

# Introduction to Probabilistic Logic Programming

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# Outline

- Logic
- Handling Uncertainty
- Probabilistic logics
- Probabilistic logic programming
- Other formalisms
- Examples
- Reasoning



- Useful to model domains with complex relationships among entities
- Various forms:
  - First Order Logic
  - Logic Programming
  - Description Logics



# First Order Logic

- Very expressive
- Open World Assumption
- Undecidable

$\forall x \textit{ Intelligent}(x) \rightarrow \textit{GoodMarks}(x)$

$\forall x, y \textit{ Friends}(x, y) \rightarrow (\textit{Intelligent}(x) \leftrightarrow \textit{Intelligent}(y))$



# Logic Programming

- Closed World Assumption
- Turing complete
- Prolog

```
flu(bob).  
hay_fever(bob).  
sneezing(X) ← flu(X).  
sneezing(X) ← hay_fever(X).
```



# Description Logics

- Subsets of First Order Logic
- Open World Assumption
- Decidable, efficient inference
- Special syntax using concepts (unary predicates) and roles (binary predicates)

*fluffy* : *Cat*

*tom* : *Cat*

*Cat*  $\sqsubseteq$  *Pet*

$\exists$ *hasAnimal*.*Pet*  $\sqsubseteq$  *NatureLover*

*(kevin, fluffy)* : *hasAnimal*

*(kevin, tom)* : *hasAnimal*

*cat(fluffy)*.

*cat(tom)*.

*pet(X)*  $\leftarrow$  *cat(X)*.

*natureLover(X)*  $\leftarrow$  *hasAnimal(X, Y), pet(Y)*.

*hasAnimal(kevin, fluffy)*.

*hasAnimal(kevin, tom)*.



# Uncertainty

- Logic: representing relationships, powerful inference
- but the real world is often uncertain

$$\forall x \textit{ Intelligent}(x) \rightarrow \textit{ GoodMarks}(x)$$

$$\forall x, y \textit{ Friends}(x, y) \rightarrow (\textit{ Intelligent}(x) \leftrightarrow \textit{ Intelligent}(y))$$



# Handling Uncertainty

- Often convenient to describe a domain using a set of random variables.
- Example: home intrusion detection system
  - Earthquake  $E$
  - Burglary  $B$
  - Alarm  $A$
  - Neighbor call  $N$
- Questions:
  - What is the probability of a burglary? (compute  $P(B = t)$ , belief computation)
  - What is the probability of a burglary given that the neighbor called? (compute  $P(B = t|N = t)$ , belief updating)
  - What is the probability of a burglary given that there was an earthquake and the neighbor called? (compute  $P(B = t|N = t, E = t)$ , belief updating)
  - What is the most likely value for burglary given that the neighbor called? ( $\arg \max_b P(b|N = t)$ , belief revision)





# Handling Uncertainty

- When assigning a causal meaning to the variables, the problems are also called
  - Diagnosis: computing  $P(\textit{cause}|\textit{symptom})$
  - Prediction: computing  $P(\textit{symptom}|\textit{cause})$
  - Classification: computing  $\arg \max_{\textit{class}} P(\textit{class}|\textit{data})$



# Handling Uncertainty

- In general, we want to compute

$$P(\mathbf{q}|\mathbf{e})$$

of a **query**  $\mathbf{q}$  (assignment of values to a set of variables  $\mathbf{Q}$ ) given the evidence  $\mathbf{e}$  (assignment of values to a set of variables  $\mathbf{E}$ ).

- **Inference.**



# Rules of Probability Theory

- **Product rule:**  $P(a, b) = P(a|b)P(b)$ 
  - Implies Bayes rule:

$$P(a|b)P(b) = P(b|a)P(a)$$
$$P(a|b) = \frac{P(b|a)P(a)}{P(b)}$$

- **Sum rule:**  $P(a) = \sum_b P(a, b)$



# Handling Uncertainty

- $\mathbf{X}$ : set of all variables describing the domain
- Joint probability distribution  $P(\mathbf{X})$ :  $P(\mathbf{x})$  for all  $\mathbf{x}$
- We can answer all types of queries using the definition of conditional probability and the sum rule:

$$P(\mathbf{q}|\mathbf{e}) = \frac{P(\mathbf{q}, \mathbf{e})}{P(\mathbf{e})} = \frac{\sum_{\mathbf{y}, \mathbf{Y}=\mathbf{X}\setminus\mathbf{Q}\setminus\mathbf{E}} P(\mathbf{y}, \mathbf{q}, \mathbf{e})}{\sum_{\mathbf{z}, \mathbf{Z}=\mathbf{X}\setminus\mathbf{E}} P(\mathbf{z}, \mathbf{e})}$$



# Handling Uncertainty

- If we have  $n$  binary variables ( $|\mathbf{X}| = n$ ), knowing the joint probability distribution requires storing  $O(2^n)$  different values.
- Even if we had the space, computing  $P(\mathbf{q}|\mathbf{e})$  would require  $O(2^n)$  operations.



# Handling Uncertainty

- A value of  $\mathbf{X}$  is  $(x_1, \dots, x_n)$ :

$$\begin{aligned} P(\mathbf{x}) &= P(x_1, \dots, x_n) = \\ &P(x_n | x_{n-1}, \dots, x_1) P(x_{n-1}, \dots, x_1) = \\ &\dots \\ &P(x_n | x_{n-1}, \dots, x_1) \dots P(x_2 | x_1) P(x_1) = \quad (1) \\ &\prod_{i=1}^n P(x_i | x_{i-1}, \dots, x_1) \end{aligned}$$

by repeated application of the product rule.

- Chain rule.



# Handling Uncertainty

- If, for each variable  $X_j$ ,  $\mathbf{Pa}_j$  is a subset of  $\{X_{j-1}, \dots, X_1\}$  such that  $X_j$  is conditionally independent of  $\{X_{j-1}, \dots, X_1\} \setminus \mathbf{Pa}_j$  given  $\mathbf{Pa}_j$ , i.e.,

$$P(x_j | x_{j-1}, \dots, x_1) = P(x_j | \mathbf{pa}_j) \text{ whenever } P(x_{j-1}, \dots, x_1) > 0,$$

then we could write

$$\begin{aligned} P(\mathbf{x}) &= P(x_1, \dots, x_n) = \\ &P(x_n | x_{n-1}, \dots, x_1) \dots P(x_2 | x_1) P(x_1) = \\ &P(x_n | \mathbf{pa}_n) \dots P(x_2 | \mathbf{pa}_1) P(x_1 | \mathbf{pa}_1) = \\ &\prod_{i=1}^n P(x_i | \mathbf{pa}_i) \end{aligned}$$



# Handling Uncertainty

- $P(x_j | \mathbf{pa}_j)$ : conditional probability table, much smaller than  $\{X_{j-1}, \dots, X_1\}$ ,
- If  $k$  is the maximum size of  $\mathbf{pa}_j$ , then the storage requirements are  $O(n2^k)$  instead of  $O(2^n)$ .



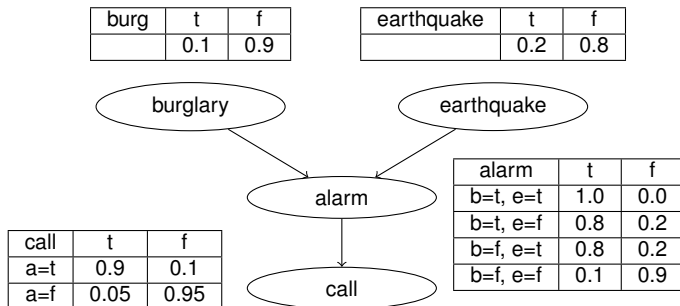


# Probabilistic Graphical Models

- Taking into account independencies among the variables enables faster inference.
- **Graphical models**: graph structures that represent independencies.
- **Bayesian network** [Pearl 88]: directed acyclic graph with a node per variable and an edge from  $X_j$  to  $X_i$  only if  $X_j \in \mathbf{Pa}_i$ .
- A BN together with the set of CPTs  $P(x_j|\mathbf{pa}_j)$  defines a joint probability distribution.

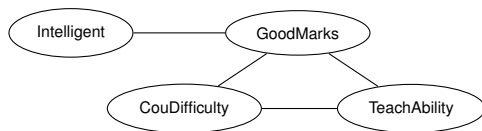


# Example - Alarm



# Markov Networks

- Undirected graphical models



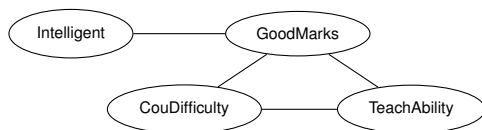
- Each clique in the graph is associated with a **potential**  $\phi_i \geq 0$

$$P(\mathbf{x}) = \frac{\prod_i \phi_i(\mathbf{x}_i)}{Z}$$
$$Z = \sum_{\mathbf{x}} \prod_i \phi_i(\mathbf{x}_i)$$

Intelligent	GoodMarks	$\phi_i(I, G)$
false	false	4.5
false	true	4.5
true	false	1.0
true	true	4.5



# Markov Networks



- If all the potential are strictly positive, we can use a log-linear model (where the  $f_i$ s are **features**)

$$P(\mathbf{x}) = \frac{\exp(\sum_i w_i f_i(\mathbf{x}_i))}{Z}$$
$$Z = \sum_{\mathbf{x}} \exp(\sum_i w_i f_i(\mathbf{x}_i))$$

$$f_i(\text{Intelligent}, \text{GoodMarks}) = \begin{cases} 1 & \text{if } \neg \text{Intelligent} \vee \text{GoodMarks} \\ 0 & \text{otherwise} \end{cases}$$
$$w_i = 1.5$$



# Combining Logic and Probability

- Logic does not handle well uncertainty
- Graphical models do not handle well relationships among entities
- Solution: combine the two
- Many approaches proposed in the areas of Logic Programming, Uncertainty in AI, Machine Learning, Databases, Knowledge Representation



# Probabilistic Logic Programming

- Distribution Semantics [Sato ICLP95]
- A probabilistic logic program defines a probability distribution over normal logic programs (called **instances** or **possible worlds** or simply **worlds**)
- The distribution is extended to a joint distribution over worlds and interpretations (or queries)
- The probability of a query is obtained from this distribution



# Probabilistic Logic Programming (PLP) Languages under the Distribution Semantics

- Probabilistic Logic Programs [Dantsin RCLP91]
- Probabilistic Horn Abduction [Poole NGC93], Independent Choice Logic (ICL) [Poole AI97]
- PRISM [Sato ICLP95]
- Logic Programs with Annotated Disjunctions (LPADs) [Vennekens et al. ICLP04]
- ProbLog [De Raedt et al. IJCAI07]
- They differ in the way they define the distribution over logic programs



- <http://cplint.eu>
  - Inference (knowledge compilation, Monte Carlo)
  - Parameter learning (EMBLEM)
  - Structure learning (SLIPCOVER)
- <https://dtai.cs.kuleuven.be/problog/>
  - Inference (knowledge compilation, Monte Carlo)
  - Parameter learning (LFI-ProbLog)





$sneezing(X) \leftarrow flu(X), msw(flu\_sneezing(X), 1).$   
 $sneezing(X) \leftarrow hay\_fever(X), msw(hay\_fever\_sneezing(X), 1).$   
 $flu(bob).$   
 $hay\_fever(bob).$

$values(flu\_sneezing(\_X), [1, 0]).$   
 $values(hay\_fever\_sneezing(\_X), [1, 0]).$   
 $: -set\_sw(flu\_sneezing(\_X), [0.7, 0.3]).$   
 $: -set\_sw(hay\_fever\_sneezing(\_X), [0.8, 0.2]).$

- Distributions over *msw* facts (random switches)
- Worlds obtained by selecting one value for every grounding of each *msw* statement



# Logic Programs with Annotated Disjunctions

[http://cplint.eu/e/sneezing\\_simple.pl](http://cplint.eu/e/sneezing_simple.pl)

```
sneezing(X) : 0.7 ; null : 0.3 ← flu(X).  
sneezing(X) : 0.8 ; null : 0.2 ← hay_fever(X).  
flu(bob).  
hay_fever(bob).
```

- Distributions over the head of rules
- *null* does not appear in the body of any rule
- Worlds obtained by selecting one atom from the head of every grounding of each clause



$sneezing(X) \leftarrow flu(X), flu\_sneezing(X).$   
 $sneezing(X) \leftarrow hay\_fever(X), hay\_fever\_sneezing(X).$   
 $flu(bob).$   
 $hay\_fever(bob).$   
 $0.7 :: flu\_sneezing(X).$   
 $0.8 :: hay\_fever\_sneezing(X).$

- Distributions over facts
- Worlds obtained by selecting or not every grounding of each probabilistic fact



# Distribution Semantics

- Case of no function symbols: finite Herbrand universe, finite set of groundings of each switch/clause/fact
- **Atomic choice**: selection of the  $i$ -th atom for grounding  $C\theta$  of switch/clause  $C$ 
  - represented with the triple  $(C, \theta, i)$
- Example  $C_1 = \text{sneezing}(X) : 0.7 ; \text{null} : 0.3 \leftarrow \text{flu}(X).$ ,  
 $(C_1, \{X/\text{bob}\}, 1)$
- A ProbLog fact  $p :: F$  is interpreted as  $F : p \vee \text{null} : 1 - p$ .



# Distribution Semantics

- **Selection**  $\sigma$ : a total set of atomic choices (one atomic choice for every grounding of each clause)
- A selection  $\sigma$  identifies a logic program  $w_\sigma$  called **world**
- The probability of  $w_\sigma$  is  $P(w_\sigma) = \prod_{(C,\theta,i) \in \sigma} P_0(C, i)$
- Finite set of worlds:  $W_T = \{w_1, \dots, w_m\}$
- $P(w)$  distribution over worlds:  $\sum_{w \in W_T} P(w) = 1$



# Distribution Semantics

- Ground query  $Q$
- $P(Q|w) = 1$  if  $Q$  is true in  $w$  and 0 otherwise
- $P(Q) = \sum_w P(Q, w) = \sum_w P(Q|w)P(w) = \sum_{w \models Q} P(w)$
- You can see  $P(Q)$  as the probability that  $Q$  is true in a world sampled at random from  $P(w)$ 
  - for each choice, sample a value to get a world
  - test the query in the world



## Example Program (LPAD) Worlds

[http://cplint.eu/e/sneezing\\_simple.pl](http://cplint.eu/e/sneezing_simple.pl)

$sneezing(bob) \leftarrow flu(bob).$	$null \leftarrow flu(bob).$
$sneezing(bob) \leftarrow hay\_fever(bob).$	$sneezing(bob) \leftarrow hay\_fever(bob).$
$flu(bob).$	$flu(bob).$
$hay\_fever(bob).$	$hay\_fever(bob).$
$P(w_1) = 0.7 \times 0.8$	$P(w_2) = 0.3 \times 0.8$

$sneezing(bob) \leftarrow flu(bob).$	$null \leftarrow flu(bob).$
$null \leftarrow hay\_fever(bob).$	$null \leftarrow hay\_fever(bob).$
$flu(bob).$	$flu(bob).$
$hay\_fever(bob).$	$hay\_fever(bob).$
$P(w_3) = 0.7 \times 0.2$	$P(w_4) = 0.3 \times 0.2$

$$P(Q) = \sum_{w \in W_{\mathcal{T}}} P(Q, w) = \sum_{w \in W_{\mathcal{T}}} P(Q|w)P(w) = \sum_{w \in W_{\mathcal{T}}: w \models Q} P(w)$$

- $sneezing(bob)$  is true in 3 worlds
- $P(sneezing(bob)) = 0.7 \times 0.8 + 0.3 \times 0.8 + 0.7 \times 0.2 = 0.94$



# Example Program (ProbLog) Worlds

- 4 worlds

$sneezing(X) \leftarrow flu(X), flu\_sneezing(X).$

$sneezing(X) \leftarrow hay\_fever(X), hay\_fever\_sneezing(X).$

$flu(bob).$

$hay\_fever(bob).$

$flu\_sneezing(bob).$

$hay\_fever\_sneezing(bob).$      $hay\_fever\_sneezing(bob).$

$P(w_1) = 0.7 \times 0.8$

$P(w_2) = 0.3 \times 0.8$

$flu\_sneezing(bob).$

$P(w_3) = 0.7 \times 0.2$

$P(w_4) = 0.3 \times 0.2$

- $sneezing(bob)$  is true in 3 worlds

- $P(sneezing(bob)) = 0.7 \times 0.8 + 0.3 \times 0.8 + 0.7 \times 0.2 = 0.94$





# Logic Programs with Annotated Disjunctions

`http://cplint.eu/e/sneezing.pl`

```
strong_sneezing(X) : 0.3 ; moderate_sneezing(X) : 0.5 ← flu(X).  
strong_sneezing(X) : 0.2 ; moderate_sneezing(X) : 0.6 ← hay_fever(X).  
flu(bob).  
hay_fever(bob).
```

- 9 worlds
- *strong\_sneezing*(bob) is true in 5
- $P(\text{strong\_sneezing}(\text{bob})) = 0.3 \cdot 0.2 + 0.3 \cdot 0.6 + 0.3 \cdot 0.2 + 0.5 \cdot 0.2 + 0.2 \cdot 0.2 = 0.44$



# Monty Hall Puzzle

- A player is given the opportunity to select one of three closed doors, behind one of which there is a prize.
- Behind the other two doors are empty rooms.
- Once the player has made a selection, Monty is obligated to open one of the remaining closed doors which does not contain the prize, showing that the room behind it is empty.
- He then asks the player if he would like to switch his selection to the other unopened door, or stay with his original choice.
- Does it matter if he switches?



# Monty Hall Puzzle

<http://cplint.eu/e/monty.swinb>

```
:- use_module(library(pita)).
:- endif.
:- pita.
:- begin_lpad.
prize(1):1/3; prize(2):1/3; prize(3):1/3.

open_door(2):0.5 ; open_door(3):0.5:- prize(1).
open_door(2):- prize(3).
open_door(3):- prize(2).

win_keep:- prize(1).

win_switch:-
    prize(2),
    open_door(3).

win_switch:-
    prize(3),
    open_door(2).
:- end_lpad.
```



# Examples

**Throwing coins** <http://cplint.eu/e/coin.swinb>

```
heads(Coin):1/2 ; tails(Coin):1/2 :-  
    toss(Coin), \+biased(Coin).  
heads(Coin):0.6 ; tails(Coin):0.4 :-  
    toss(Coin), biased(Coin).  
fair(Coin):0.9 ; biased(Coin):0.1.  
toss(coin).
```



# Examples

## Mendel's inheritance rules for pea plants

<http://cplint.eu/e/mendel.pl>

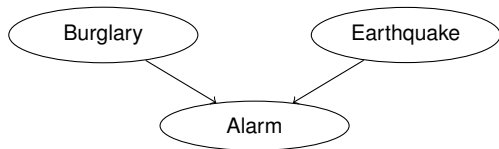
```
color(X, purple) :-cg(X, _A, p) .
color(X, white) :-cg(X, 1, w) , cg(X, 2, w) .
cg(X, 1, A):0.5 ; cg(X, 1, B):0.5 :-
    mother(Y, X) , cg(Y, 1, A) , cg(Y, 2, B) .
cg(X, 2, A):0.5 ; cg(X, 2, B):0.5 :-
    father(Y, X) , cg(Y, 1, A) , cg(Y, 2, B) .
```

## Probability of paths <http://cplint.eu/e/path.swinb>

```
path(X, X) .
path(X, Y) :-path(X, Z) , edge(Z, Y) .
edge(a, b):0.3 .
edge(b, c):0.2 .
edge(a, c):0.6 .
```



# Encoding Bayesian Networks



alarm	t	f
b=t,e=t	1.0	0.0
b=t,e=f	0.8	0.2
b=f,e=t	0.8	0.2
b=f,e=f	0.1	0.9

burg	t	f	earthq	t	f
	0.1	0.9		0.2	0.8

<http://cplint.eu/e/alarm.pl>

```
burg(t):0.1 ; burg(f):0.9.  
earthq(t):0.2 ; earthq(f):0.8.  
alarm(t):-burg(t),earthq(t).  
alarm(t):0.8 ; alarm(f):0.2:-burg(t),earthq(f).  
alarm(t):0.8 ; alarm(f):0.2:-burg(f),earthq(t).  
alarm(t):0.1 ; alarm(f):0.9:-burg(f),earthq(f).
```



# Expressive Power

- All languages under the distribution semantics have the same expressive power
- LPADs have the most general syntax
- There are transformations that can convert each one into the others
- PRISM, ProbLog to LPAD: direct mapping



# LPADs to ProbLog

- Clause  $C_i$  with variables  $\bar{X}$

$$H_1 : p_1 \vee \dots \vee H_n : p_n \leftarrow B.$$

is translated into

$$H_1 \leftarrow B, f_{i,1}(\bar{X}).$$

$$H_2 \leftarrow B, \text{not}(f_{i,1}(\bar{X})), f_{i,2}(\bar{X}).$$

$\vdots$

$$H_n \leftarrow B, \text{not}(f_{i,1}(\bar{X})), \dots, \text{not}(f_{i,n-1}(\bar{X})).$$

$$\pi_1 :: f_{i,1}(\bar{X}).$$

$\vdots$

$$\pi_{n-1} :: f_{i,n-1}(\bar{X}).$$

where  $\pi_1 = p_1$ ,  $\pi_2 = \frac{p_2}{1-\pi_1}$ ,  $\pi_3 = \frac{p_3}{(1-\pi_1)(1-\pi_2)}$ ,  $\dots$

- In general  $\pi_i = \frac{p_i}{\prod_{j=1}^{i-1} (1-\pi_j)}$





# Conversion to Bayesian Networks

- PLP can be converted to Bayesian networks
- Conversion for an LPAD  $T$
- For each ground atom  $A$  a binary variable  $A$
- For each clause  $C_i$  in the grounding of  $T$

$$H_1 : p_1 \vee \dots \vee H_n : p_n \leftarrow B_1, \dots, B_m, \neg C_1, \dots, \neg C_l$$

a variable  $CH_i$  with  $B_1, \dots, B_m, C_1, \dots, C_l$  as parents and  $H_1, \dots, H_n$  and *null* as values



# Conversion to Bayesian Networks

$$H_1 : p_1 \vee \dots \vee H_n : p_n \leftarrow B_1, \dots, B_m, \neg C_1, \dots, \neg C_l$$

- The CPT of  $CH_i$  is

	...	$B_1 = 1, \dots, B_m = 1, C_1 = 0, \dots, C_l = 0$	...
$CH_i = H_1$	0.0	$p_1$	0.0
...			
$CH_i = H_n$	0.0	$p_n$	0.0
$CH_i = null$	1.0	$1 - \sum_{i=1}^n p_i$	1.0



# Conversion to Bayesian Networks

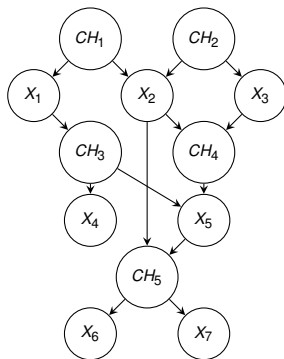
- Each variable  $A$  corresponding to atom  $A$  has as parents all the variables  $CH_i$  of clauses  $C_i$  that have  $A$  in the head.
- The CPT for  $A$  is:

	at least one parent = A	remaining cols
$A = 1$	1.0	0.0
$A = 0$	0.0	1.0



# Conversion to Bayesian Networks

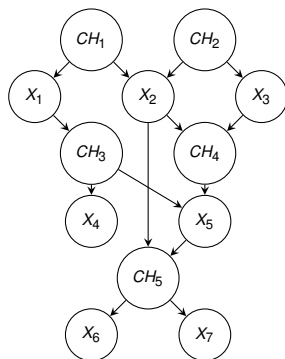
- $C_1 = x_1 : 0.4 \vee x_2 : 0.6.$   
 $C_2 = x_2 : 0.1 \vee x_3 : 0.9.$   
 $C_3 = x_4 : 0.6 \vee x_5 : 0.4 \leftarrow x_1.$   
 $C_4 = x_5 : 0.4 \leftarrow x_2, x_3.$   
 $C_5 = x_6 : 0.3 \vee x_7 : 0.2 \leftarrow x_2, x_5.$



# Conversion to Bayesian Networks

$CH_1, CH_2$	$x_1, x_2$	$x_1, x_3$	$x_2, x_2$	$x_2, x_3$
$x_2 = 1$	1.0	0.0	1.0	1.0
$x_2 = 0$	0.0	1.0	0.0	0.0

$x_2, x_5$	1,1	1,0	0,1	0,0
$CH_5 = x_6$	0.3	0.0	0.0	0.0
$CH_5 = x_7$	0.2	0.0	0.0	0.0
$CH_5 = null$	0.5	1.0	1.0	1.0



# Function Symbols

- What if function symbols are present?
- Infinite, countable Herbrand universe
- Infinite, countable Herbrand base
- Infinite, countable grounding of the program  $T$
- Uncountable  $W_T$
- Each world infinite, countable
- $P(w) = 0$
- Semantics not well-defined

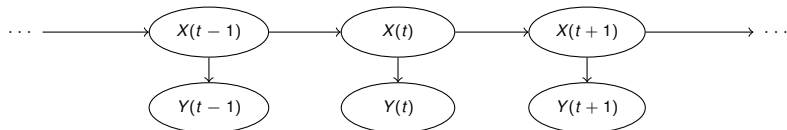


# Game of dice

$\text{on}(0, 1) : 1/3$  ;  $\text{on}(0, 2) : 1/3$  ;  $\text{on}(0, 3) : 1/3$ .  
 $\text{on}(T, 1) : 1/3$  ;  $\text{on}(T, 2) : 1/3$  ;  $\text{on}(T, 3) : 1/3$  :-  
     $T1$  is  $T-1$ ,  $T1 \geq 0$ ,  $\text{on}(T1, F)$ , \+  $\text{on}(T1, 3)$ .



# Hidden Markov Models



```
hmm(S, O) :-hmm(q1, [], S, O).
```

```
hmm(end, S, S, []).
```

```
hmm(Q, S0, S, [L|O]) :-
```

```
    Q\= end,
```

```
    next_state(Q, Q1, S0),
```

```
    letter(Q, L, S0),
```

```
    hmm(Q1, [Q|S0], S, O).
```

```
next_state(q1, q1, _S) : 1/3; next_state(q1, q2, _S) : 1/3;
```

```
next_state(q1, end, _S) : 1/3.
```

```
next_state(q2, q1, _S) : 1/3; next_state(q2, q2, _S) : 1/3;
```

```
next_state(q2, end, _S) : 1/3.
```

```
letter(q1, a, _S) : 0.25; letter(q1, c, _S) : 0.25;
```

```
letter(q1, g, _S) : 0.25; letter(q1, t, _S) : 0.25.
```

```
letter(q2, a, _S) : 0.25; letter(q2, c, _S) : 0.25;
```

```
letter(q2, g, _S) : 0.25; letter(q2, t, _S) : 0.25.
```





# Hybrid Programs

- Up to now only discrete random variables and discrete probability distributions.
- Hybrid Probabilistic Logic Programs: some of the random variables are continuous.
- cplint allows the specification of density functions over arguments of atoms in the head of rules



# Hybrid Programs

- A probability density on an argument `Var` of an atom `A` is specified with

`A : Density :- Body.`

where `Density` is a special atom

- `uniform(Var, L, U) : Var` is uniformly distributed in  $[L, U]$
- `gaussian(Var, Mean, Variance) : Gaussian` distribution
- `dirichlet(Var, Par) : Dirichlet` distribution with parameters  $\alpha$  specified by the list `Par`
- `gamma(Var, Shape, Scale) : gamma` distribution
- `beta(Var, Alpha, Beta) : beta` distribution
- + others (see the manual)



# Hybrid Programs

- Also discrete distributions, with either a finite or countably infinite support:
  - `discrete(Var, D)` or `finite(Var, D)`: `D` is a list of couples `Value:Prob` assigning probability `Prob` to `Value`
  - `uniform(Var, D)`: `D` is a list of values each taking the same probability (1 over the length of `D`).
  - `poisson(Var, Lambda)`: Poisson distribution

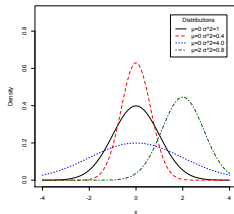


- For each random variable, sample a value, obtaining a world
- Test  $Q$  in the world
- $P(Q)$  is the probability that  $Q$  is true in the world

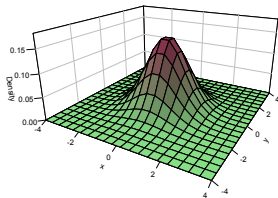


# Examples

$g(X)$  : gaussian( $X, 0, 1$ ).



$g(X)$  : gaussian( $X, [0, 0], [ [1, 0], [0, 1] ]$ ).



# Gaussian Mixture Example

- [http://cplint.eu/e/gaussian\\_mixture.pl](http://cplint.eu/e/gaussian_mixture.pl) defines a mixture of two Gaussians:

```
heads:0.6;tails:0.4.  
g(X) : gaussian(X,0, 1) .  
h(X) : gaussian(X,5, 2) .  
mix(X) :- heads, g(X) .  
mix(X) :- tails, h(X) .
```

- The argument  $X$  of `mix(X)` follows a distribution that is a mixture of two Gaussian, one with mean 0 and variance 1 with probability 0.6 and one with mean 5 and variance 2 with probability 0.4.



# Description Logics

- DISPONTE: “DIstribution Semantics for Probabilistic ONTologiEs” [Riguzzi et al. SWJ15]
- Probabilistic axioms:
  - $p :: E$   
e.g.,  $p :: C \sqsubseteq D$  represents the fact that we believe in the truth of  $C \sqsubseteq D$  with probability  $p$ .
- DISPONTE applies the distribution semantics of probabilistic logic programming to description logics



- World  $w$ : regular DL KB obtained by selecting or not the probabilistic axioms
- Probability of a query  $Q$  given a world  $w$ :  $P(Q|w) = 1$  if  $w \models Q$ , 0 otherwise
- Probability of  $Q$   
$$P(Q) = \sum_w P(Q, w) = \sum_w P(Q|w)P(w) = \sum_{w:w \models Q} P(w)$$





# Example

0.4 :: *fluffy* : *Cat*

0.3 :: *tom* : *Cat*

0.6 :: *Cat*  $\sqsubseteq$  *Pet*

$\exists$  *hasAnimal.Pet*  $\sqsubseteq$  *NatureLover*

(*kevin*, *fluffy*) : *hasAnimal*

(*kevin*, *tom*) : *hasAnimal*



- $P(\textit{kevin} : \textit{NatureLover}) = 0.4 \times 0.3 \times 0.6 + 0.4 \times 0.7 \times 0.6 + 0.6 \times 0.3 \times 0.6 = 0.348$



# Knowledge-Based Model Construction

- The probabilistic logic theory is used directly as a template for generating an underlying complex graphical model [Breese et al. TSMC94].
- Languages: CLP(BN), Markov Logic



# CLP(BN) [Costa UAI02]

- Variables in a CLP(BN) program can be random
- Their values, parents and CPTs are defined with the program
- To answer a query with uninstantiated random variables, CLP(BN) builds a BN and performs inference
- The answer will be a probability distribution for the variables
- Probabilistic dependencies expressed by means of CLP constraints

```
{ Var = Function with p(Values, Dist) }  
{ Var = Function with p(Values, Dist, Parents) }
```



# CLP(BN)

```
.....  
course_difficulty(Key, Dif) :-  
{ Dif = difficulty(Key) with p([h,m,l],  
[0.25, 0.50, 0.25]) }.  
student_intelligence(Key, Int) :-  
{ Int = intelligence(Key) with p([h, m, l],  
[0.5,0.4,0.1]) }.  
.....  
registration(r0,c16,s0).  
registration(r1,c10,s0).  
registration(r2,c57,s0).  
registration(r3,c22,s1).
```



# CLP(BN)

```
.....  
registration_grade(Key, Grade):-  
  registration(Key, CKey, SKey),  
  course_difficulty(CKey, Dif),  
  student_intelligence(SKey, Int),  
  { Grade = grade(Key) with  
    p([a,b,c,d],  
%h h h m h l m h m m m l l h l m l l  
[0.20,0.70,0.85,0.10,0.20,0.50,0.01,0.05,0.10,  
 0.60,0.25,0.12,0.30,0.60,0.35,0.04,0.15,0.40,  
 0.15,0.04,0.02,0.40,0.15,0.12,0.50,0.60,0.40,  
 0.05,0.01,0.01,0.20,0.05,0.03,0.45,0.20,0.10 ],  
  [Int,Dif])  
}.
```

.....



# CLP(BN)

```
?- [school_32].  
    ?- registration_grade(r0,G).  
p(G=a)=0.4115,  
p(G=b)=0.356,  
p(G=c)=0.16575,  
p(G=d)=0.06675 ?  
?- registration_grade(r0,G),  
   student_intelligence(s0,h).  
p(G=a)=0.6125,  
p(G=b)=0.305,  
p(G=c)=0.0625,  
p(G=d)=0.02 ?
```



# Markov Logic

- A Markov Logic Network (MLN) [Richardson, Domingos ML06] is a set of pairs  $(F, w)$  where  $F$  is a formula in first-order logic  $w$  is a real number
- Together with a set of constants, it defines a Markov network with
  - One node for each grounding of each predicate in the MLN
  - One feature for each grounding of each formula  $F$  in the MLN, with the corresponding weight  $w$

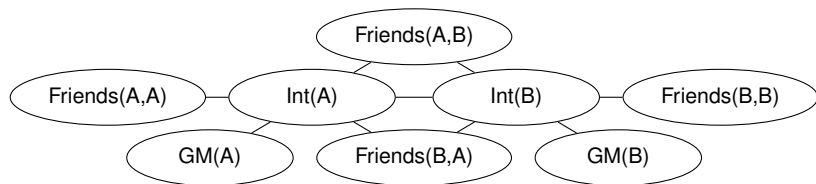


# Markov Logic Example

1.5  $\forall x \text{ Intelligent}(x) \rightarrow \text{GoodMarks}(x)$

1.1  $\forall x, y \text{ Friends}(x, y) \rightarrow (\text{Intelligent}(x) \leftrightarrow \text{Intelligent}(y))$

- Constants Anna (A) and Bob (B)





# Markov Networks

- Probability of an interpretation  $\mathbf{x}$

$$P(\mathbf{x}) = \frac{\exp(\sum_i w_i n_i(\mathbf{x}_i))}{Z}$$

- $n_i(\mathbf{x}_i)$  = number of true groundings of formula  $F_i$  in  $\mathbf{x}$
- Typed variables and constants greatly reduce size of ground Markov net



# Reasoning Tasks

- Inference: we want to compute the probability of a query given the model and, possibly, some evidence, or find assignments of the random variables with the highest probability
- Weight learning: we know the structural part of the model (the logic formulas) but not the numeric part (the weights) and we want to infer the weights from data
- Structure learning we want to infer both the structure and the weights of the model from data



## Inference for PLP under DS

- EVID: compute an unconditional probability  $P(e)$ , the probability of evidence (also query in this case).
- COND: compute the conditional probability distribution of the query given the evidence, i.e. compute  $P(q|e)$
- MPE or *most probable explanation*: find the most likely value of all non-evidence atoms given the evidence, i.e. solving the optimization problem  $\arg \max_q P(q|e)$
- MAP or *maximum a posteriori*: find the most likely value of a set of non-evidence atoms given the evidence, i.e. finding  $\arg \max_q P(q|e)$ . MPE is a special case of MAP where  $Q \cup E = H_T$ .
- DISTR: compute the probability distribution or density of the non-ground arguments of a conjunction of literals  $q$ , e.g., computing the probability density of  $X$  in goal  $mix(X)$  of the Gaussian mixture



# Weight Learning

- Given
  - model: a probabilistic logic model with unknown parameters
  - data: a set of interpretations
- Find the values of the parameters that maximize the probability of the data given the model
- Discriminative learning: maximize the conditional probability of a set of outputs (e.g. ground instances for a predicate) given a set of inputs
- Alternatively, the data are queries for which we know the probability: minimize the error in the probability of the queries that is returned by the model



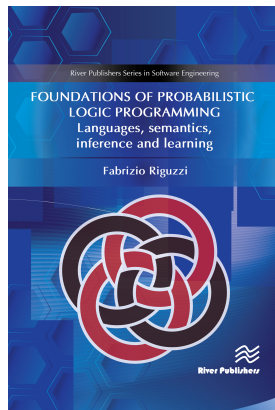
# Structure Learning

- Given
  - language bias: a specification of the search space
  - data: a set of interpretations
- Find the formulas and the parameters that maximize the likelihood of the data given the model
- Discriminative learning: again maximize the conditional likelihood of a set of outputs given a set of inputs



# Conclusions

- Handling relationships
- Handling uncertainty
- Open problems
  - Semantics for hybrid programs with function symbols
  - Learning hybrid programs



# Resources

- **Online course on cplint**
  - **Moodle** <https://edu.swi-prolog.org/>
  - **Videos of lectures** <https://www.youtube.com/playlist?list=PLJPXEH0boeND0UGWJxBRWs7qzzKpC-FkN>
- **ACAI summer school on Statistical Relational AI**  
<http://acai2018.unife.it/>
- **Videos of lectures** <https://www.youtube.com/playlist?list=PLJPXEH0boeNDWTNwWTWnVffXi5XwAj1mb>
- **Videos of lecture Probabilistic Inductive Logic Programming**
  - **Part 1** <https://youtu.be/mLdPGSlgNxU>
  - **Part 2** [https://youtu.be/DRlOft0Y\\_Ng](https://youtu.be/DRlOft0Y_Ng)
- **cplint in Playing with Prolog** [https://www.youtube.com/playlist?list=PLJPXEH0boeNAik6QnfvG1AGRQxFY\\_LCE3](https://www.youtube.com/playlist?list=PLJPXEH0boeNAik6QnfvG1AGRQxFY_LCE3)





**THANKS FOR  
LISTENING  
AND  
ANY  
QUESTIONS ?**





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