

$$\sum_{n=0}^{\infty} \frac{(a; q)_n}{(q; q)_n} x^n = \frac{(ax; q)_{\infty}}{(x; q)_{\infty}}, \quad |x| < 1.$$

The following is the homogeneous form of the q -shifted factorial:

$$P_n(x, y) = (y/x; q)_n x^n = (x - y)(x - qy)(x - q^2y) \cdots (x - q^{n-1}y). \tag{1.2}$$

Because the polynomials $P_n(x, y)$ occur so often in q -series, Chen et al. [7] proposed to call them the Cauchy polynomials because they are the coefficients in the expansion of the homogeneous version of the Cauchy identity (the generating function of $P_n(x, y)$):

$$\sum_{n=0}^{\infty} P_n(x, y) \frac{t^n}{(q; q)_n} = \frac{(yt; q)_{\infty}}{(xt; q)_{\infty}}, \quad |xt| < 1. \tag{1.3}$$

Setting $y = 0$, the Cauchy identity becomes Euler's identity:

$$\sum_{n=0}^{\infty} \frac{(xt)^n}{(q; q)_{\infty}} = \frac{1}{(xt; q)_{\infty}}, \quad |xt| < 1. \tag{1.4}$$

Setting $x = 0$, the Cauchy identity becomes, another, Euler's identity:

$$\sum_{n=0}^{\infty} \frac{(-1)^n q^{\binom{n}{2}} (yt)^n}{(q; q)_n} = (yt; q)_{\infty}. \tag{1.5}$$

In 1970, Goldman and Rota [10] have shown the q -binomial identity

$$P_n(x, y) = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} P_k(x, z) P_{n-k}(z, y). \tag{1.6}$$

Setting $z = 0$ in (1.6), one obtains the following identity:

$$P_n(x, y) = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} (-1)^k q^{\binom{k}{2}} y^k x^{n-k}. \tag{1.7}$$

Note that, the Cauchy polynomials $P_n(x, y)$ naturally arise in the q -umbral calculus as studied by Andrews [1, 2], Goldman and Rota [10], Goulden and Jackson [11], Ihrig and Ismail [12], Johnson [14] and Roman [17].

The usual q -differential operator, or the q -derivative operator is defined by:

$$D_q \{f(x)\} = \frac{f(x) - f(qx)}{x}. \tag{1.8}$$

The Leibniz rule for D_q is the following identity:

$$D_q^n \{f(x)g(x)\} = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} q^{k(k-n)} D_q^k \{f(x)\} D_q^{n-k} \{g(q^k x)\}. \tag{1.9}$$

$D_q^0 f(x)$ is understood as the identity.

In [5], Chen and Liu developed a method for deriving hypergeometric identities by parameter augmentation, which means that a hypergeometric identity with multiple parameters may be derived from its special case obtained by reducing some parameters to zero.

In [6], Chen and Liu realized the parameter augmentation by the q -exponential operator $T(bD_q)$, which leads to considerable simplifications of some well known q -summation and transformation formulas. The q -exponential operator is defined by

$$T(bD_q) = \sum_{n=0}^{\infty} \frac{(bD_q)^n}{(q; q)_n}.$$

The following operator identities were obtained:

Theorem 1.1. (Chen and Liu [6]). *Let D_q be defined as above. Then*

$$D_q^k \{x^n\} = \frac{(q; q)_n}{(q; q)_{n-k}} x^{n-k}. \quad (1.10)$$

$$D_q^k \left\{ \frac{1}{(xt; q)_\infty} \right\} = \frac{t^k}{(xt; q)_\infty}. \quad (1.11)$$

The classical Rogers-Szegö polynomials play an important role in the theory of orthogonal polynomials, particularly in the study of the Askey-Wilson integral [4]. Some important results on the Rogers-Szegö polynomials naturally fall into the framework of parameter augmentation such as Mehler's formula, Rogers formula and the linearization formula and its inverse [3, 6, 13, 15, 16, 18, 20]. The classical Rogers-Szegö polynomials are defined by:

$$h_n(x|q) = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} x^k,$$

which has the generating function:

$$\sum_{n=0}^{\infty} h_n(x|q) \frac{t^n}{(q; q)_n} = \frac{1}{(xt, t; q)_\infty}, \quad \max\{|xt|, |t|\} < 1. \quad (1.12)$$

In the same paper, Chen and Liu represented the polynomials $h_n(x|q)$ by the augmentation operator as follows:

$$T(D_q) \{x^n\} = h_n(x|q).$$

Using the above operator definition of the Rogers-Szegö polynomials and the augmentation argument, they easily derived Mehler's formula and the Rogers formula for $h_n(x|q)$.

Theorem 1.2. (Chen and Liu [6]).

The Mehler's formula for $h_n(x|q)$ is

$$\sum_{n=0}^{\infty} h_n(x|q) h_n(y|q) \frac{t^n}{(q; q)_n} = \frac{(xyt^2; q)_\infty}{(xt, t, yt, xyt; q)_\infty}, \quad (1.13)$$

where $\max\{|xt|, |t|, |yt|, |xyt|\} < 1$.

The Rogers formula for $h_n(x|q)$ is

$$\sum_{n=0}^{\infty} \sum_{m=0}^{\infty} h_{n+m}(x|q) \frac{t^n}{(q; q)_n} \frac{s^m}{(q; q)_m} = \frac{(xst; q)_\infty}{(xs, s, xt, t; q)_\infty}, \quad (1.14)$$

where $\max\{|xs|, |s|, |xt|, |t|\} < 1$.

In 2006, Zhang and Wang [19] used the q -exponential operator $T(bD_q)$ to some terminating summation formulas of basic hypergeometric series and q -integrals to obtain some q -series identities and q -integrals involving ${}_3\phi_2$. The following operator identity were obtained:

Theorem 1.3. (Zhang and Wang [19]). *Let D_q be defined as above. Then*

$$D_q^k \left\{ \frac{(xv; q)_\infty}{(xt; q)_\infty} \right\} = t^k (v/t; q)_k \frac{(xvq^k; q)_\infty}{(xt; q)_\infty}. \tag{1.15}$$

In 2003, Chen et al. [7], introduced the homogenous q -difference operator D_{xy} , which is suitable for the study of the Cauchy polynomials, acting on function in two variables x and y :

$$D_{xy}f(x, y) = \frac{f(x, q^{-1}y) - f(qx, y)}{x - q^{-1}y}.$$

Based on the homogeneous q -difference operator, they built up the homogeneous q -shift operator as the q -exponential of the homogeneous q -difference operator:

$$E(D_{xy}) = \sum_{n=0}^{\infty} \frac{D_{xy}^n}{(q; q)_n}.$$

They also introduced the homogeneous Rogers-Szegö polynomials and derive their generating function by using the homogeneous q -shift operator $E(D_{xy})$. The homogeneous Rogers-Szegö polynomials are defined by:

$$h_n(x, y|q) = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} P_k(x, y),$$

which has the generating function:

$$\sum_{n=0}^{\infty} h_n(x, y|q) \frac{t^n}{(q; q)_n} = \frac{(yt; q)_\infty}{(xt, t; q)_\infty}, \quad \max\{|xt|, |t|\} < 1.$$

In 2007, Chen et al. [8] present an operator approach to derive Mehler’s formula and Rogers formula for the homogeneous Rogers-Szegö polynomials $h_n(x, y|q)$. The proofs of these results are based on parameter augmentation with respect to the q -exponential operator $T(D_q)$ and the homogeneous q -shift operator $E(D_{xy})$.

In this paper, we introduce a new q -exponential operator $R(bD_q)$. We present an operator proof for Mehler’s formula and Rogers formula for both the Cauchy polynomials $P_n(x, y)$ and the homogeneous Rogers-Szegö polynomials $h_n(x, y|q)$.

2. The q -exponential operator $R(bD_q)$

Let D_q be defined as in (1.8). We define a q -exponential operator $R(bD_q)$ as follows:

$$R(bD_q) = \sum_{k=0}^{\infty} \frac{(-1)^k q^{\binom{k}{2}} b^k}{(q; q)_k} D_q^k. \quad (2.1)$$

The operator proof needs operator identities, so we derive some identities for the q -exponential operator $R(bD_q)$. We use R_a for the operator R acting on the variable a . The following theorem for the exponential operator $R_a(bD_q)$ is easy to verify.

Theorem 2.1. *We have*

$$R_a(bD_q) \left\{ \frac{1}{(at; q)_{\infty}} \right\} = \frac{(bt; q)_{\infty}}{(at; q)_{\infty}}. \quad (2.2)$$

$$R_a(bD_q) \left\{ \frac{(av; q)_{\infty}}{(at; q)_{\infty}} \right\} = \frac{(av; q)_{\infty}}{(at; q)_{\infty}} {}_1\phi_1 \left(\begin{matrix} v/t \\ av \end{matrix}; q, bt \right). \quad (2.3)$$

Theorem 2.2. *We have*

$$R_a(bD_q) \left\{ \frac{(av; q)_{\infty}}{(at, as; q)_{\infty}} \right\} = \frac{(bs; q)_{\infty}}{(as; q)_{\infty}} {}_2\phi_1 \left(\begin{matrix} v/t, b/a \\ bs \end{matrix}; q, at \right). \quad (2.4)$$

Proof. By using (1.9), we get

$$\begin{aligned} & R_a(bD_q) \left\{ \frac{(av; q)_{\infty}}{(at, as; q)_{\infty}} \right\} \\ &= \sum_{n=0}^{\infty} \frac{(-1)^n q^{\binom{n}{2}} b^n}{(q; q)_n} \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} q^{k(k-n)} D_q^k \left\{ \frac{(av; q)_{\infty}}{(at; q)_{\infty}} \right\} D_q^{n-k} \left\{ \frac{1}{(asq^k; q)_{\infty}} \right\} \\ &= \sum_{k=0}^{\infty} \frac{(-1)^k q^{\binom{k}{2}} b^k}{(q; q)_k} D_q^k \left\{ \frac{(av; q)_{\infty}}{(at; q)_{\infty}} \right\} \sum_{n=0}^{\infty} \frac{(-1)^n q^{\binom{n}{2}} b^n}{(q; q)_n} D_q^n \left\{ \frac{1}{(asq^k; q)_{\infty}} \right\} \\ &= \sum_{k=0}^{\infty} \frac{(-1)^k q^{\binom{k}{2}} b^k}{(q; q)_k} t^k (v/t; q)_k \frac{(avq^k; q)_{\infty}}{(at; q)_{\infty}} R_a(bD_q) \left\{ \frac{1}{(asq^k; q)_{\infty}} \right\} \quad (\text{by using (1.15)}) \\ &= \sum_{k=0}^{\infty} \frac{(-1)^k q^{\binom{k}{2}} b^k}{(q; q)_k} t^k (v/t; q)_k \frac{(avq^k; q)_{\infty}}{(at; q)_{\infty}} \frac{(bsq^k; q)_{\infty}}{(asq^k; q)_{\infty}} \quad (\text{by using (2.2)}) \\ &= \frac{(av, bs; q)_{\infty}}{(at, as; q)_{\infty}} \sum_{k=0}^{\infty} \frac{(v/t, as; q)_k}{(q, av, bs; q)_k} (-1)^k q^{\binom{k}{2}} (bt)^k \\ &= \frac{(av, bs; q)_{\infty}}{(at, as; q)_{\infty}} {}_2\phi_2 \left(\begin{matrix} v/t, as \\ av, bs \end{matrix}; q, bt \right). \end{aligned}$$

By Jackson's transformation [9, Appendix III, equation (III.4)], we get the required result. ■

Theorem 2.3. *We have*

$$R_a(bD_q) \left\{ \frac{1}{(as, at; q)_\infty} \right\} = \frac{(bt; q)_\infty}{(as, at; q)_\infty} {}_1\phi_1 \left(\begin{matrix} at \\ bt \end{matrix}; q, bs \right). \quad (2.5)$$

Proof. From (1.9), we get

$$\begin{aligned} & R_a(bD_q) \left\{ \frac{1}{(as, at; q)_\infty} \right\} \\ &= \sum_{n=0}^{\infty} \frac{(-1)^n q^{\binom{n}{2}} b^n}{(q; q)_n} \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} q^{k(k-n)} D_q^k \left\{ \frac{1}{(as; q)_\infty} \right\} D_q^{n-k} \left\{ \frac{1}{(atq^k; q)_\infty} \right\} \\ &= \sum_{n=0}^{\infty} \frac{(-1)^n q^{\binom{n}{2}} b^n}{(q; q)_n} \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} q^{k(k-n)} \frac{s^k}{(as; q)_\infty} \frac{(tq^k)^{n-k}}{(atq^k; q)_\infty} \quad (\text{by using (1.11)}) \\ &= \frac{1}{(as, at; q)_\infty} \sum_{k=0}^{\infty} \frac{(-1)^k q^{\binom{k}{2}} (bs)^k}{(q; q)_k} (at; q)_k \sum_{n=0}^{\infty} \frac{(-1)^n q^{\binom{n}{2}} (btq^k)^n}{(q; q)_n} \\ &= \frac{1}{(as, at; q)_\infty} \sum_{k=0}^{\infty} \frac{(-1)^k q^{\binom{k}{2}} (bs)^k}{(q; q)_k} (at; q)_k (btq^k; q)_\infty \quad (\text{by using (1.5)}) \\ &= \frac{(bt; q)_\infty}{(as, at; q)_\infty} \sum_{k=0}^{\infty} \frac{(at; q)_k}{(q, bt; q)_k} (-1)^k q^{\binom{k}{2}} (bs)^k \\ &= \frac{(bt; q)_\infty}{(as, at; q)_\infty} {}_1\phi_1 \left(\begin{matrix} at \\ bt \end{matrix}; q, bs \right). \end{aligned}$$

Theorem 2.4. *We have*

$$R_x(yD_q) \left\{ \frac{x^n}{(xt; q)_\infty} \right\} = \frac{(yt; q)_\infty P_n(x, y)}{(xt; q)_\infty (yt; q)_n}. \quad (2.6)$$

Proof. By using (2.1) and (1.9), we get

$$\begin{aligned} & R_x(yD_q) \left\{ \frac{x^n}{(xt; q)_\infty} \right\} \\ &= \sum_{k=0}^{\infty} \frac{(-1)^k q^{\binom{k}{2}} y^k}{(q; q)_k} \sum_{j=0}^k \begin{bmatrix} k \\ j \end{bmatrix} q^{j(j-k)} D_q^j \left\{ \frac{1}{(xt; q)_\infty} \right\} D_q^{k-j} \{ (xq^j)^n \} \\ &= \frac{1}{(xt; q)_\infty} \sum_{j=0}^{\infty} \frac{(-1)^j q^{\binom{j}{2}} (ytq^n)^j}{(q; q)_j} \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} (-1)^k q^{\binom{k}{2}} y^k x^{n-k} \quad (\text{by using (1.10)}) \\ &= \frac{(yt; q)_\infty P_n(x, y)}{(xt; q)_\infty (yt; q)_n}. \quad (\text{by using (1.5) and (1.7)}) \end{aligned}$$

■

3. Mehler's formula and Rogers formula for $P_n(x, y)$

By using (1.7), the Cauchy polynomials $P_n(x, y)$ can easily be represented by the augmentation operator as follows:

$$R_x(yD_q)\{x^n\} = P_n(x, y). \quad (3.1)$$

Using the operator definition (3.1) of the Cauchy polynomials $P_n(x, y)$, it is easy to give a simple derivation for Mehler's formula and Rogers formula for $P_n(x, y)$.

Theorem 3.1. (Mehler's formula for $P_n(x, y)$). *We have*

$$\sum_{n=0}^{\infty} P_n(x, y)P_n(z, w) \frac{t^n}{(q; q)_n} = \frac{(xwt; q)_{\infty}}{(xzt; q)_{\infty}} {}_1\phi_1 \left(\begin{matrix} w/z \\ xwt \end{matrix}; q, yzt \right), \quad |zxt| < 1.$$

Proof. From (3.1), we get

$$\begin{aligned} \sum_{n=0}^{\infty} P_n(x, y)P_n(z, w) \frac{t^n}{(q; q)_n} &= R_x(yD_q) \left\{ \sum_{k=0}^{\infty} P_n(z, w) \frac{(xt)^k}{(q; q)_k} \right\} \\ &= R_x(yD_q) \left\{ \frac{(xwt; q)_{\infty}}{(xzt; q)_{\infty}} \right\} \quad (\text{by using (1.3)}) \\ &= \frac{(xwt; q)_{\infty}}{(xzt; q)_{\infty}} {}_1\phi_1 \left(\begin{matrix} w/z \\ xwt \end{matrix}; q, yzt \right). \quad (\text{by using (2.3)}) \end{aligned}$$

■

Theorem 3.2. (Rogers formula for $P_n(x, y)$). *We have*

$$\sum_{n=0}^{\infty} \sum_{m=0}^{\infty} P_{n+m}(x, y) \frac{t^n}{(q; q)_n} \frac{s^m}{(q; q)_m} = \frac{(yt; q)_{\infty}}{(xs, xt; q)_{\infty}} {}_1\phi_1 \left(\begin{matrix} xt \\ yt \end{matrix}; q, ys \right),$$

where $\max\{|xt|, |xs|\} < 1$.

Proof. From (3.1), we get

$$\begin{aligned} & \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} P_{n+m}(x, y) \frac{t^n}{(q; q)_n} \frac{s^m}{(q; q)_m} \\ &= R_x(yD_q) \left\{ \sum_{n=0}^{\infty} \frac{(xt)^n}{(q; q)_n} \sum_{m=0}^{\infty} \frac{(xs)^m}{(q; q)_m} \right\} \\ &= R_x(yD_q) \left\{ \frac{1}{(xs, xt; q)_{\infty}} \right\} \tag{by using (1.4)} \\ &= \frac{(yt; q)_{\infty}}{(xs, xt; q)_{\infty}} {}_1\phi_1 \left(\begin{matrix} xt \\ yt \end{matrix}; q, ys \right). \tag{by using (2.5)} \end{aligned}$$

■

4. Mehler’s formula and Rogers formula for $h_n(x, y|q)$

The homogeneous Rogers-Szegö polynomials $h_n(x, y|q)$ can easily be represented by the augmentation operator as follows:

$$R_x(yD_q) \{h_n(x|q)\} = h_n(x, y|q). \tag{4.1}$$

Using the operator definition (4.1) of the homogeneous Rogers-Szegö polynomials $h_n(x, y|q)$, it is easy to give a simple derivation of the Mehler’s formula and Rogers formula for $h_n(x, y|q)$.

Theorem 4.1. (Mehler’s formula for $h_n(x, y|q)$). *We have*

$$\sum_{n=0}^{\infty} h_n(x, y|q) h_n(u, v|q) \frac{t^n}{(q; q)_n} = \frac{(yt, xvt; q)_{\infty}}{(xt, t, xut; q)_{\infty}} {}_3\phi_2 \left(\begin{matrix} y, xt, v/u \\ yt, xvt \end{matrix}; q, ut \right),$$

where $\max \{|xt|, |t|, |ut|, |xut|\} < 1$.

Proof. From (4.1), we get

$$\begin{aligned} & \sum_{n=0}^{\infty} h_n(x, y|q) h_n(u, v|q) \frac{t^n}{(q; q)_n} \\ &= R_x(yD_q) R_u(vD_q) \left\{ \sum_{n=0}^{\infty} h_n(x|q) h_n(u|q) \frac{t^n}{(q; q)_n} \right\} \\ &= R_x(yD_q) \left\{ \frac{1}{(xt, t; q)_{\infty}} R_u(vD_q) \left\{ \frac{(uxt^2; q)_{\infty}}{(ut, uxt; q)_{\infty}} \right\} \right\} \tag{by using (1.13)} \\ &= R_x(yD_q) \left\{ \frac{(vxt; q)_{\infty}}{(xt, t, uxt; q)_{\infty}} {}_2\phi_1 \left(\begin{matrix} xt, v/u \\ vxt \end{matrix}; q, ut \right) \right\}. \tag{by using (2.4)} \end{aligned}$$

By Heine’s transformation ${}_2\phi_1$ series [9, Appendix III, equation (III.2)], we get

$${}_2\phi_1 \left(\begin{matrix} xt, v/u \\ vxt \end{matrix}; q, ut \right) = \frac{(xut, vt; q)_\infty}{(vxt, ut; q)_\infty} {}_2\phi_1 \left(\begin{matrix} t, v/u \\ vt \end{matrix}; q, xut \right).$$

Hence

$$\begin{aligned} & \sum_{n=0}^{\infty} h_n(x, y|q)h_n(u, v|q) \frac{t^n}{(q; q)_n} \\ &= \frac{(vt; q)_\infty}{(t, ut; q)_\infty} \sum_{n=0}^{\infty} \frac{(t, v/u; q)_n (ut)^n}{(q, vt; q)_n} R_x(yD_q) \left\{ \frac{x^n}{(xt; q)_\infty} \right\} \\ &= \frac{(vt, yt; q)_\infty}{(xt, t, ut; q)_\infty} \sum_{n=0}^{\infty} \frac{(t, v/u; q)_n (ut)^n}{(q, vt; q)_n} \frac{P_n(x, y)}{(yt; q)_n} && \text{(by using (2.6))} \\ &= \frac{(vt, yt; q)_\infty}{(xt, t, ut; q)_\infty} {}_3\phi_2 \left(\begin{matrix} t, v/u, y/x \\ vt, yt \end{matrix}; q, xut \right). && \text{(by using (1.1) and (1.2))} \end{aligned}$$

By transformation ${}_3\phi_2$ series [9, Appendix III, equation (III.9)], we get the required result. ■

Theorem 4.2. (Rogers formula for $h_n(x, y|q)$). *We have*

$$\sum_{n=0}^{\infty} \sum_{m=0}^{\infty} h_{n+m}(x, y|q) \frac{t^n}{(q; q)_n} \frac{s^m}{(q; q)_m} = \frac{(ys; q)_\infty}{(xs, s, xt; q)_\infty} {}_2\phi_1 \left(\begin{matrix} y, xs \\ ys \end{matrix}; q, t \right),$$

where $\max \{|xs|, |s|, |xt|, |t|\} < 1$.

Proof. From (4.1), we get

$$\begin{aligned} & \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} h_{n+m}(x, y|q) \frac{t^n}{(q; q)_n} \frac{s^m}{(q; q)_m} \\ &= R_x(yD_q) \left\{ \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} h_{n+m}(x|q) \frac{t^n}{(q; q)_n} \frac{s^m}{(q; q)_m} \right\} \\ &= \frac{1}{(s, t; q)_\infty} R_x(yD_q) \left\{ \frac{(xst; q)_\infty}{(xs, xt; q)_\infty} \right\} && \text{(by using (1.14))} \\ &= \frac{1}{(s, t; q)_\infty} \frac{(ys; q)_\infty}{(xs; q)_\infty} {}_2\phi_1 \left(\begin{matrix} s, y/x \\ ys \end{matrix}; q, xt \right). && \text{(by using (2.4))} \end{aligned}$$

By Heine’s transformation ${}_2\phi_1$ series [9, Appendix III, equation (III.3)], we get desired result. ■

Our derivation for Mehler's formula and Rogers formula for $h_n(x, y|q)$ seems shorter and simpler than the one given in [8], because we only use the q -exponential operator $R(bD_q)$, while their proofs are based on parameter augmentation with respect to the q -exponential operator $T(D_q)$ and the homogeneous q -shift operator $E(D_{xy})$.

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