

AUTOMATED REASONING

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Let us consider programs consisting of rules of the kind:

$$H \leftarrow B_1, \dots, B_m, \text{not } C_1, \dots, \text{not } C_n \quad (1)$$

where H, B_i, C_j are atoms, $n \geq 0, m \geq 0$ is said an (ASP) rule.

Sets of these rules are called *general programs*.

An extended T_P can be defined:

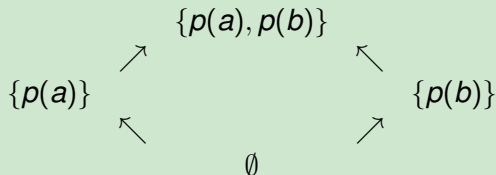
$$T_P(I) = \left\{ a : \begin{array}{l} a \leftarrow b_1, \dots, b_m, \neg c_1, \dots, \neg c_n \in \text{ground}(P), \\ \{b_1, \dots, b_m\} \subseteq I, \\ \{c_1, \dots, c_n\} \cap I = \emptyset \end{array} \right\}$$

PROGRAMS WITH NEGATION

EXAMPLE

Let $P = p(a) \leftarrow \text{not } p(b)$ (it's the theory: $T = p(a) \vee p(b)$).

There are 4 Herbrand interpretations:



3 of them are models. There is no A such that $T \models A$.

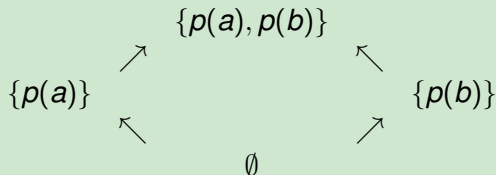
Moreover, $T_P(\emptyset) = \{p(a)\}$, $T_P(\{p(b)\}) = \emptyset$: this is not monotone.

We need other techniques for reasoning on the semantics of programs with Negation (stable model semantics).

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We need other techniques for reasoning on the semantics of programs with Negation (stable model semantics).

SEMANTICS OF GENERAL PROGRAMS

WHAT IS THE EFFECT OF THE LOSS OF MONOTONICITY?

```
student(alberto).      student(bruno).      student(carlo).  
course(fondamenti).   course(asd).
```

```
studied(alberto, fondamenti). studied(bruno, fondamenti).  
studied(carlo,asd).
```

```
can_participate_exam(S,E) :-  
    student(S), course(E),  
    studied(S,E),  
    not fail_selftest(S,E).
```

```
fail_selftest(S,E) :- test(S,E,VOTO), VOTO < 15.
```

What can we deduce? And if now knew that `test(carlo,asd,10)`. And if now knew that `test(alberto,fondamenti,5)`. ???

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SEMANTICS OF GENERAL PROGRAMS

PROGRAM COMPLETION

Given a program P :

$r(a, c).$

$r(a, d).$

$q(X) :- r(X, Y), \text{ not } s(Y).$

$p(a) :- \text{ not } p(b).$

$p(b) :- \text{ not } p(a).$

SEMANTICS OF GENERAL PROGRAMS

PROGRAM COMPLETION

it is normalized, obtaining $norm(P)$:

$r(X_1, X_2) :- X_1=a, X_2=c.$

$r(X_1, X_2) :- X_1=a, X_2=d.$

$q(X_1) :- r(X_1, Y), \text{ not } s(Y).$

$p(X_1) :- X_1=a, \text{ not } p(b).$

$p(X_1) :- X_1=b, \text{ not } p(a).$

SEMANTICS OF GENERAL PROGRAMS

PROGRAM COMPLETION

Let us collect equal heads and add **iff** and explicit quantifiers, obtaining *iff*(P):

$$r(X_1, X_2) \leftrightarrow (X_1=a \wedge X_2=c) \vee (X_1=a \wedge X_2=d)$$

$$q(X_1) \leftrightarrow \exists Y (r(X_1, Y) \wedge \neg s(Y))$$

$$p(X_1) \leftrightarrow (X_1=a \wedge \neg p(b)) \vee (X_1=b \wedge \neg p(a))$$

$$s(X_1) \leftrightarrow \text{false}$$

SEMANTICS OF GENERAL PROGRAMS

PROGRAM COMPLETION

The completion of P is:

$$r(X_1, X_2) \leftrightarrow (X_1=a \wedge X_2=c) \vee (X_1=a \wedge X_2=d)$$

$$q(X_1) \leftrightarrow \exists Y (r(X_1, Y) \wedge \neg s(Y))$$

$$p(X_1) \leftrightarrow (X_1=a \wedge \neg p(b)) \vee (X_1=b \wedge \neg p(a))$$

$$s(X_1) \leftrightarrow \text{false}$$

(plus the so-called *freeness axioms*)

SEMANTICS OF GENERAL PROGRAMS

HERBRAND MODELS OF THE COMPLETION

$$r(X_1, X_2) \leftrightarrow (X_1=a \wedge X_2=c) \vee (X_1=a \wedge X_2=d)$$

$$q(X_1) \leftrightarrow \exists Y (r(X_1, Y) \wedge \neg s(Y))$$

$$p(X_1) \leftrightarrow (X_1=a \wedge \neg p(b)) \vee (X_1=b \wedge \neg p(a))$$

$$s(X_1) \leftrightarrow \text{false}$$

We need to consider 28 atoms:

s(a)	s(b)	s(c)	s(d)
p(a)	p(b)	p(c)	p(d)
q(a)	q(b)	q(c)	q(d)
r(a,a)	r(a,b)	r(a,c)	r(a,d)
r(b,a)	r(b,b)	r(b,c)	r(b,d)
r(c,a)	r(c,b)	r(c,c)	r(c,d)
r(d,a)	r(d,b)	r(d,c)	r(d,d)

Which of them are in all models of the completions?

Which one in no-one?

SEMANTICS OF GENERAL PROGRAMS

HERBRAND MODELS OF THE COMPLETION

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s(a) F s(b) F s(c) F s(d) F

p(a) p(b) p(c) p(d)

q(a) q(b) q(c) q(d)

r(a,a) r(a,b) r(a,c) r(a,d)

r(b,a) r(b,b) r(b,c) r(b,d)

r(c,a) r(c,b) r(c,c) r(c,d)

r(d,a) r(d,b) r(d,c) r(d,d)

Let's analyze s

SEMANTICS OF GENERAL PROGRAMS

HERBRAND MODELS OF THE COMPLETION

$$r(X_1, X_2) \leftrightarrow (X_1=a \wedge X_2=c) \vee (X_1=a \wedge X_2=d)$$

$$q(X_1) \leftrightarrow \exists Y (r(X_1, Y) \wedge \neg s(Y))$$

$$p(X_1) \leftrightarrow (X_1=a \wedge \neg p(b)) \vee (X_1=b \wedge \neg p(a))$$

$$s(X_1) \leftrightarrow \text{false}$$

s(a) F	s(b) F	s(c) F	s(d) F
p(a)	p(b)	p(c)	p(d)
q(a)	q(b)	q(c)	q(d)
r(a,a) F	r(a,b) F	r(a,c) T	r(a,d) T
r(b,a) F	r(b,b) F	r(b,c) F	r(b,d) F
r(c,a) F	r(c,b) F	r(c,c) F	r(c,d) F
r(d,a) F	r(d,b) F	r(d,c) F	r(d,d) F

Let's analyze r

SEMANTICS OF GENERAL PROGRAMS

HERBRAND MODELS OF THE COMPLETION

$$r(X_1, X_2) \leftrightarrow (X_1=a \wedge X_2=c) \vee (X_1=a \wedge X_2=d)$$

$$q(X_1) \leftrightarrow \exists Y (r(X_1, Y) \wedge \neg s(Y))$$

$$p(X_1) \leftrightarrow (X_1=a \wedge \neg p(b)) \vee (X_1=b \wedge \neg p(a))$$

$$s(X_1) \leftrightarrow \text{false}$$

s(a) F	s(b) F	s(c) F	s(d) F
p(a)	p(b)	p(c)	p(d)
q(a) T	q(b) F	q(c) F	q(d) F
r(a,a) F	r(a,b) F	r(a,c) T	r(a,d) T
r(b,a) F	r(b,b) F	r(b,c) F	r(b,d) F
r(c,a) F	r(c,b) F	r(c,c) F	r(c,d) F
r(d,a) F	r(d,b) F	r(d,c) F	r(d,d) F

Let's analyze q

SEMANTICS OF GENERAL PROGRAMS

HERBRAND MODELS OF THE COMPLETION

$$r(X_1, X_2) \leftrightarrow (X_1=a \wedge X_2=c) \vee (X_1=a \wedge X_2=d)$$

$$q(X_1) \leftrightarrow \exists Y (r(X_1, Y) \wedge \neg s(Y))$$

$$p(X_1) \leftrightarrow (X_1=a \wedge \neg p(b)) \vee (X_1=b \wedge \neg p(a))$$

$$s(X_1) \leftrightarrow \text{false}$$

s(a) F	s(b) F	s(c) F	s(d) F
p(a) ?	p(b) ?	p(c) F	p(d) F
q(a) T	q(b) F	q(c) F	q(d) F
r(a,a) F	r(a,b) F	r(a,c) T	r(a,d) T
r(b,a) F	r(b,b) F	r(b,c) F	r(b,d) F
r(c,a) F	r(c,b) F	r(c,c) F	r(c,d) F
r(d,a) F	r(d,b) F	r(d,c) F	r(d,d) F

Let's analyze p

SEMANTICS OF GENERAL PROGRAMS

HERBRAND MODELS OF THE COMPLETION

- Three sets of atoms emerge:
 - Those true in all Herbrand models of the completion
 - Those false in all Herbrand models of the completion
 - The others (true in some models, false in others models)
- This suggest a data structure storing the set I^+ (always true) and I^- (always false). This is sometimes called Fitting 3-valued semantics
- These sets can be computed using the notion of *well-founded* model.
- The well-founded model is a pair $\langle I^+, I^- \rangle$ which is unique and computable in polynomial time on the ground program.
- If $I^+ \cup I^- \neq B_P$ the well-founded model is not a real model!
- If it is a model it will be the unique **stable model**

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SEMANTICS OF GENERAL PROGRAMS

GROUNDING

- We have already used the notion of ground program
- We will start our reasoning on the ground version of the program
- Given a general program P , $ground(P)$ is the set of all ground instances of P obtained replacing the variables in the clauses with all elements of \mathcal{H}_P
- Later we'll see the complexity of computing $ground(P)$.

SEMANTICS OF GENERAL PROGRAMS

GROUNDING

$P =$

$p(a) . \quad p(b) . \quad q(b) . \quad q(c) .$
 $r(X, Y) \quad :- \quad p(X), q(Y) .$

$ground(P) =$

$p(a) . \quad p(b) . \quad q(b) . \quad q(c) .$
 $r(a, a) \quad :- \quad p(a), q(a) .$
 $r(a, b) \quad :- \quad p(a), q(b) .$
 $r(a, c) \quad :- \quad p(a), q(c) .$
 $r(b, a) \quad :- \quad p(c), q(a) .$
 $r(b, b) \quad :- \quad p(c), q(b) .$
 $r(b, c) \quad :- \quad p(c), q(c) .$
 $r(c, a) \quad :- \quad p(c), q(a) .$
 $r(c, b) \quad :- \quad p(c), q(b) .$
 $r(c, c) \quad :- \quad p(c), q(c) .$

SEMANTICS OF GENERAL PROGRAMS

STABLE MODELS

- Let P be

$$p \text{ :- not } q.$$

We know that P has two minimal models: $\{p\}$ e $\{q\}$.

- $\{q\}$ does not capture the meaning “if you have no reasons for believing in q , then believe in p ”). There are no info in P to justify that q is true.
- We would like to have as unique model $\{p\}$ (it is also the well-founded model).
- If P is:

$$p \text{ :- not } q. \quad q \text{ :- not } p.$$

then well-founded simply states $I^+ = \emptyset, I^- = \emptyset$ (i.e., nothing)

SEMANTICS OF GENERAL PROGRAMS

STABLE MODEL (GELFOND-LIFSCHITZ 1988)

- Given a general program P and a **candidate** model S , let us define P^S (**the reduct of P w.r.t. S**) as follows:
 - 1 remove every rule that contains a naf-literal `not L` in the body such that $L \in S$;
 - 2 remove every naf-literal from the bodies of the remaining rules.
- Let us observe that P^S is a definite program. We can compute its minimum model M_{P^S} . If $M_{P^S} = S$ then S is a **stable model** (a.k.a. **answer set**) for P .

SEMANTICS OF GENERAL PROGRAMS

STABLE MODEL (GELFOND-LIFSCHITZ 1988)

Let us consider the program P

```
p :- a.  
a :- not b.  
b :- not a.
```

the candidate stable models for P are all the subsets of $\mathcal{B}_P = \{a, b, p\}$.

SEMANTICS OF GENERAL PROGRAMS

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\emptyset We have that $P^\emptyset = \{p \leftarrow a. a. b.\}$. \emptyset is not the minimum model of P^\emptyset . Thus \emptyset is not an answer set of P .

SEMANTICS OF GENERAL PROGRAMS

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$\{a\}$ We have that $P^{\{a\}} = \{p \leftarrow a. a.\}$. $\{a\}$ is not the minimum model of $P^{\{a\}}$. Thus $\{a\}$ is not an answer set of P .

SEMANTICS OF GENERAL PROGRAMS

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the candidate stable models for P are all the subsets of $\mathcal{B}_P = \{a, b, p\}$.

$\{b\}$ We have that $P^{\{b\}} = \{p \leftarrow a. b.\}$. $\{b\}$ is the minimum model of $P^{\{b\}}$. Thus, $\{b\}$ is an answer set of P .

SEMANTICS OF GENERAL PROGRAMS

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$\{p, a\}$ We have that $P^{\{p,a\}} = \{p \leftarrow a. a.\}$. $\{p, a\}$ is the minimum model of $P^{\{p,a\}}$. Thus, $\{p, a\}$ is an answer set of P .

SEMANTICS OF GENERAL PROGRAMS

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```
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b :- not a.
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the candidate stable models for P are all the subsets of $\mathcal{B}_P = \{a, b, p\}$.

$\{a, b\}$, $\{b, p\}$ e $\{a, b, p\}$ are not answer sets of P since they include properly answer sets (e.g., $\{b\}$) [This is a theorem. Answer Sets are always minimal]

SEMANTICS OF GENERAL PROGRAMS

STABLE MODEL (GELFOND-LIFSCHITZ 1988)

Let us consider the program P

```
p :- a.  
a :- not b.  
b :- not a.
```

the candidate stable models for P are all the subsets of $\mathcal{B}_P = \{a, b, p\}$.

Thus P has two answer sets: $\{b\}$ and $\{p, a\}$.

SEMANTICS OF GENERAL PROGRAMS

STABLE MODEL (GELFOND-LIFSCHITZ 1988)

Let us consider the program P

$a \text{ :- not } b.$

$b \text{ :- not } c.$

$d.$

The set $S_1 = \{b, d\}$ is an answer set of P . As a matter of fact, $P^{S_1} = \{b, d\}$ that has S_1 as minimum model.

Instead, $S_2 = \{a, d\}$ is not an answer set of P : $P^{S_2} = \{a, b, d\}$ has not S_2 as minimum model.

SEMANTICS OF GENERAL PROGRAMS

STABLE MODEL (GELFOND-LIFSCHITZ 1988)

Let us consider the program P

$$\begin{array}{l} p \text{ :- not } p, \quad d. \\ d. \end{array}$$

It admits the (logical) model $\{p, d\}$. Observe that any model of P must contain d . Thus we have two possible candidates for being answer sets:

- $S_1 = \{d\}$: then $P^{S_1} = \{p \leftarrow d. \quad d.\}$. Its minimum model is not S_1 .
- $S_2 = \{d, p\}$: then $P^{S_2} = \{d.\}$. Its minimum model is not S_2 .

This program has logical models but it has not stable models!

SEMANTICS OF GENERAL PROGRAMS

STABLE MODEL (GELFOND-LIFSCHITZ 1988)

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SEMANTICS OF GENERAL PROGRAMS

“CONSTRAINTS”

- We should think to the body of an ASP rule as a justification for supporting the truth of its head.
- Intuitively, *“ p is in the answer set only if it is supported by the fact that it is the head of a body which is true in the answer set. The only exception is that you cannot support p by the presence of `not p` in its body”*

- E.g.

`p :- not p, d.`

does not support the truth of p .

- (but p could be supported by another rule, in case)

SEMANTICS OF GENERAL PROGRAMS

“CONSTRAINTS”

- From the answer set point of view, if p does not occur elsewhere in (head of rules of) the program

$p \text{ :- not } p, d.$

is equivalent to state that d **must be false**

- This can be simply stated by

$\text{:- } d$

(called constraint)

- constraints are therefore **syntactic sugar**

SEMANTICS OF GENERAL PROGRAMS

NON-DETERMINISTIC CHOICES

Let us consider the following program:

```
a :- not n_a.  n_a :- not a.  
b :- not n_b.  n_b :- not b.  
c :- not n_c.  n_c :- not c.  
d :- not n_d.  n_d :- not d.
```

Its answer sets are all (and only) the sets containing exactly one option between

- a and n_a,
- b and n_b,
- c and n_c,
- d and n_d.

Also for this case we have a **syntactic sugar**.

SEMANTICS OF GENERAL PROGRAMS

COMPLEXITY

THEOREM

Given a *ground* program P , the problem of establishing whether it admits answer sets (stable models) is NP-complete.

NP Let P ground program, a candidate stable model S will contain only atoms occurring in P , thus $|S| \leq |P|$. Computing P^S , the fixpoint computation of M_{PS} , and checking if $S = M_{PS}$ therefore polynomial w.r.t. $|P|$. Thus the problem is in NP.

SEMANTICS OF GENERAL PROGRAMS

COMPLEXITY

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Hardness Let us consider an instance φ of 3SAT:

$$\underbrace{(A \vee \neg B \vee C)}_{c1} \wedge \underbrace{(\neg A \vee B \vee \neg C)}_{c2}$$

and define accordingly the program P_φ :

```
a :- not na.   na :- not a.
b :- not nb.   nb :- not b.
c :- not nc.   nc :- not c.
c1 :- a.       c1 :- nb.   c1 :- c.
c2 :- na.       c2 :- b.   c2 :- nc.
:- not c1.     :- not c2.
```

P_φ can be computed in LOGSPACE and it is immediate to check that it admits a stable model iff φ is satisfiable.

SEMANTICS OF GENERAL PROGRAMS

SUMMARY

- P definite program: unique minimal model M_P . If P is ground and finite you can compute it in PTIME.
- P general program. B_P is always a logical model, but it is not interesting.
- P general program. It admits a unique well-founded model. If P is ground and finite you can compute it in PTIME. If it is total it is also the unique stable model.
- If instead it is partial, and P is ground and finite establishing the existence of a stable model is NP complete.
- We have a programming paradigm exactly for the class NP.
- It is also useful for non monotonic reasoning.