

Reachability via saturation

Gabriele Puppis

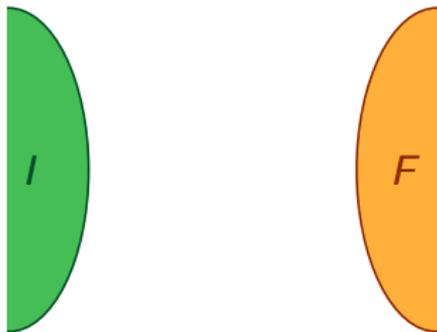
LaBRI / CNRS



Reachability is semi-decidable

A path connecting two sets, if exists, can be found in finitely many steps.

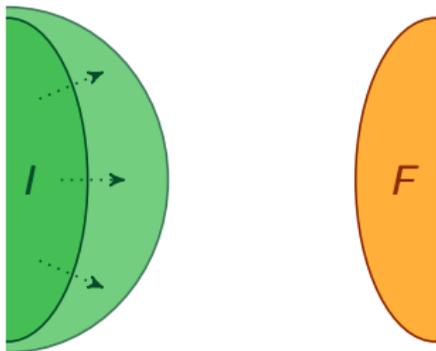
Forward analysis



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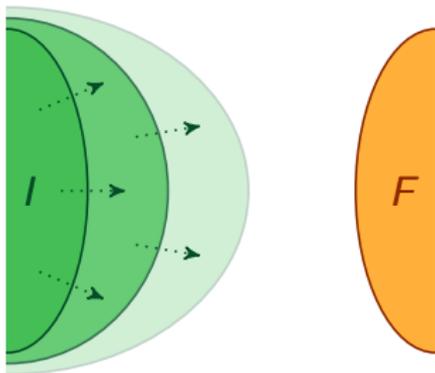
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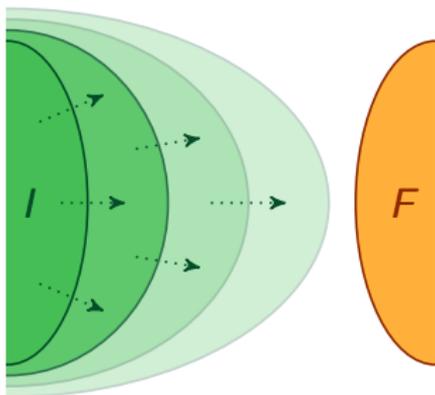
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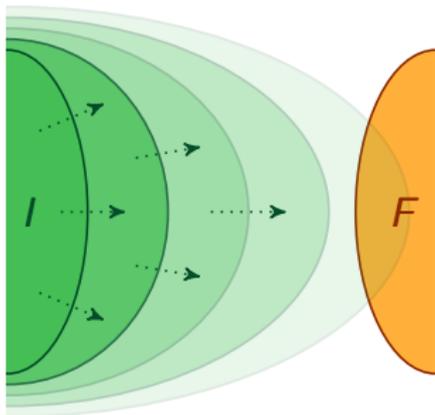
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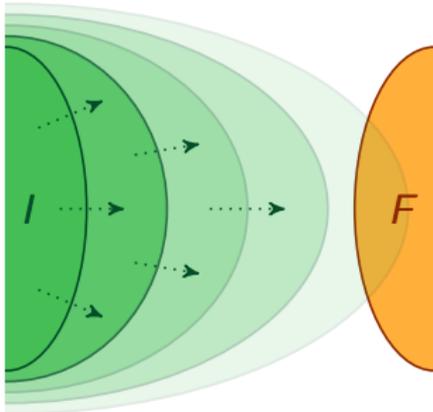
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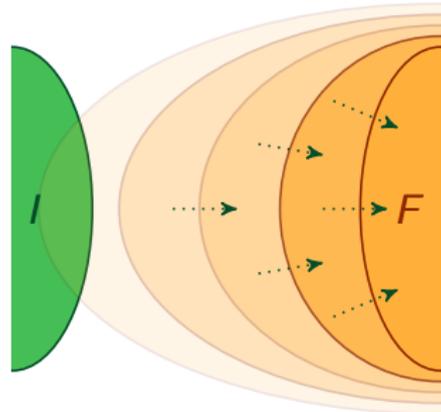
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Backward analysis

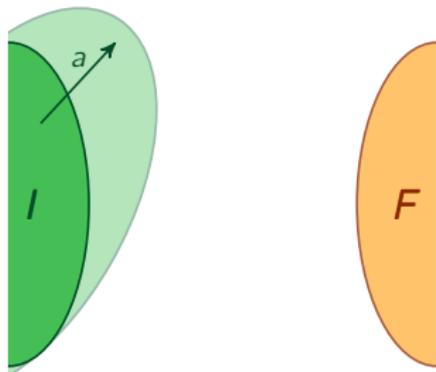


The problem is of course termination, namely, to detect non-reachability...

Sometimes non-reachability can be checked effectively using “safe” **over-approximations** of reachable sets

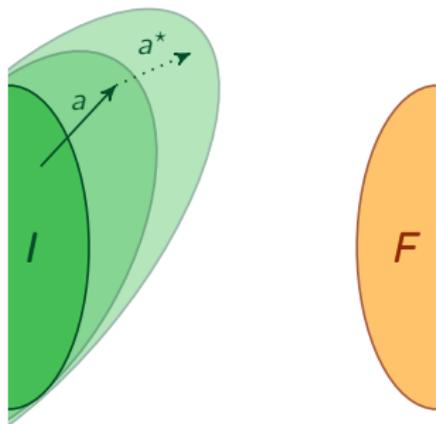
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Acceleration / pumping



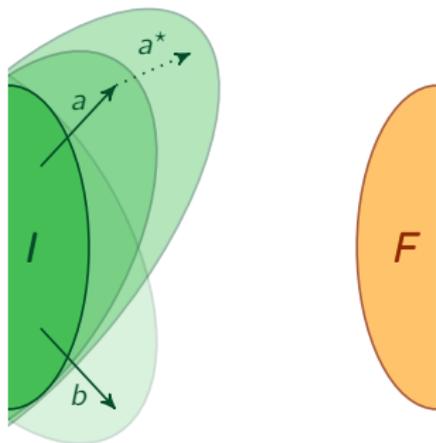
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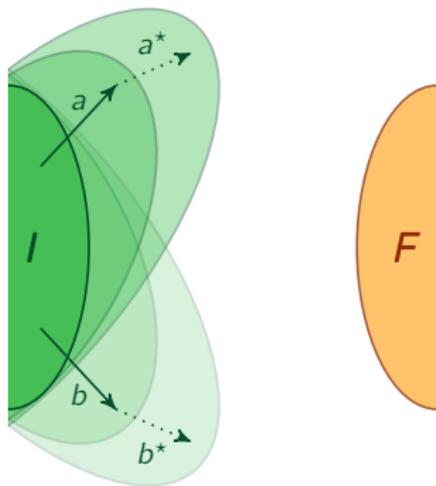
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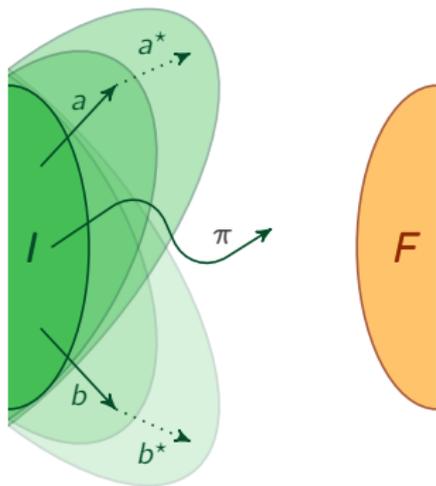
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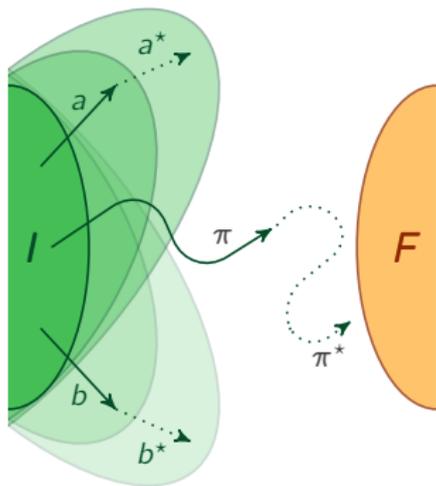
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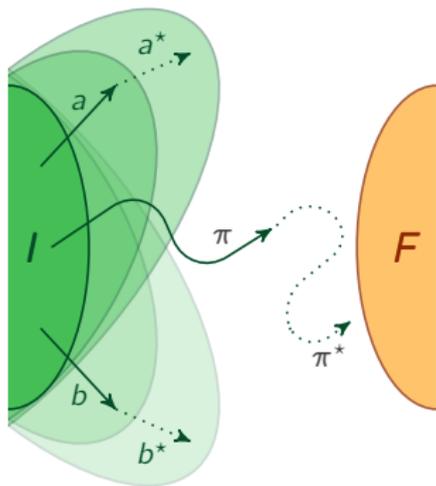
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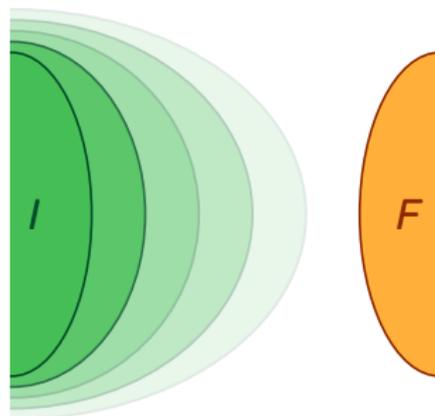


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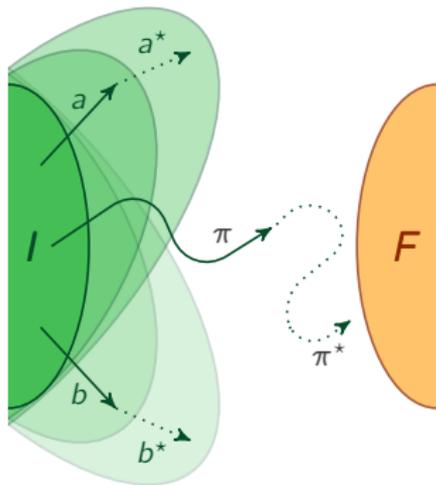


Invariant analysis

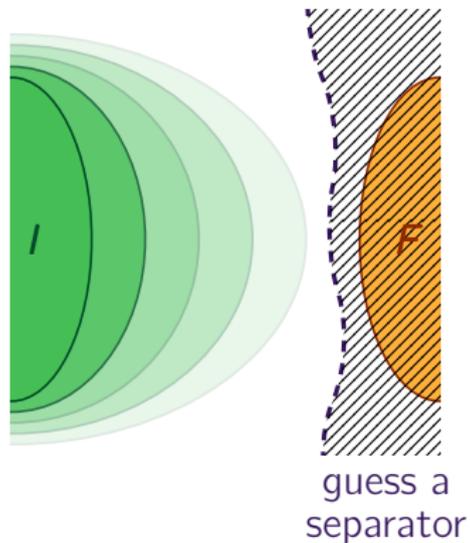


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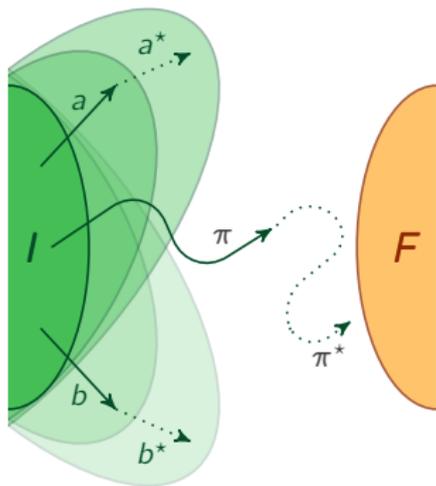


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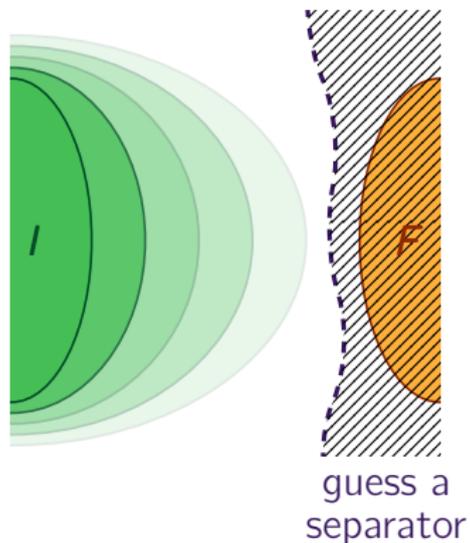


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Invariant analysis



👉 Both approaches require **symbolic representations** of infinite sets

Backward reachability for pushdown systems

Given a pushdown system $\mathcal{P} = (Q, \Sigma, \Gamma, \Delta)$ and a set $B_0 \subseteq Q \cdot \Gamma^*$ of target configurations, define:

$$B_{n+1} = B_n \cup \{ qz \mid \exists q'z' \in B_n. \exists a \in \Sigma. qz \xrightarrow{a} q'z' \}$$

$$B_\omega = \bigcup_{n \in \mathbb{N}} B_n$$

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Example

Consider the pushdown system



$$B_0 = \{q\varepsilon\} \quad B_1 = \{q\varepsilon, q\gamma\} \quad B_2 = \{q\varepsilon, q\gamma, q\gamma\gamma\} \quad \dots$$

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$B_\omega = q\varepsilon^*$ is indeed regular, but how to efficiently compute it?



“Pump” the changes from B_n to B_{n+1} to obtain a new sequence C_0, C_1, \dots that converges more quickly:

$$\text{(completeness)} \quad \forall n \in \mathbb{N}. \quad B_n \subseteq C_n$$

$$\text{(soundness)} \quad \forall n \in \mathbb{N}. \quad C_n \subseteq B_\omega$$

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the limit $\bigcup_{n \in \mathbb{N}} C_n$ coincides with B_ω



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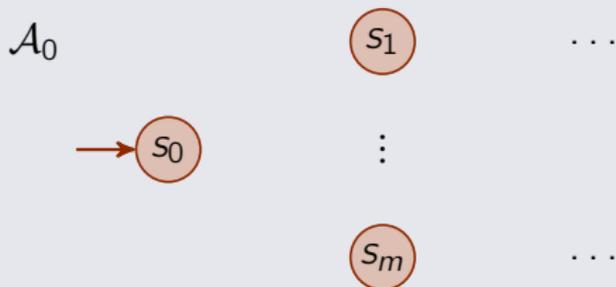
The sets C_0, C_1, \dots will be defined by automata $\mathcal{A}_0, \mathcal{A}_1, \dots$ sharing the **same state space**...

Initial conditions

- The pushdown system \mathcal{P} has m states q_1, \dots, q_m

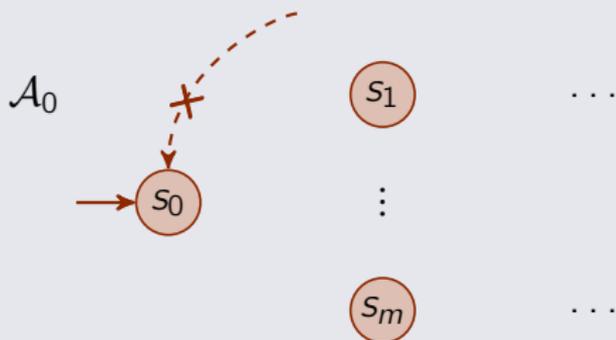
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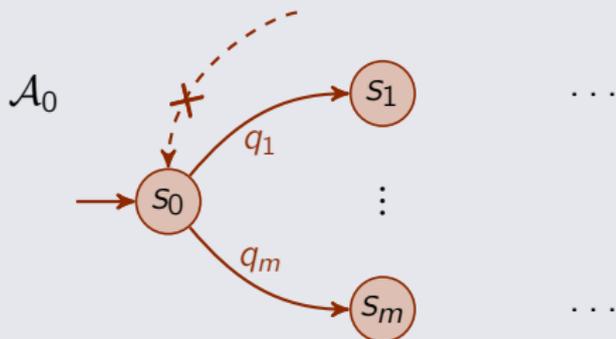
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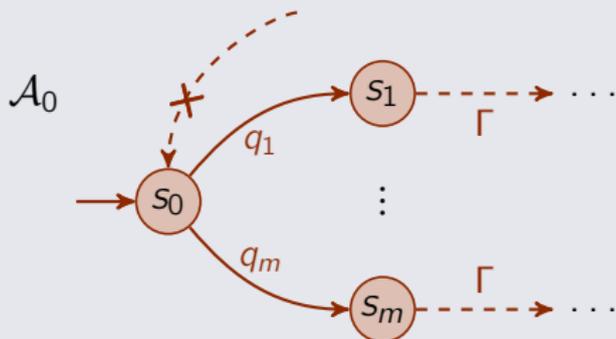
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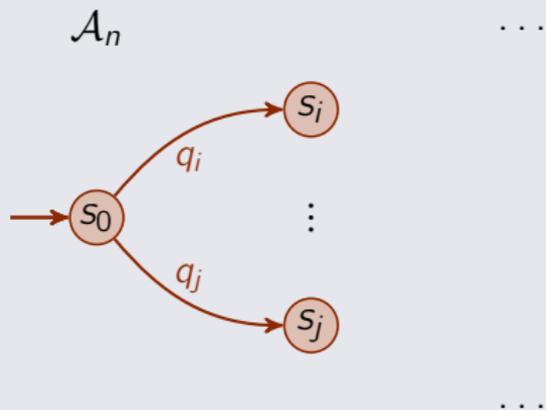
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- The other transitions in \mathcal{A}_0 are labelled by stack symbols



Saturation procedure

Construct \mathcal{A}_{n+1} from \mathcal{A}_n by adding transitions, as follows:

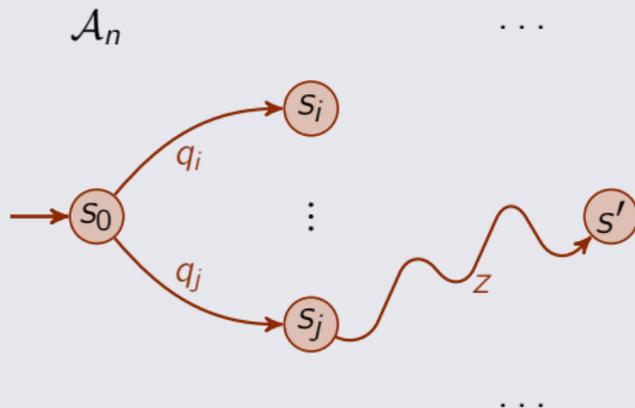
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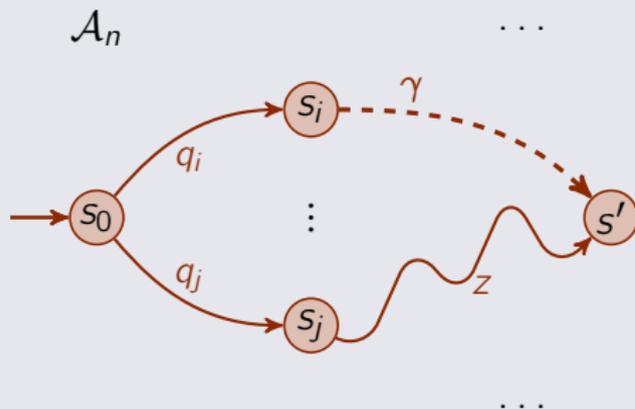
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Termination: straightforward

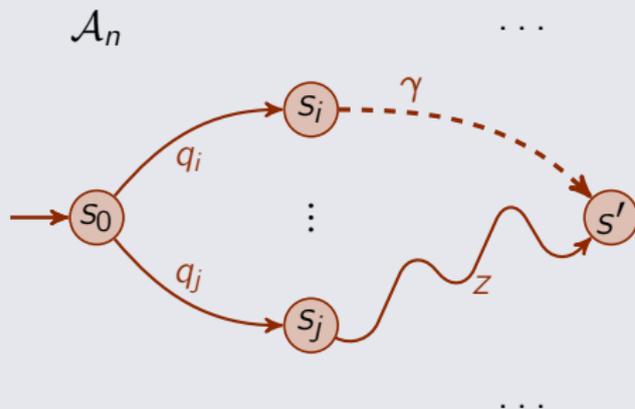
Only polynomially many
transitions can be added

(\Rightarrow reachability in PTIME)

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Soundness: by induction on n

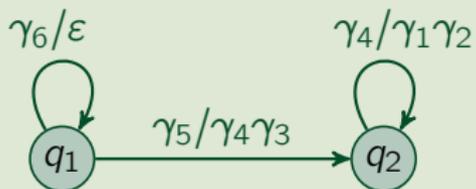
$$s_0 \xrightarrow[\mathcal{A}_{n+1}]{q'z'} s'$$

\Downarrow

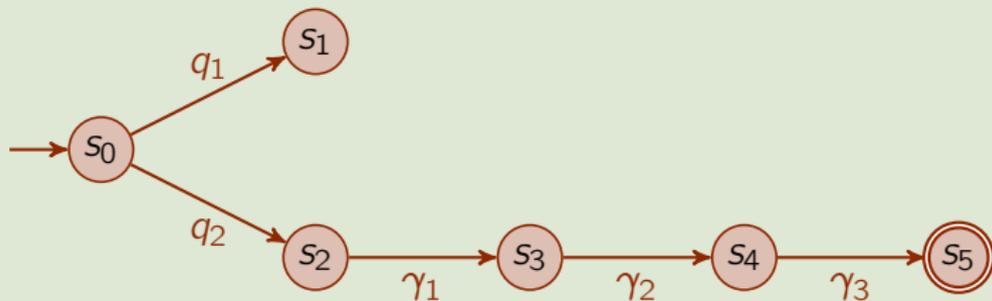
$$s_0 \xrightarrow[\mathcal{A}_0]{qz} s' \quad \wedge \quad q'z' \xrightarrow[\mathcal{P}]{*} qz$$

Example

Consider the target set $B_0 = \{q_2\gamma_1\gamma_2\gamma_3\}$ over the pushdown system

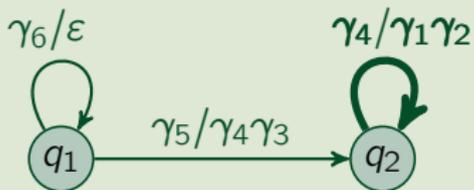


$$C_0 = \{q_2\gamma_1\gamma_2\gamma_3\}$$

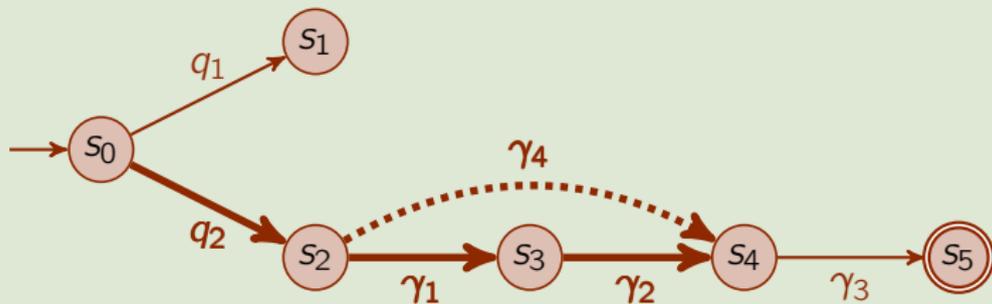


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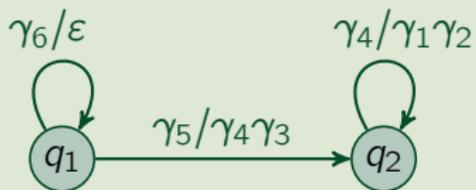


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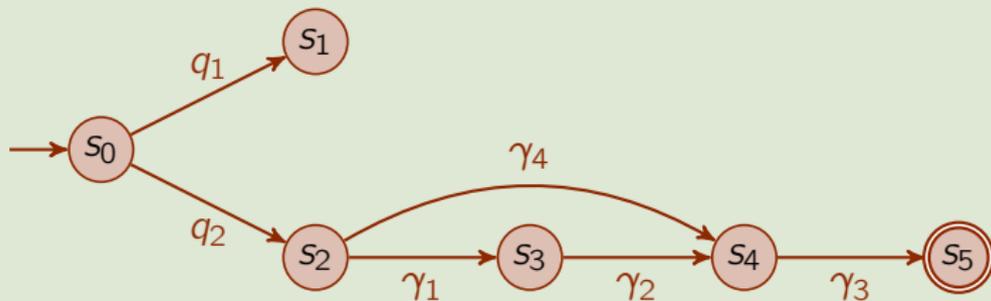
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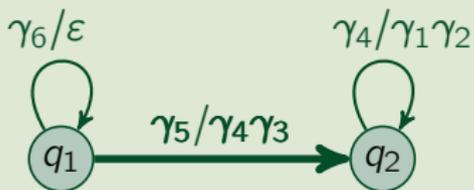
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$$C_1 = \{q_2\gamma_1\gamma_2\gamma_3, q_2\gamma_4\gamma_3\}$$



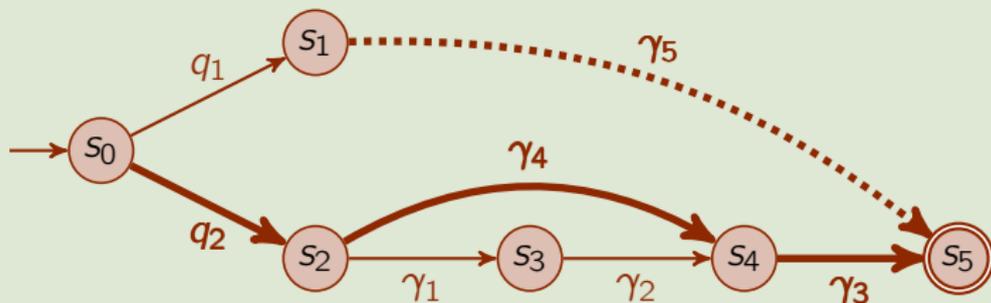
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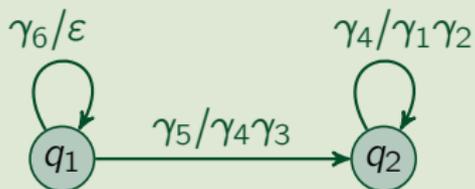
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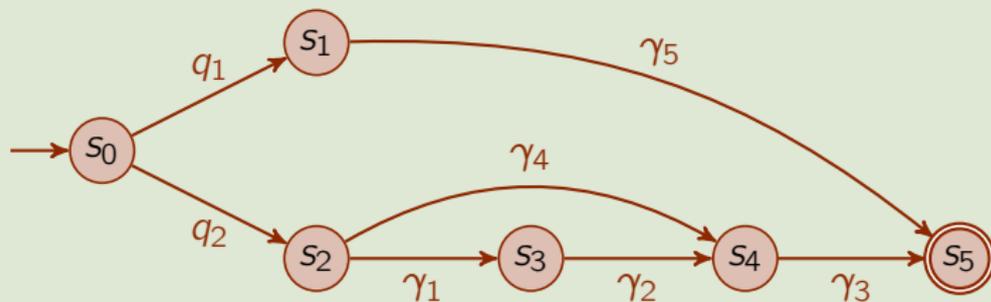
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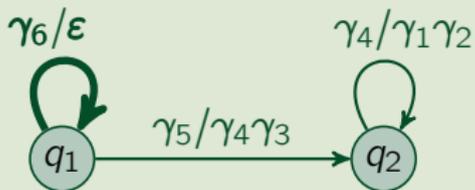
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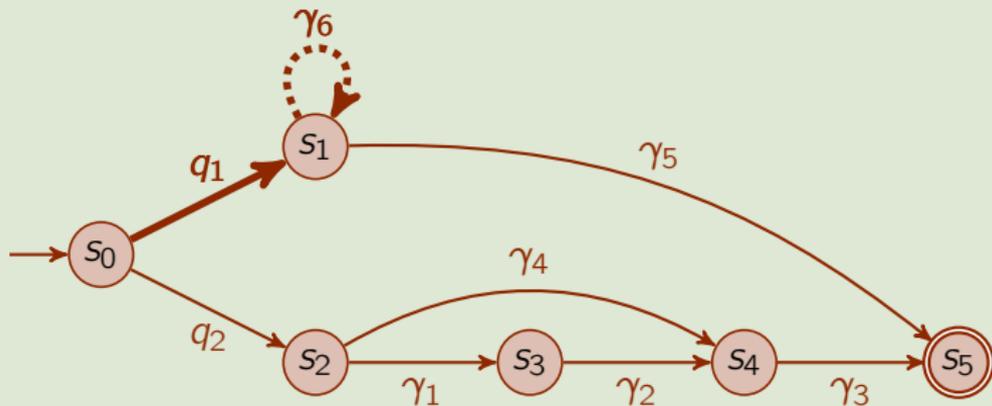
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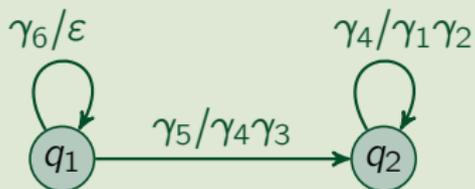
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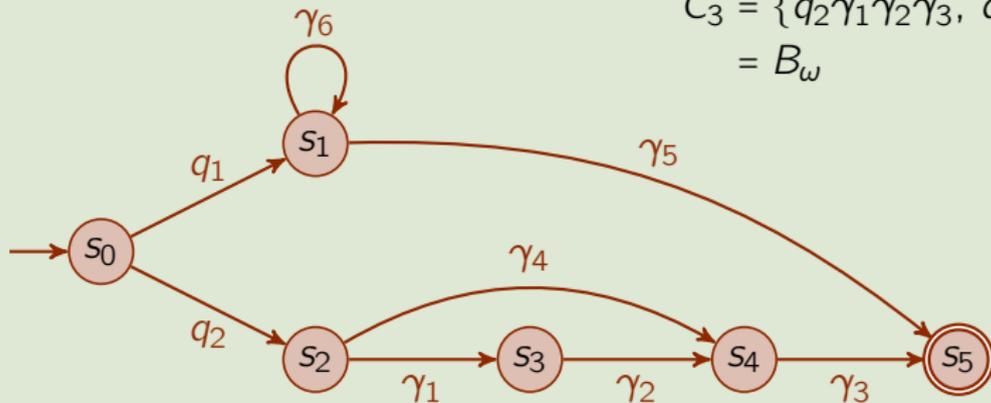


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$$C_3 = \{q_2\gamma_1\gamma_2\gamma_3, q_2\gamma_4\gamma_3, q_1\gamma_6^*\gamma_5\}$$
$$= B_\omega$$



Theorem (Bouajjani, Esparza & Maler '97)

Given a pushdown system \mathcal{P} and a regular set B of configurations, the set of configurations that can reach B is regular and can be computed in polynomial time.

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Given an **alternating** pushdown system \mathcal{P} and a regular set B of conf., the **winning region** for the **B -reachability game** is regular and can be computed in polynomial time.

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Similar generalizations can be proved for:

- **tree rewriting systems**
(Löding '06, ...)
- reachability games on **higher-order pushdown systems**
(Bouajjani & Meyer '04, Hague & Ong '07, ...)
- ...

Definition

A **lossy VAS** is a transition system (\mathbb{N}^k, Δ) ,
where Δ is a finite subset of $Q \times \mathbb{Z}^k \times Q$ and

$$\bar{x} \longrightarrow \bar{y} \quad \text{iff} \quad \begin{cases} \bar{x}, \bar{y} \geq 0 \\ \bar{y}' - \bar{x} \in \Delta \quad \text{for some } \bar{y}' \geq \bar{y} \end{cases}$$

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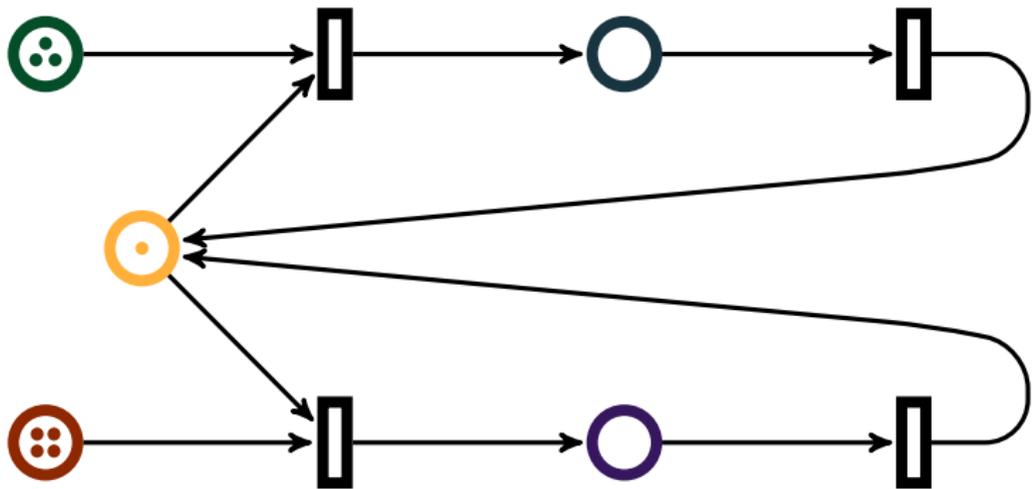
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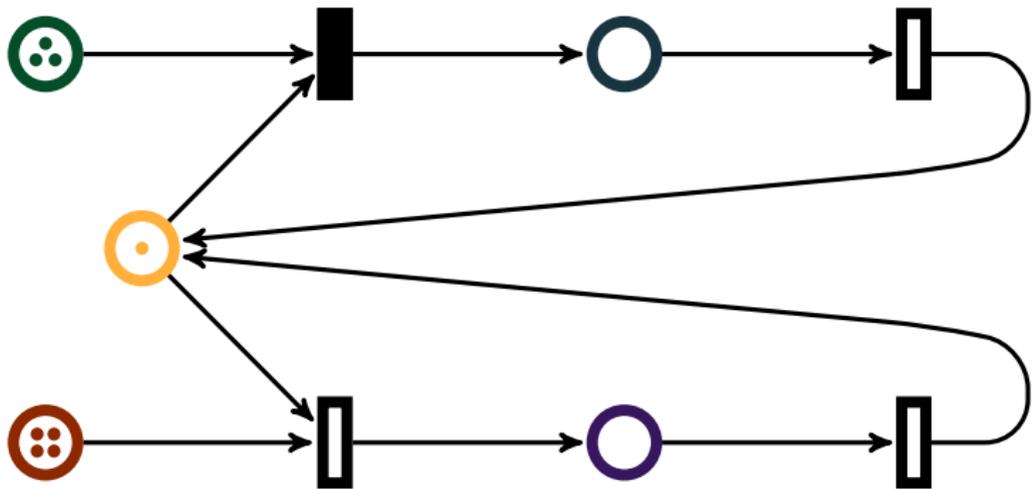
 States do not add power, as they can be implemented by counters

e.g. 2 states = 2 additional counters that sum up to 1
 $(p, \bar{x}) \longrightarrow (q, \bar{y})$ becomes $(0, 1, \bar{x}) \longrightarrow (1, 0, \bar{y})$

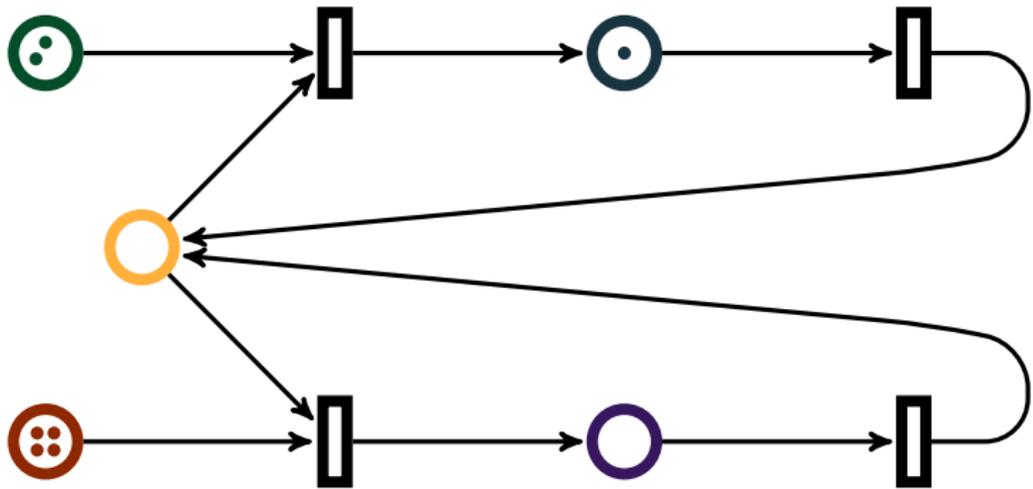
VAS are the same as **Petri nets**:



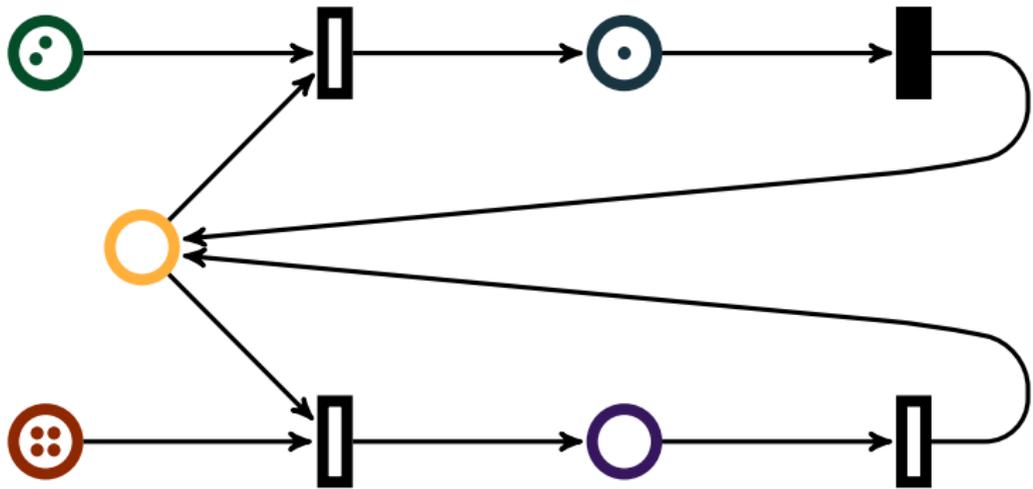
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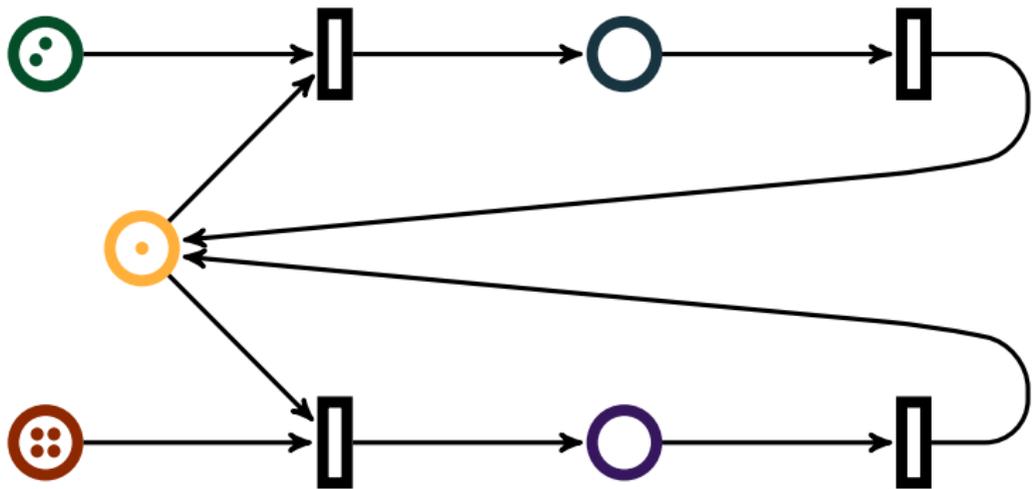
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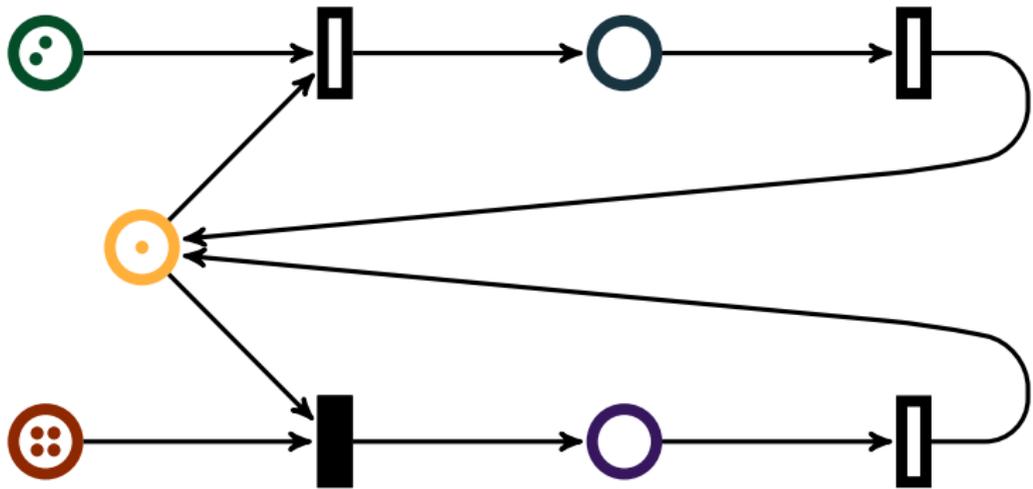
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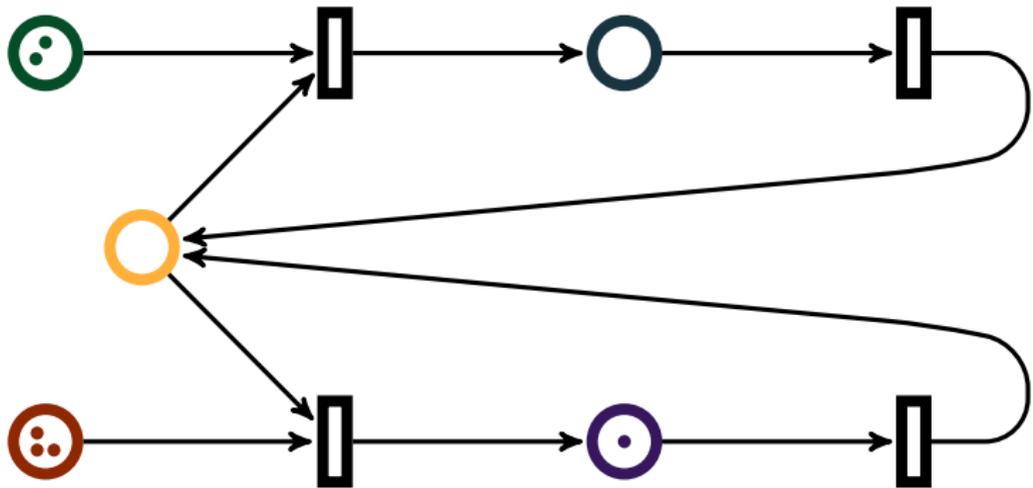
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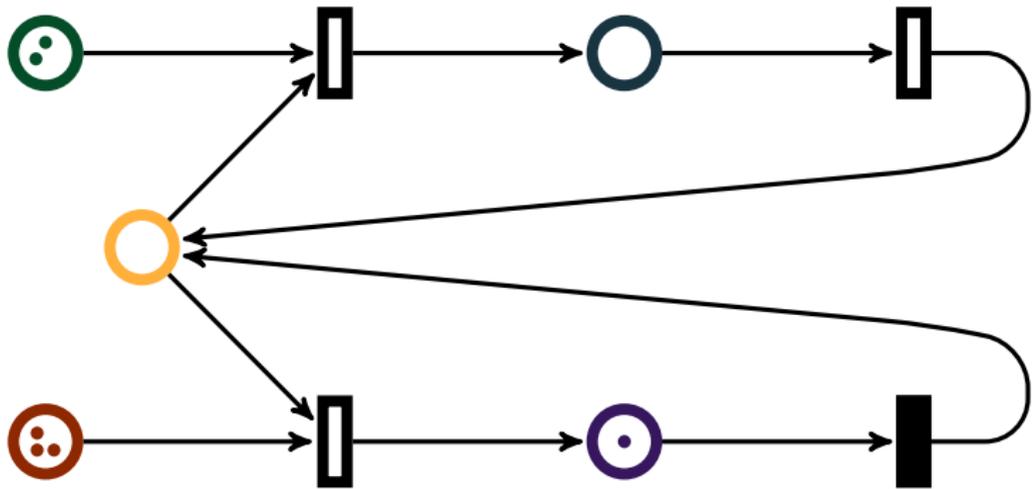
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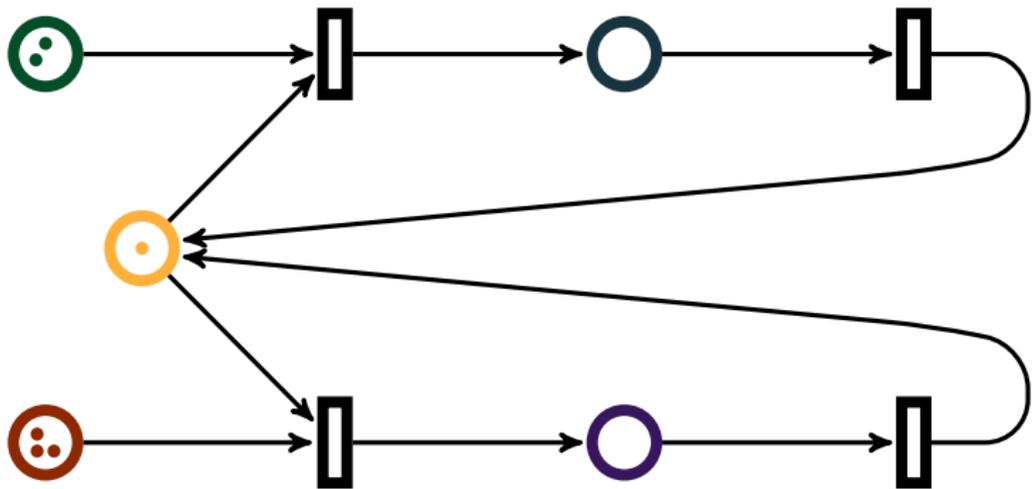
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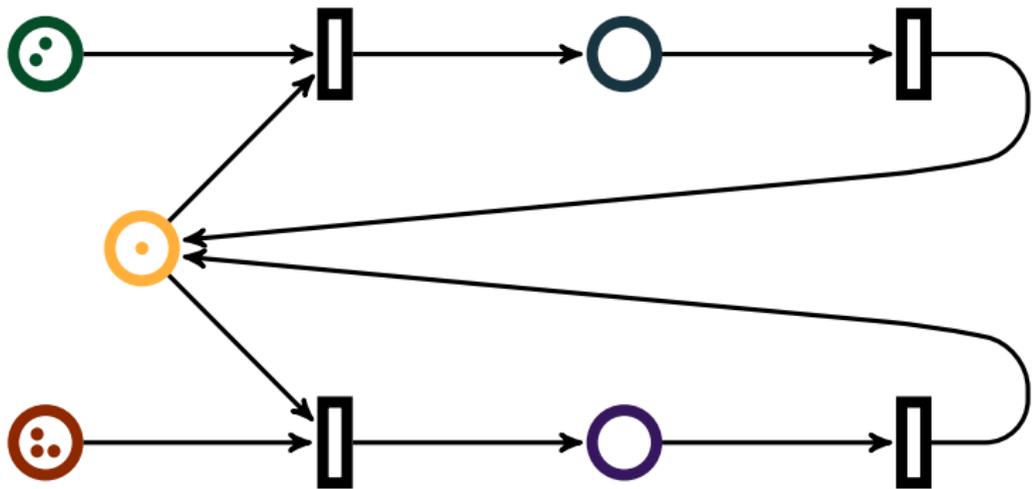
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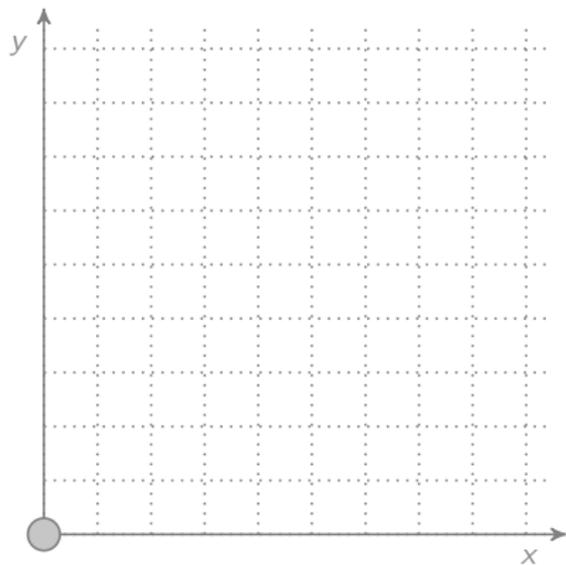
VAS are the same as **Petri nets**:



👉 configurations = tokens per location (e.g. $(2, 1, 3, 0, 0)$)
transitions = transfers of tokens (e.g. $(0, -1, -1, 0, 1)$)

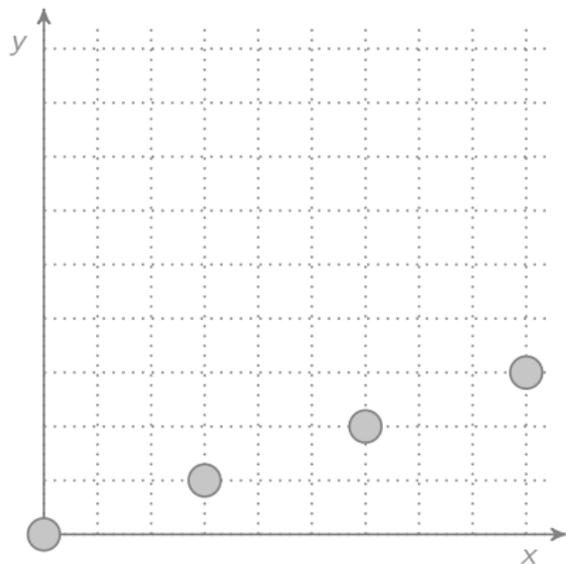
We may expect that reachable sets are **linear**...

$(0, 0)$



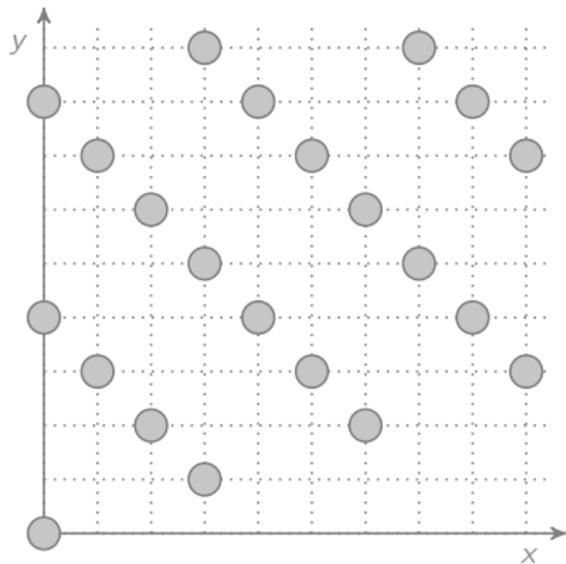
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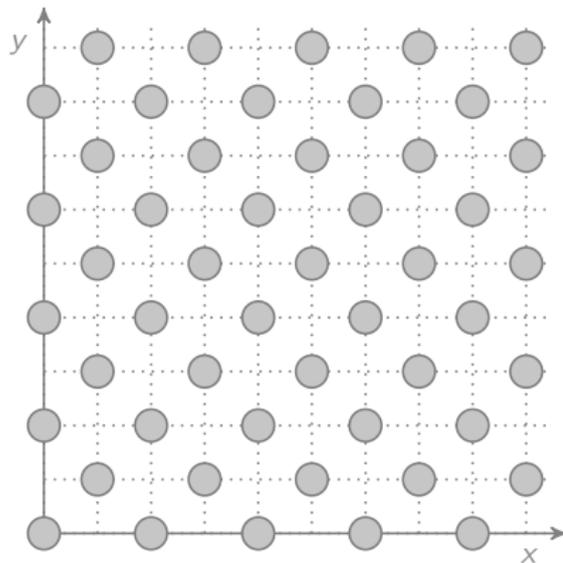
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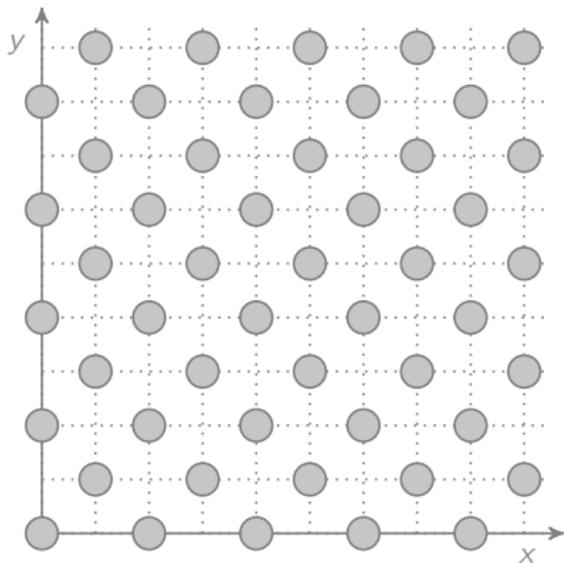
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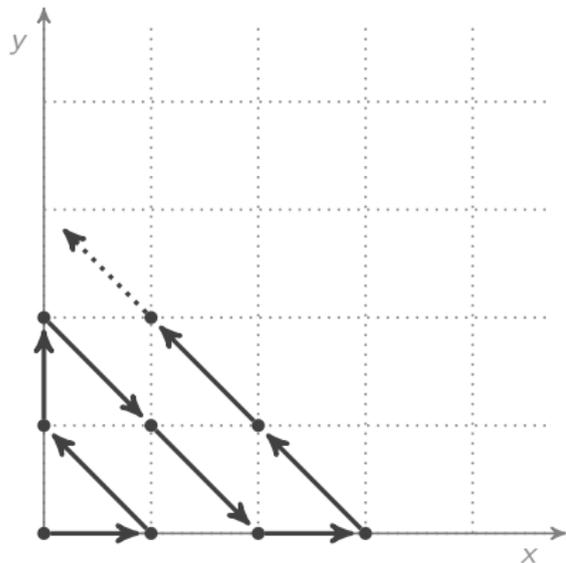
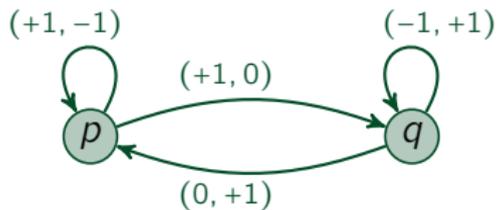
Theorem (Ginsburg '66)

Finite unions of linear sets are precisely the **Presburger sets**
i.e. sets definable in **FO[$\mathbb{N}, +$]**

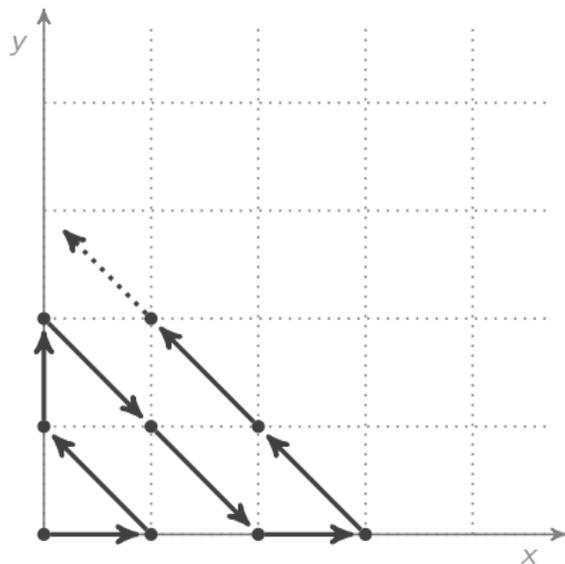
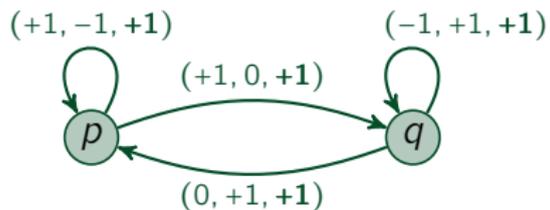
e.g. $\varphi(x, y) = \exists z. x + y = z + z$



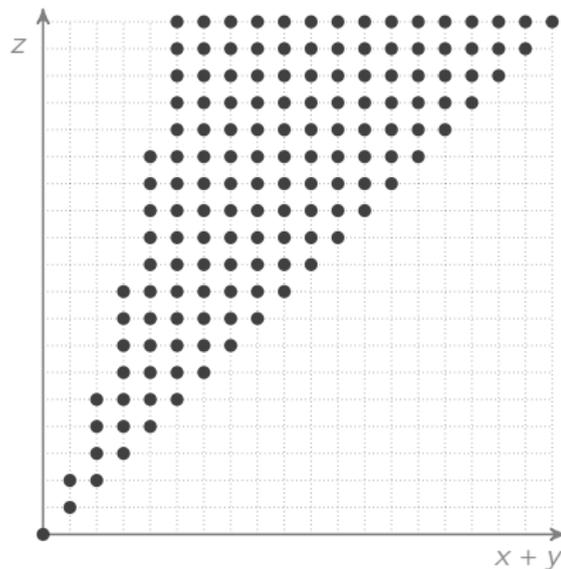
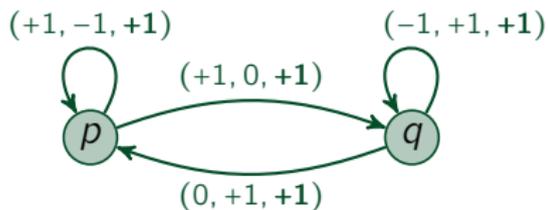
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$$(x + y) \leq z \leq \mathcal{O}((x + y)^2)$$

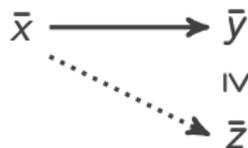
To overcome the problem of representing reachable sets, we try to **over-approximate by downward closures**:

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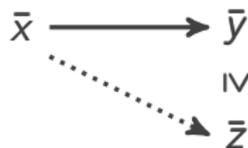
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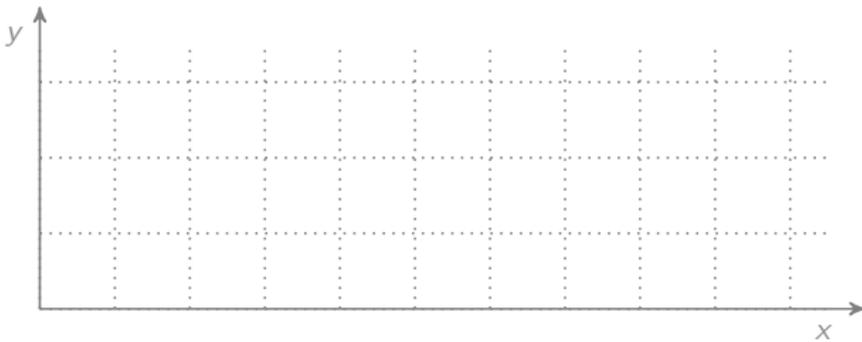
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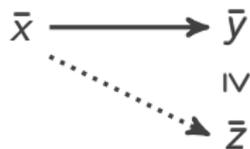
The pointwise order \leq on \mathbb{N}^k is a **well partial order** (i.e. all **decreasing chains** and all **antichains** are finite)



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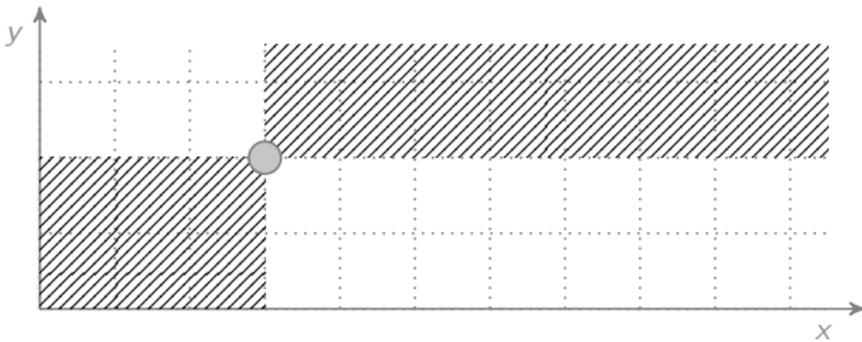
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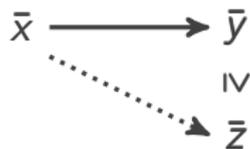
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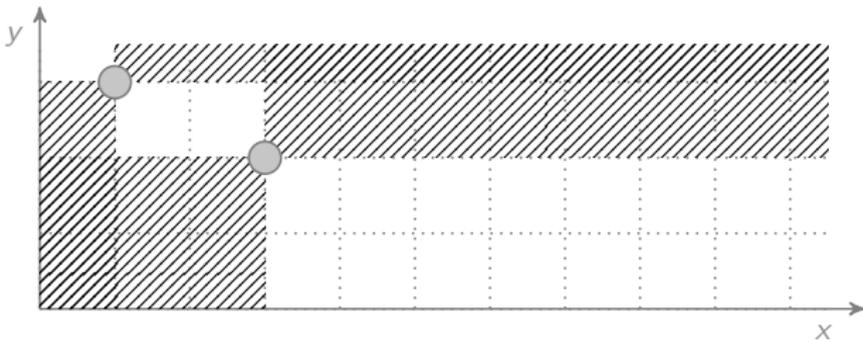
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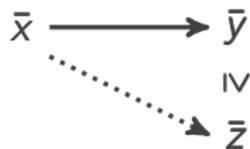
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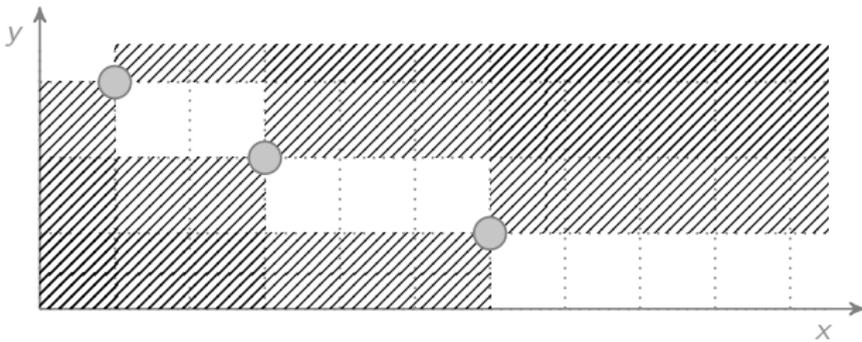
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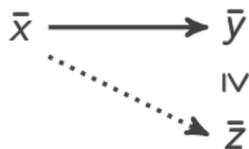
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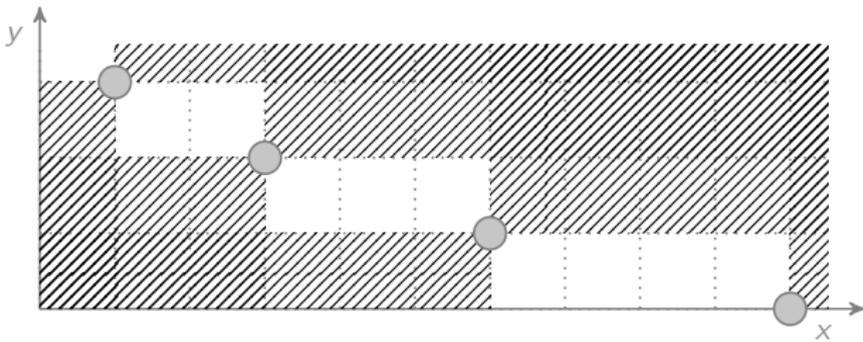
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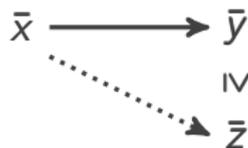
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Lemma

For all subsets V of $(\mathbb{N} \cup \{\infty\})^k$, there is an **antichain** W such that

$$V^\downarrow = W^\downarrow$$

⇒ we can finitely represent downward-closed sets by antichains

Karp & Miller Algorithm '69

Saturation of downward-closed sets via transition function Δ

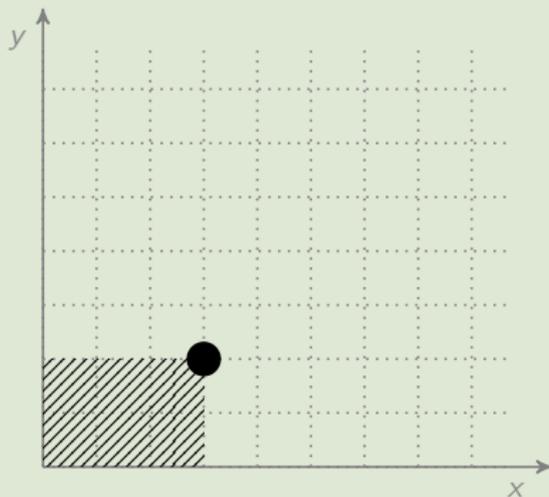
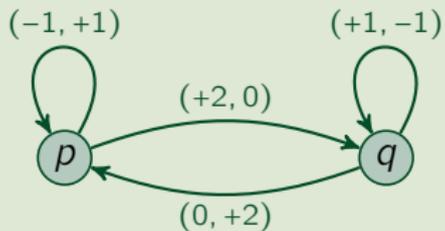
 acceleration on emerging dominating sets...

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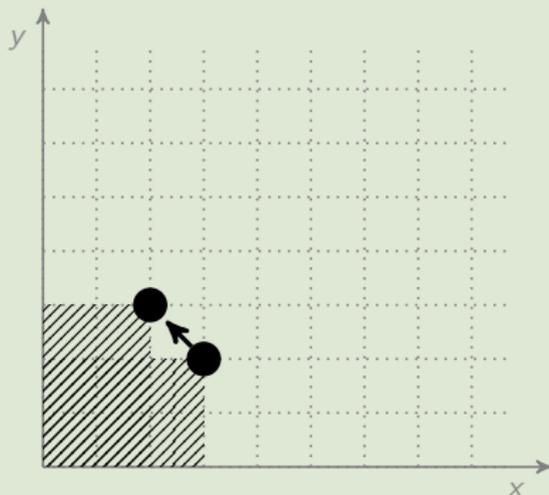
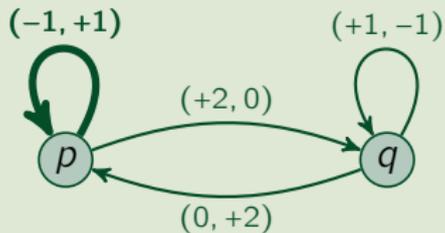


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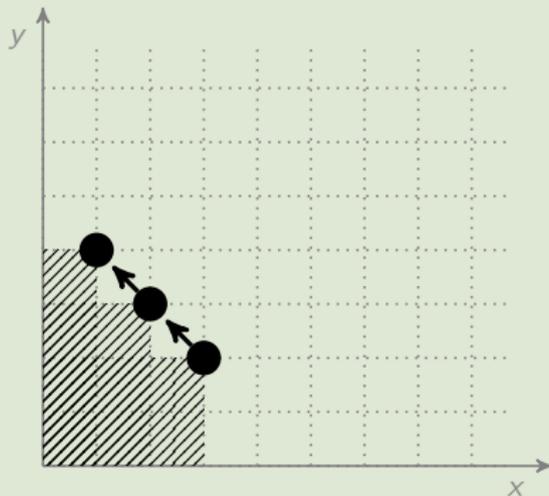
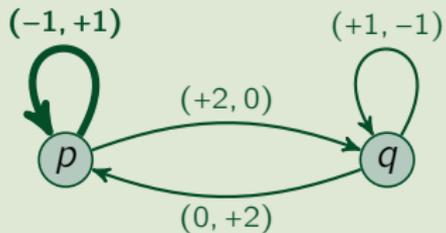


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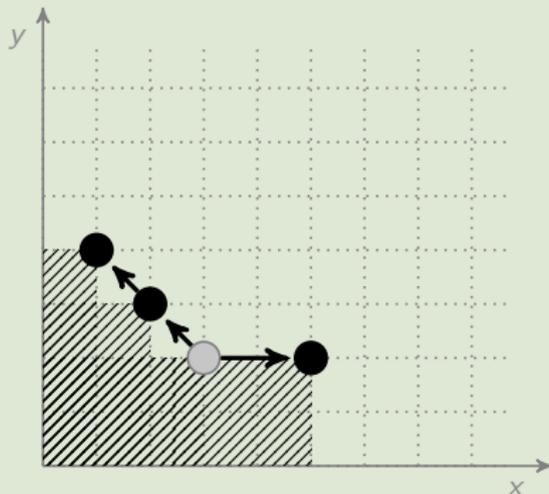
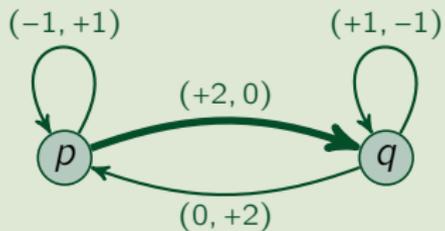


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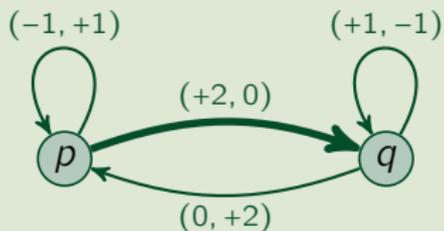


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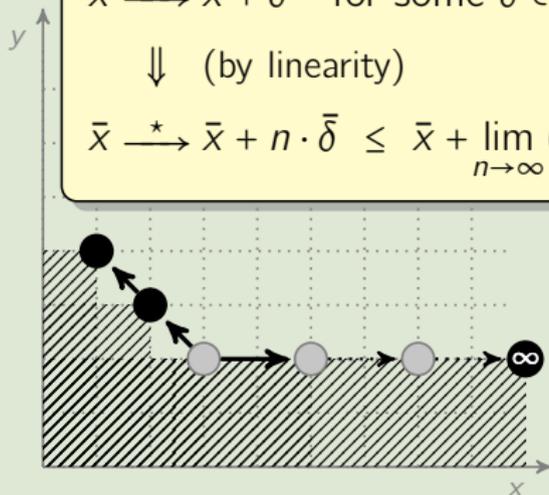


Correctness of acceleration

$$\bar{x} \xrightarrow{*} \bar{x} + \bar{\delta} \quad \text{for some } \bar{\delta} \in \mathbb{N}^k$$

↓ (by linearity)

$$\bar{x} \xrightarrow{*} \bar{x} + n \cdot \bar{\delta} \leq \bar{x} + \lim_{n \rightarrow \infty} (n \cdot \bar{\delta})$$

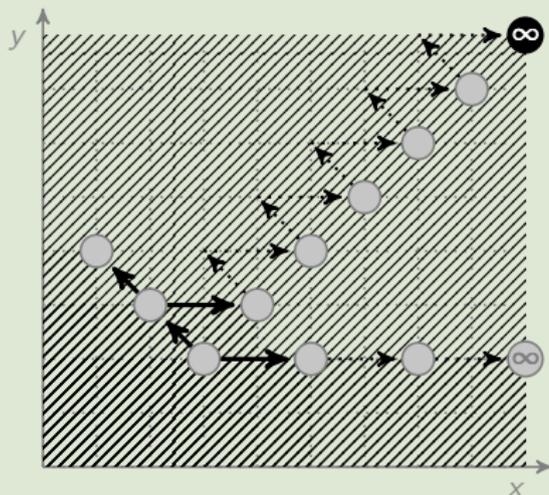
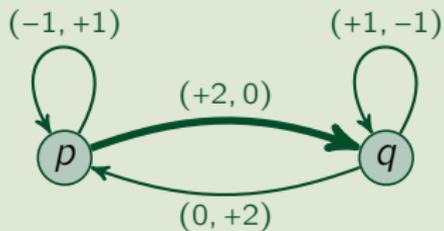


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Example



Theorem (Rackoff '78)

Coverability on VAS (i.e. given \bar{x}, \bar{y} , tell if $\exists \bar{z} \geq \bar{y}. \bar{x} \xrightarrow{*} \bar{z}$)
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Corollary 1

Reachability on lossy VAS is EXPSPACE-complete.

Corollary 2

Control-state reachability on VAS is EXPSPACE-complete.

There are other results similar in spirit...

Theorem (Adbulla, Cerans & Jonsson '96, ...)

Coverability is decidable (**non-primitive recursive**) on VAS with

- **resets** (e.g. $x := 0$)
- **transfers** (e.g. $x := y + z$)
- **positive guards** (e.g. *if* $[x > 0]$ *then* ...)

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Unfortunately, acceleration for the above systems does not work,

e.g. $(1, 0) \xrightarrow[y:=1]{\text{reset } x} (0, 1) \xrightarrow[y:=y-1]{x:=x+2} (2, 0)$, but $(1, 0) \not\xrightarrow{*} (3, 0)$

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However, we can still exploit Dickson's Lemma with

① **upward-closed sets**

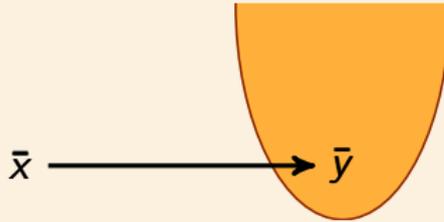
they cover more vectors than downward-closed sets!

② **backward reachability**

i.e. compute $B_{n+1} = \{ \bar{x} \mid \exists \bar{y} \in B_n. \bar{x} \longrightarrow \bar{y} \}$

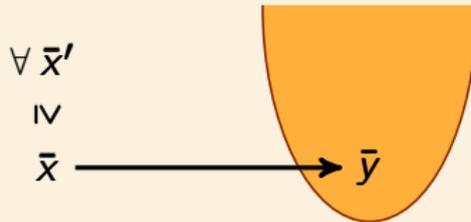
Lemma

VAS transitions with resets, transfers, and positive guards are **backward-compatible with upward-closures**, i.e.



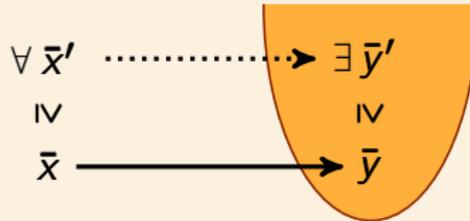
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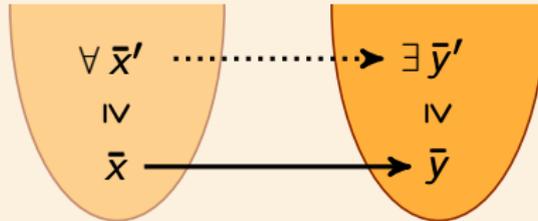
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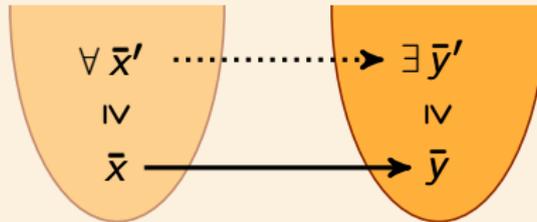
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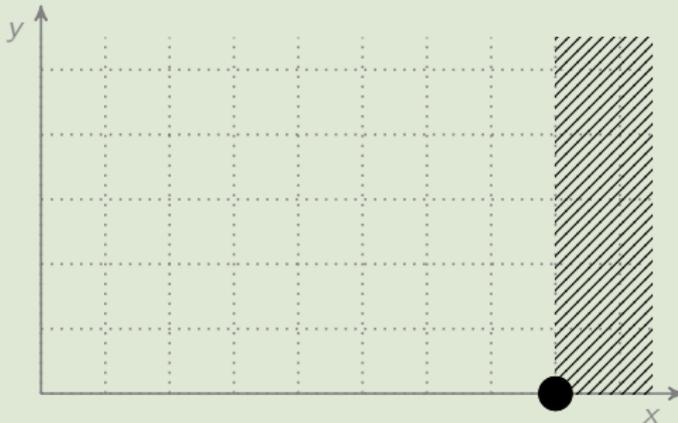


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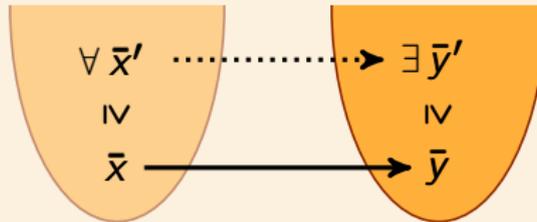


Example of backward coverability analysis

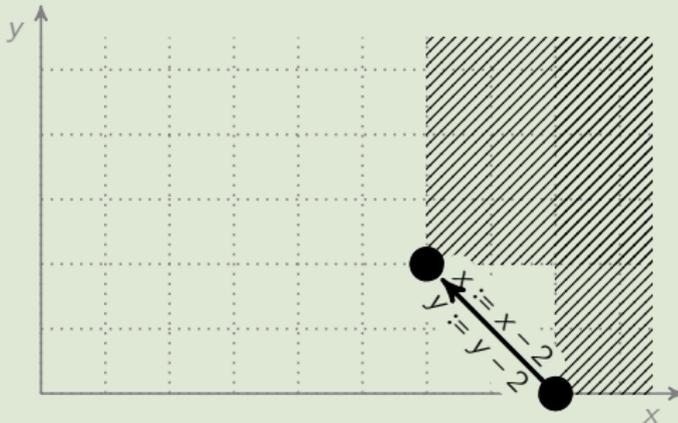


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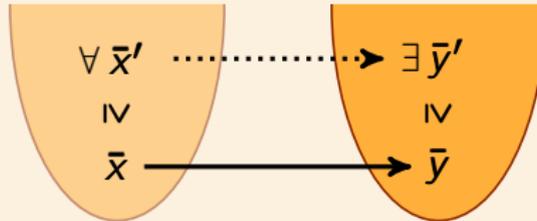


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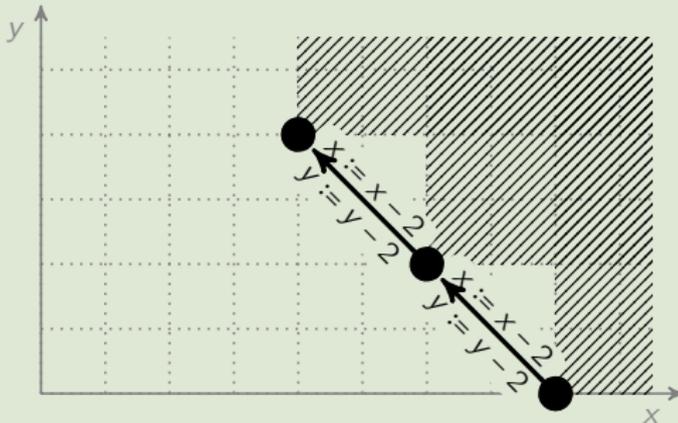


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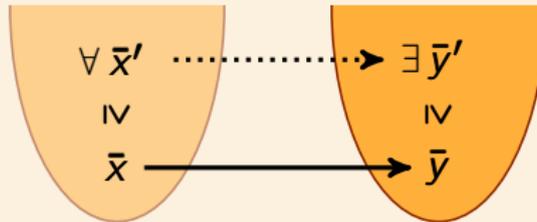


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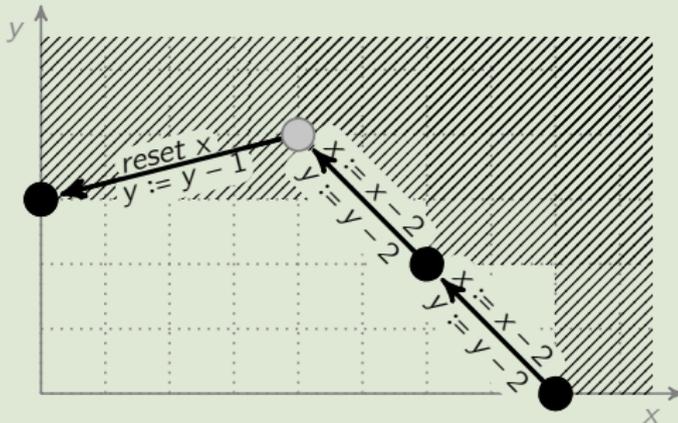


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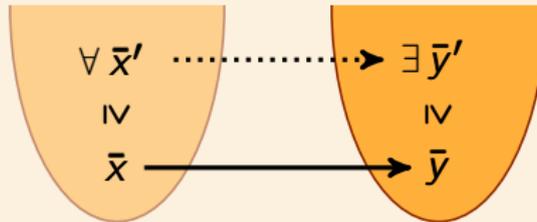


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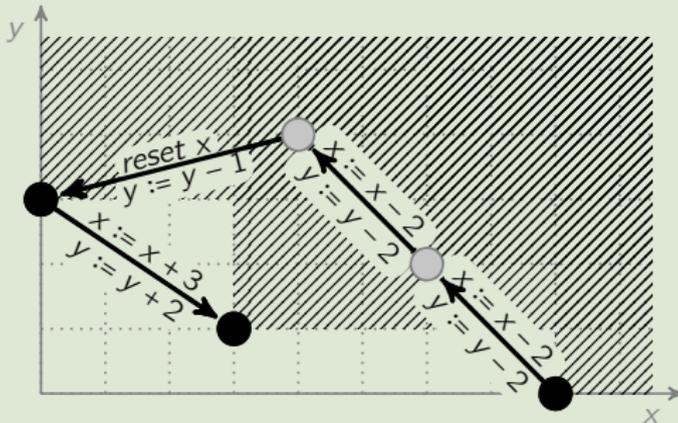


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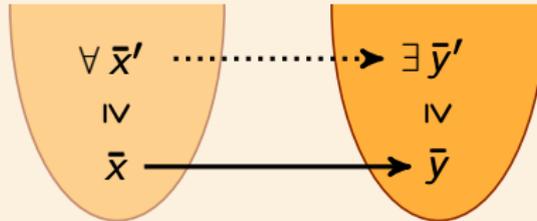


Example of backward coverability analysis

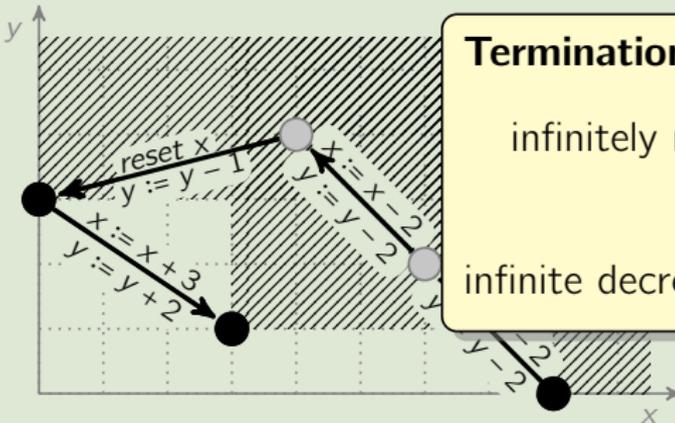


Lemma

VAS transitions with resets, transfers, and positive guards are **backward-compatible with upward-closures**, i.e.



Example of backward coverability analysis



Termination by Dickson's Lemma:

infinitely many emerging points



infinite decreasing chain or antichain

These ideas for coverability analysis can be extended to:

- **Lossy Channel Systems**

(instead of Dickson's Lemma,
use Higman's Lemma for the sub-sequence partial order)

- **Timed Petri nets**

(token have time-stamps, transitions have time constraints)

- **Alternating Finite Memory Automata**

(finite control states + one register to store
and compare symbols from an infinite alphabet)

- ...

Now, back to the original reachability problem on VAS...

Separation Theorem (Leroux '92, '09, ..., '12)

If $\bar{x} \not\rightarrow_{\Delta}^* \bar{y}$, then there is a partition (X, Y) of \mathbb{N}^k such that

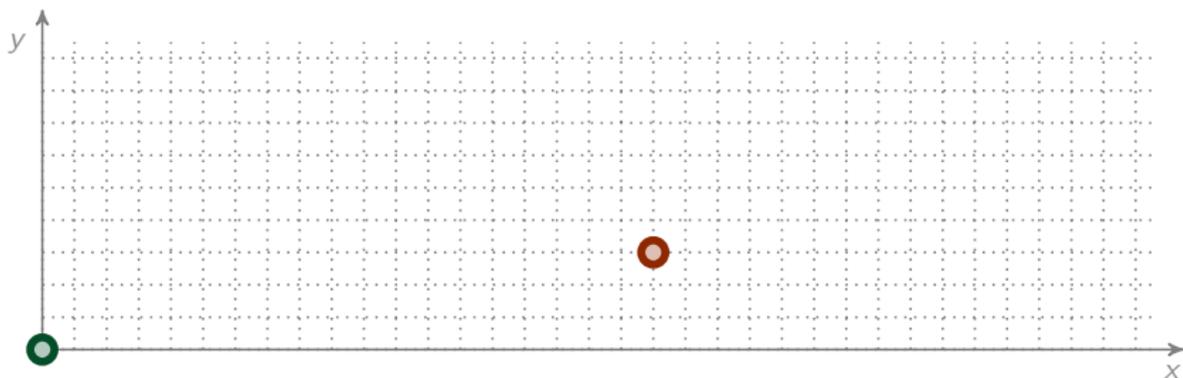
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(or, equally, sets definable in **Presburger logic** $\text{FO}[\mathbb{N}, +]$)
- 2 $\bar{x} \in X$ and $\bar{y} \in Y$
- 3 X is a **forward invariant**, i.e. $(X + \Delta) \cap \mathbb{N}^k \subseteq X$
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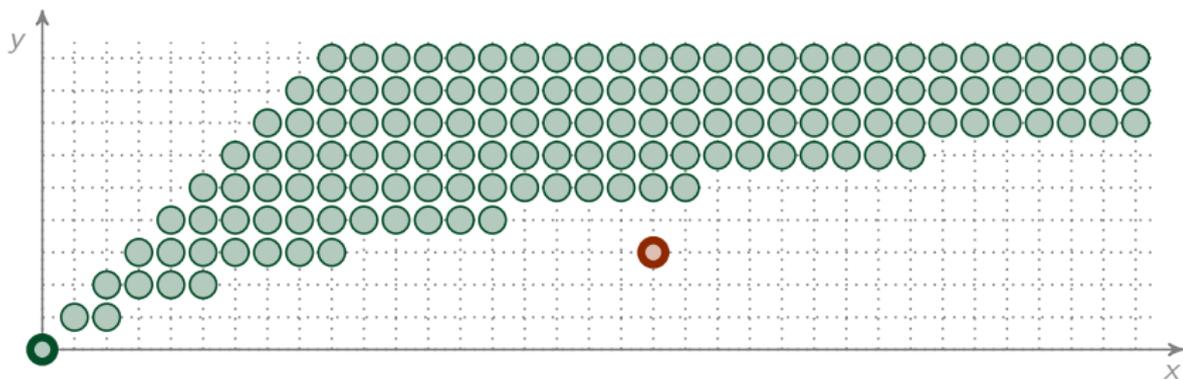


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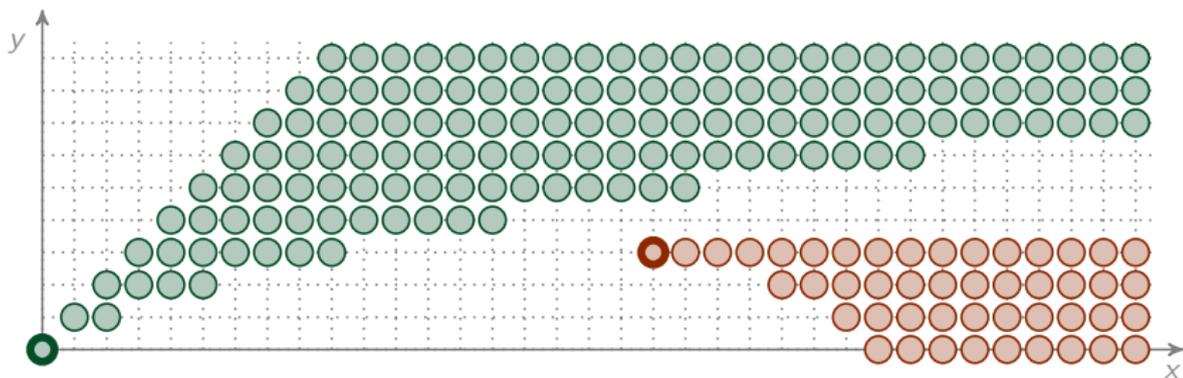


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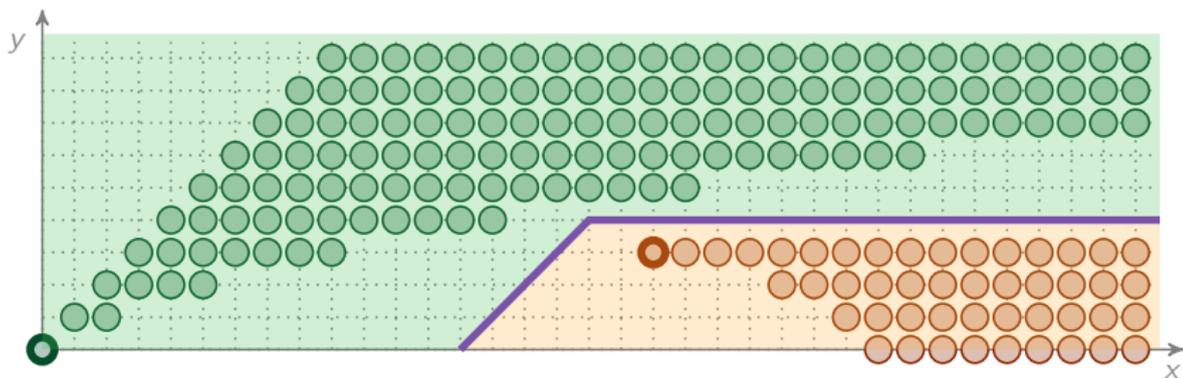


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Enumerate in parallel:

- 1 the possible finite sequences π of transitions
(answer positively if $\bar{x} \xrightarrow{\pi} \bar{y}$)
- 2 the possible Presburger formulas defining partitions (X, Y) of \mathbb{N}^k
(answer negatively if (X, Y) is an invariant separating \bar{x} and \bar{y})

"That's all Folks!"

